

# CFD ACCELERATION TECHNIQUES: IMPLICIT RUNGE-KUTTA

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# CFD Acceleration Techniques

- Goal
  - Decrease run-time of Computational Fluid Dynamics (CFD) software
- Methods
  - Implicit Runge-Kutta
  - Multigrid
  - GPU Acceleration

# Implicit Runge-Kutta Methods

- CFD - Solving Navier-Stokes Equations
  - Coupled Non-linear PDEs

Momentum Equations - Newton's 2nd Law

$$\frac{\partial(\rho\vec{u})}{\partial t} + \rho\vec{u} \cdot \nabla\vec{u} = -\nabla P + \nabla \cdot (\mu\nabla\vec{u}) + S_u$$

Continuity - Mass Conservation

$$\frac{\partial\rho}{\partial t} + \nabla \cdot (\rho\vec{u}) = 0$$

- After spatial discretization of Momentum Equation
  - Non-Linear ODE

$$\frac{\partial u}{\partial t} = F(u(t))$$

# Implicit Runge-Kutta Methods

- General Form of Runge-Kutta

$$\frac{\partial u}{\partial t} = F(t, u)$$

$$\Delta t = t_{n+1} - t_n$$

$s$  = number of stages

$$u_i = u_n + \Delta t \sum_{j=1}^s a_{i,j} F(t_n + c_j \Delta t, u_j)$$

$$u_{n+1} = u_n + \Delta t \sum_{i=1}^s b_i F(t_n + c_i \Delta t, u_i)$$

$c_1$	$a_{11}$	$a_{12}$	$\cdots$	$a_{1j}$	$\cdots$	$a_{1s}$
$c_2$	$a_{21}$	$a_{22}$	$\cdots$	$a_{2j}$	$\cdots$	$a_{2s}$
$\vdots$	$\vdots$	$\vdots$	$\ddots$	$\vdots$	$\ddots$	$\vdots$
$c_i$	$a_{i1}$	$a_{i2}$	$\cdots$	$a_{ij}$	$\cdots$	$a_{is}$
$\vdots$	$\vdots$	$\vdots$	$\ddots$	$\vdots$	$\ddots$	$\vdots$
$c_s$	$a_{s1}$	$a_{s2}$	$\cdots$	$a_{sj}$	$\cdots$	$a_{ss}$
	$b_1$	$b_2$	$\cdots$	$b_j$	$\cdots$	$b_s$

Butcher Tableau

# Implicit Runge-Kutta Methods

- Different Classifications of Runge-Kutta
  - Explicit (ERK)

$$u_i = u_n + \Delta t \sum_{j=1}^{i-1} a_{i,j} F(t_n + c_j \Delta t, u_j)$$

$u_i$  has no dependence on  $u_i, u_{i+1}, \dots$

0	0				
$c_2$	$a_{21}$	0			
$c_3$	$a_{31}$	$a_{32}$	0		
$\vdots$	$\vdots$	$\vdots$	$\ddots$	$\ddots$	
$c_s$	$a_{s1}$	$a_{s2}$	$\dots$	$a_{s,s-1}$	0
	$b_1$	$b_2$	$\dots$	$b_{s-1}$	$b_s$

Butcher Tableau

# Implicit Runge-Kutta Methods

- Different Classifications of Runge-Kutta
  - Diagonally-Implicit (DIRK)

$$\begin{aligned} u_i &= u_n + \Delta t \sum_{j=1}^i a_{i,j} F(t_n + c_j \Delta t, u_j) \\ &= u_n + a_{i,i} \Delta t F(t_n + c_i \Delta t, u_i) \\ &\quad + \Delta t \sum_{j=1}^{i-1} a_{i,j} F(t_n + c_j \Delta t, u_j) \end{aligned}$$

$c_1$	$a_{11}$			
$c_2$	$a_{21}$	$a_{22}$		
$\vdots$	$\vdots$	$\vdots$	$\ddots$	
$c_s$	$a_{s1}$	$a_{s2}$	$\cdots$	$a_{s,s}$
	$b_1$	$b_2$	$\cdots$	$b_s$

Butcher Tableau

$u_i$  is dependent on  $u_i$ , but not  $u_{i+1}$ ,  $u_{i+2}$ ,  $\dots$

# Implicit Runge-Kutta Methods

- Different Classifications of Runge-Kutta
  - Singly-Diagonal Implicit (SDIRK)

$$\begin{aligned}
 u_i &= u_n + \Delta t \sum_{j=1}^i a_{i,j} F(t_n + c_j \Delta t, u_j) \\
 &= u_n + \gamma \Delta t F(t_n + c_i \Delta t, u_i) \\
 &\quad + \Delta t \sum_{j=1}^{i-1} a_{i,j} F(t_n + c_j \Delta t, u_j)
 \end{aligned}$$

$c_1$	$\gamma$			
$c_2$	$a_{21}$	$\gamma$		
$\vdots$	$\vdots$	$\vdots$	$\ddots$	
$c_s$	$a_{s1}$	$a_{s2}$	$\cdots$	$\gamma$
	$b_1$	$b_2$	$\cdots$	$b_s$

Butcher Tableau

The implicit coefficients do not change from stage to stage. Can take advantage with factorization (ex. LU).

# Implicit Runge-Kutta Methods

- Different Classifications of Runge-Kutta
  - Fully-Implicit (FIRK)
  - Explicit (ERK)
  - Diagonally-Implicit (DIRK)
  - Singly-Diagonal Implicit (SDIRK)
  - Explicit first stage, Diagonally-Implicit (EDIRK)
  - Explicit first stage, Singly-Diagonal Implicit (ESDIRK)
  - Implicit-Explicit (IMEX)
- Focused on EDIRK and ESDIRK



# Implicit Runge-Kutta Methods

- SIMPLER Algorithm for Incompressible Flows
  - Linearize and decouple equations
    - 1) Guess velocity field
    - 2) Solve pressure equation to find pressure
    - 3) Solve momentum equations to find velocity field (approx)
    - 4) Solve pressure correction equation and correct velocities
    - 5) Iterate steps 2-4 until converged
    - 6) Advance to the next time step using the current velocity field as the guessed velocity field for the next step

# Implicit Runge-Kutta Methods

- Runge-Kutta SIMPLER Algorithm

- 1) Guess velocity field
- 2) Solve pressure equation to find pressure
- 3) Use Runge-Kutta to update the velocities
- 4) Advance to the next time step using the current velocity field as the guessed velocity field for the next step

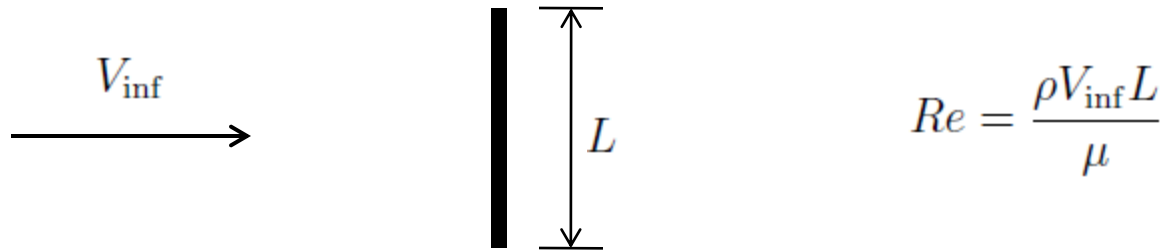
Removes iterations by updating the velocities in a more accurate way and removing the need for corrections

# Implicit Runge-Kutta Methods

- Implementation
  - 2-D incompressible structured solver
  - Testing different implicit Runge-Kutta methods
    - EDIRK ( 2, 3, & 4 stage)
    - ESDIRK with Approximate Factorization & LU Factorization ( 2, 3, 4, & 5 stage)
    - Baseline comparisons are SIMPLER with C-N and 4-stage Explicit Runge-Kutta SIMPLER

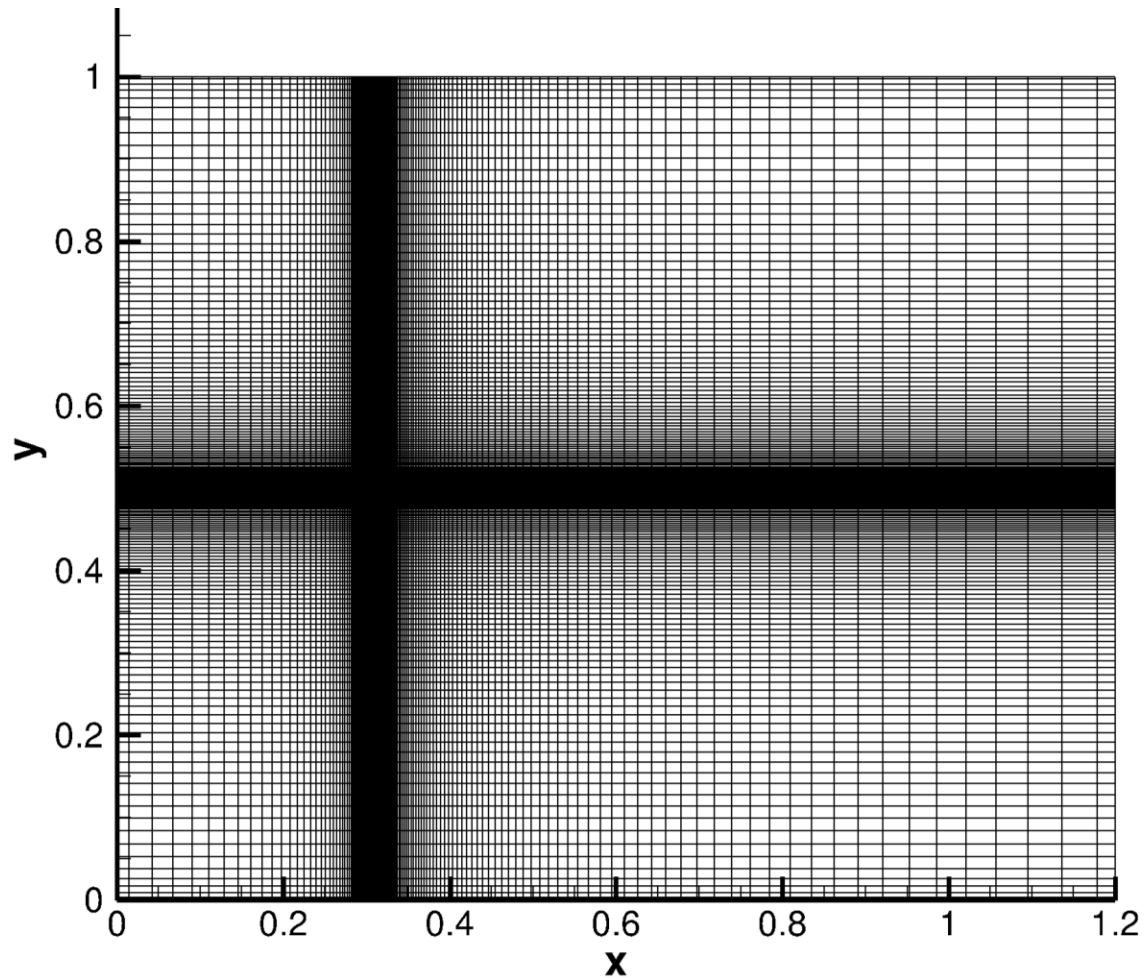
# Implicit Runge-Kutta Methods

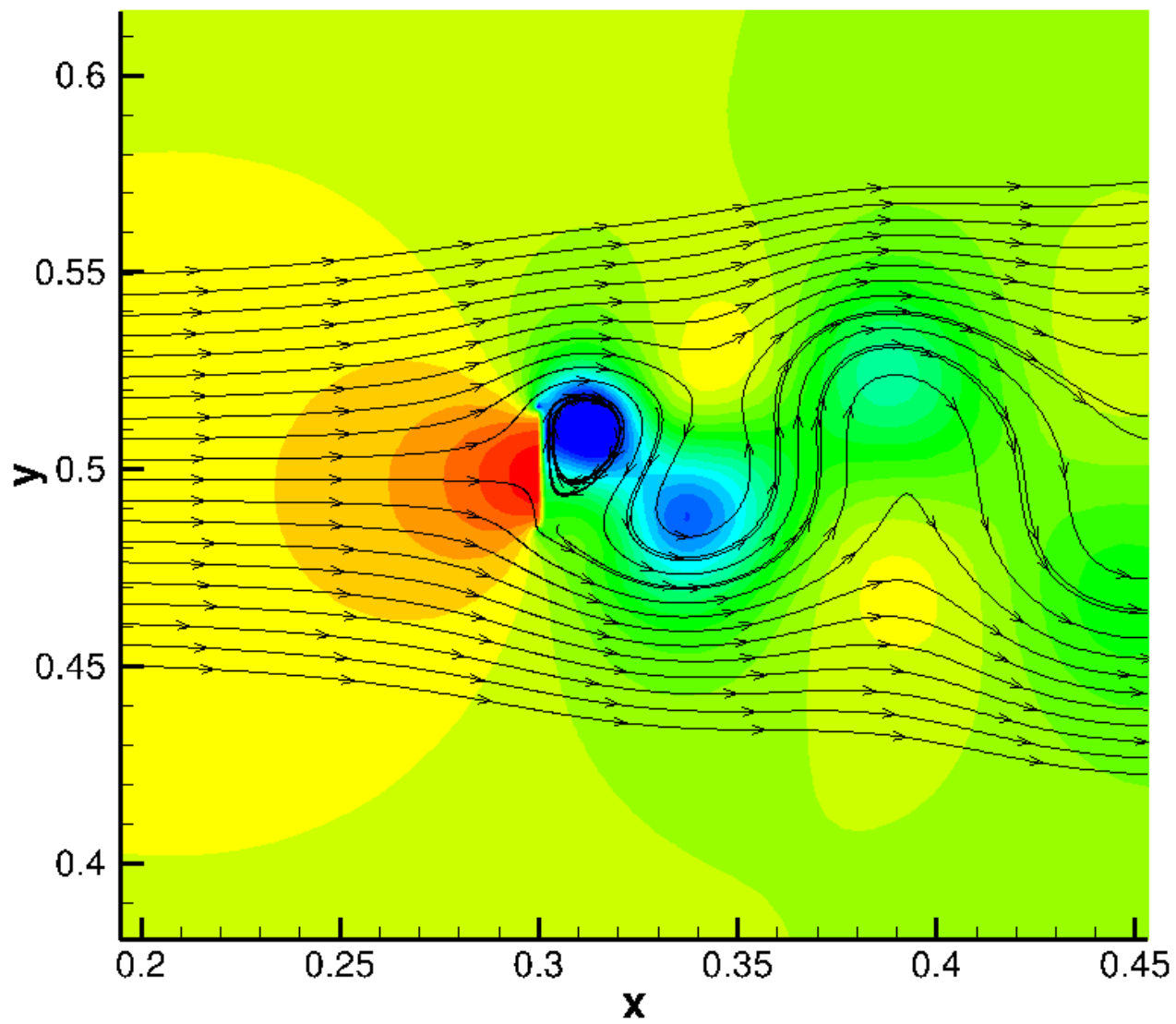
- Test Case
  - Flat Plate at 90 degrees to the flow

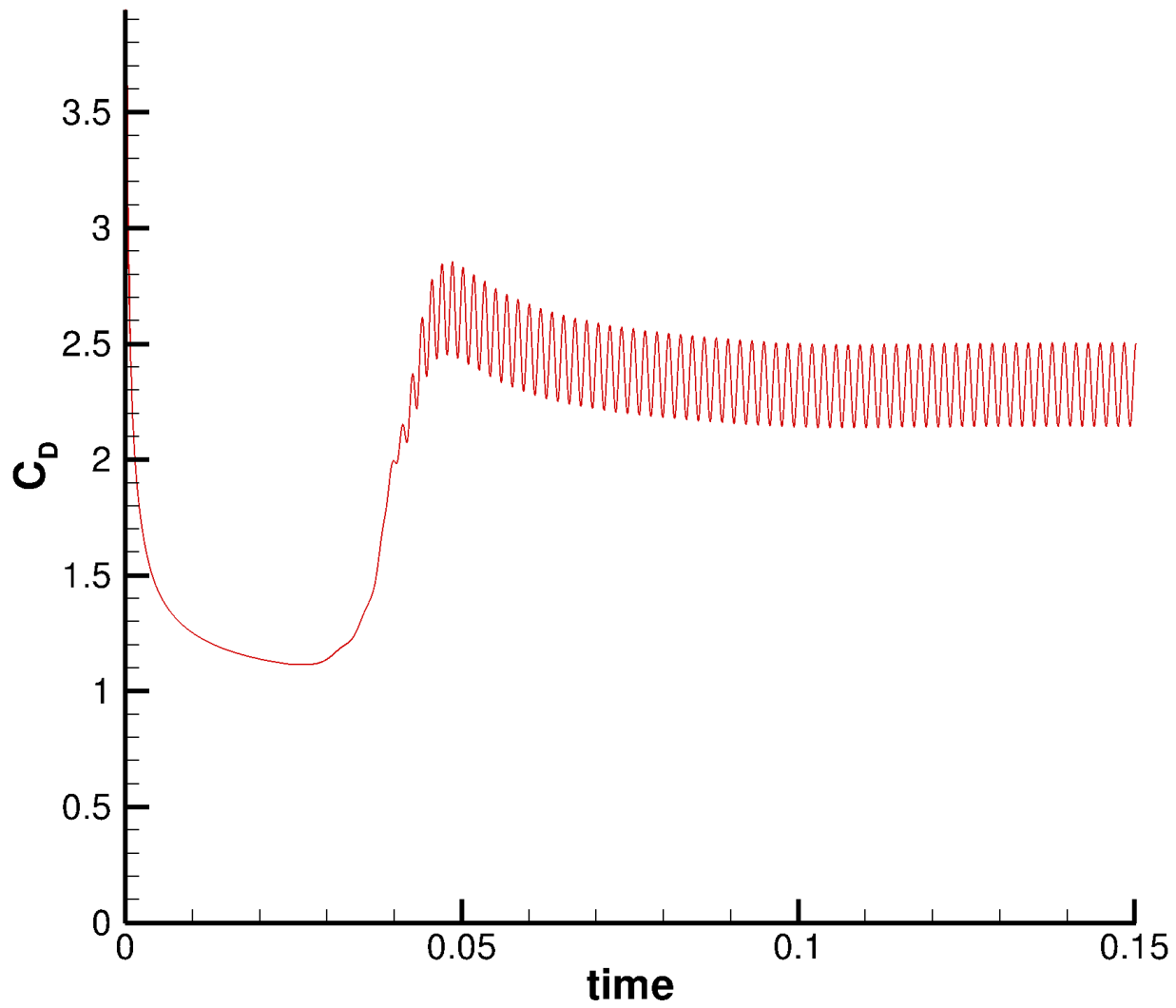


- At high Reynolds numbers vortices are shed in a cyclic pattern

- 172 x 172 Structured Grid







# Baseline Results

	SIMPLER C-N	ERK – 4
Max. time step	1.00 E-05	2.10 E-06
Run Time	5105 sec.	954 sec.
	~ 1hr. 15 min.	~ 16 min.
Decrease in Run time		81%
Period (1/s)	0.0036	0.0036
Avg. $C_D$	2.3	2.3



# EDIRK Methods

	EDIRK – 4	EDIRK – 3	EDIRK – 2
Max. time step	6.53 E-06	6.41 E-06	6.50 E-6
time step / ERK time step	3.11	3.05	3.10
Run Time	1013 sec.	778 sec.	507 sec.
	~ 17 min.	~ 13 min.	~ 8.5 min.
Decrease in Run time vs. CN	80%	85%	90%
Decrease in Run time vs. ERK	-6%	18%	47%
Period (1/s)	0.0036	0.0036	0.0036
Avg. $C_D$	2.3	2.3	2.3

# ESDIRK w/ AF & LU Fact. Methods

	ESDIRK – 5	ESDIRK – 4	ESDIRK – 3	ESDIRK – 2
Max. time step	6.53 E-06	6.55 E-06	6.46 E-6	6.67 E-6
time step / ERK time step	3.11	3.12	3.08	3.18
Run Time	564 sec.	506 sec.	438 sec.	365 sec.
	~ 9.5 min.	~ 8.5 min.	~ 7.5 min	~6 min.
Decrease in Run time vs. CN	89%	90%	91%	93%
Decrease in Run time vs. ERK	41%	47%	54%	62%
Period (1/s)	0.0036	0.0036	0.0036	0.0036
Avg. $C_D$	2.3	2.3	2.3	2.3

# Conclusions

- Implicit Runge-Kutta can reduce run-time
- Fewer stages
  - Reduce number of computations
  - No loss in accuracy
- ESDIRK faster than EDIRK
  - Due to factorization
- EDIRK - 10% run-time of SIMPLER, 53% of ERK
- ESDIRK – 7% run-time of SIMPLER, 38% of ERK

# Future Work

- Acceleration Techniques
  - Extend current implicit Runge-Kutta methods into 3D
  - Include rotor model in 3D and test with wind turbine
  - Multigrid
- Application
  - Solve wind energy problem with the use of CFD

Questions?