

Synthesis of Supervisor under partial observation

- Observability is not preserved under union:

$$L(G) = \text{pr}(a^*b a^*)$$

$$M(a) = M(b) \neq \epsilon.$$

$$K_1 = \{b\} \quad K_2 = \{aa\} \Rightarrow K_1, K_2 \text{ observable}$$

$$K = K_1 \cup K_2 = \{b, aa\} \text{ not observable.}$$

- observability not preserved under intersection

$$K_3 = \{b, aa, baa, aab\}, \quad K_4 = \{b, aa, ba\} \Rightarrow K_3, K_4 \text{ observable } \left. \vphantom{K_3, K_4} \right\} \text{ (HW)}$$

$$K_3 \cap K_4 = \{b, aa\} \text{ not observable.}$$

- Observability is preserved under union over a chain of increasing languages.

Consider such a chain $\{K_i\}$ with $K_i \subseteq K_{i+1}$, $\forall i \geq 0$.

Pick $s, t \in \text{pr}\left[\bigcup_i K_i\right]$, $\sigma \in \Sigma$ s.t. $M(s) = M(t)$, $s\sigma \in \text{pr}\left[\bigcup_i K_i\right]$, $t\sigma \in L(G)$.

Since $s, t, s\sigma \in \text{pr}\left[\bigcup_i K_i\right] = \bigcup_i \text{pr}(K_i)$, there exist i_1, i_2, i_3 such that $s \in \text{pr}(K_{i_1})$, $t \in \text{pr}(K_{i_2})$, $s\sigma \in \text{pr}(K_{i_3})$.

Choose $i = \max\{i_1, i_2, i_3\}$. Then $s, t, s\sigma \in \text{pr}(K_i)$.

So from observability of K_i , $t\sigma \in \text{pr}(K_i) \subseteq \bigcup_i \text{pr}(K_i) = \text{pr}\left[\bigcup_i K_i\right]$.

$\Rightarrow \max O(K)$: "maximal obs. sublang. of K exists."

- Since prefix-closed, relative-closure, controllability all preserved under union,

$\Rightarrow \max PCO(K)$ and $\max RCO(K)$ exist (use on-line computation method).

- Observability of prefix-closed lang. is preserved under intersection

$\Rightarrow \inf \overline{PO}(K)$ exists

Consider $\{K_i\}$ such that each K_i is $\overline{PO}(K)$.

Pick $s, t \in \bigcap_i K_i$, $\sigma \in \Sigma$ such that $s\sigma \in \bigcap_i K_i$, $t\sigma \in L(G)$.

Then $s, t, s\sigma \in K_i, \forall i \Rightarrow t\sigma \in K_i, \forall i \Rightarrow t\sigma \in \bigcap_i K_i$

Computation of $\inf \overline{PO}(K)$

Thm: $\inf \overline{PO}(K) = \underbrace{\sup P[\tilde{M}^{-1}\tilde{M}(\text{pr}(K))]}_H \cap L(G)$.

$$\left. \begin{aligned} \tilde{M}(\epsilon) &= \epsilon \\ \tilde{M}(\delta\sigma) &= M(\delta)\sigma \\ \Rightarrow \tilde{M}^{-1}\tilde{M}(\delta\sigma) &= \{\tau \mid M(\tau) = M(\delta\sigma)\} \end{aligned} \right\}$$

Need to show (i) $H \supseteq K$, (ii) $H \in \overline{PO}(K)$, (iii) $H' \in \overline{PO}(K) \Rightarrow H \subseteq H'$.

Proof: (i) $K \subseteq \text{pr}(K) \subseteq \sup P(\text{pr}(K)) \subseteq \sup P[\tilde{M}^{-1}\tilde{M}(\text{pr}(K))] \Rightarrow K \subseteq H$
 $K \subseteq L(G)$

(ii) H is intersection of two prefix-closed languages $\Rightarrow H$ prefix-closed

To see H observable, pick $s, t \in H, \sigma \in \Sigma$ s.t. $M(s) = M(t), \delta\sigma \in H, \tau \in L(G)$

To show $\tau\sigma \in H$, it suffices to show $\tau\sigma \in \sup P[\tilde{M}^{-1}\tilde{M}(\text{pr}(K))]$ (since $\tau\sigma \in K$)

I.e., every prefix of $\tau\sigma \in \tilde{M}^{-1}\tilde{M}(\text{pr}(K))$.

Since $t \in H \subseteq \sup P[\tilde{M}^{-1}\tilde{M}(\text{pr}(K))]$ every prefix of $t \in \tilde{M}^{-1}\tilde{M}(\text{pr}(K))$.

Suffices to show; $\tau\sigma \in \tilde{M}^{-1}\tilde{M}(\text{pr}(K))$. Follows since, $\delta\sigma \in H \subseteq \tilde{M}^{-1}\tilde{M}(\text{pr}(K))$
 (since $\tilde{M}(\delta\sigma) = \tilde{M}(\tau\sigma)$)

(iii) Suppose for contradiction, $\exists \delta \in H - H'$. Then $\delta \notin H'$ (since $H' \neq \emptyset$ & closed)

Thus $\delta = \bar{\delta}\sigma$, and let $\bar{\delta}$ be the smallest trace in $H - H'$. I.e., $\bar{\delta} \in H'$.

Since $\bar{\delta}\sigma \in H \subseteq \sup P[\tilde{M}^{-1}\tilde{M}(\text{pr}(K))]$; each prefix of $\bar{\delta}\sigma \in \tilde{M}^{-1}\tilde{M}(\text{pr}(K))$

$\Rightarrow \bar{\delta}\sigma \in \tilde{M}^{-1}\tilde{M}(\text{pr}(K)) \Rightarrow \exists \bar{\tau}\sigma = \text{pr}(K)$ s.t. $M(\bar{\tau}) = M(\bar{\delta})$.

Since $\text{pr}(K) \subseteq H'$, $\bar{\tau}\sigma \in H'$. ($\Rightarrow \bar{\tau} \in H'$, since H' prefix-closed)

So, we have $\bar{\delta}, \bar{\tau} \in H', \sigma \in \Sigma$ s.t. $\bar{\delta}\sigma \in H', \bar{\delta}\sigma = \delta \in L(G) \not\subseteq H$, but $\bar{\delta}\sigma \notin H'$

Contradiction to the fact that H' observable.

Modular computation of $\inf \overline{PO}(K)$

$$\left. \begin{aligned} \inf \overline{PCO}(K) &= K^M \Sigma^* \cap L(G) \\ K^M \Sigma^* &= (K^{\Sigma^*})^M \neq (K^M)^{\Sigma^*} \end{aligned} \right\} \begin{aligned} K^M \Sigma^* &= \inf \overline{PCO}(K) & \text{when } L(G) = \Sigma^* \\ &= \inf \overline{PC}(K) & \text{when } L(G) = \Sigma^* \\ &= \inf \overline{PO}(K) & \text{when } L(G) = \Sigma^*. \end{aligned}$$

$\inf \overline{PC}(K) = \text{pr}(K) \Sigma^* \cap L(G) \Rightarrow K^{\Sigma^*} = \text{pr}(K) \Sigma^*$

$\inf \overline{PO}(K) = \Rightarrow K^M = \sup P[\tilde{M}^{-1}\tilde{M}(\text{pr}(K))]$

Modular computation of $\inf \overline{\text{PCO}}(K)$

• $K^{\Sigma_u, M} = (K^{\Sigma_u})^M \quad \text{--- (1)}$

$\Rightarrow K^{\Sigma_u} \subseteq K^{\Sigma_u, M} \Rightarrow (K^{\Sigma_u})^M \subseteq (K^{\Sigma_u, M})^M = K^{\Sigma_u, M}$

(\Leftarrow) suffices to show that $(K^{\Sigma_u})^M \in \overline{\text{PCO}}(K)$ when $L(G) = \Sigma^*$

Since $(K^{\Sigma_u})^M \in \overline{\text{PCO}}(K)$ when $L(G) = \Sigma^*$, suffices to show $(K^{\Sigma_u})^M \in \overline{\text{PCO}}(K)$ when $L(G) = \Sigma^*$.

Pick $\delta \in (K^{\Sigma_u})^M, r \in \Sigma_u \Rightarrow \delta \in \text{supp } P[\tilde{M}^{-1} \tilde{M}(K^{\Sigma_u})] \subseteq \tilde{M}^{-1} \tilde{M}(K^{\Sigma_u})$

$\Rightarrow \forall t \in \delta : t \in \tilde{M}^{-1} \tilde{M}(K^{\Sigma_u})$

$\Rightarrow \forall t \in \delta : \exists u_t \in K^{\Sigma_u}$ s.t. $\tilde{M}(u_t) = \tilde{M}(t)$

Since $u_s \in K^{\Sigma_u}, r \in \Sigma_u$, follows that $u_{sr} \in K^{\Sigma_u}$

$\delta r \in \text{supp } [\tilde{M}^{-1} \tilde{M}(K^{\Sigma_u})] \subseteq \tilde{M}^{-1} \tilde{M}(K^{\Sigma_u})$
 $= (K^{\Sigma_u})^M.$

$\left\{ \begin{array}{l} \text{Also, } \tilde{M}(u_s) = \tilde{M}(s) \Rightarrow \tilde{M}(u_{sr}) = \tilde{M}(sr). \text{ So, } sr \in \tilde{M}^{-1} \tilde{M}(K^{\Sigma_u}) \\ \text{Also, } \forall t \in \delta : t \in \tilde{M}^{-1} \tilde{M}(K^{\Sigma_u}) \end{array} \right.$

• $\inf \overline{\text{PCO}}(K) = K^{\Sigma_u, M} \cap L(G) \stackrel{(1)}{=} (K^{\Sigma_u})^M \cap L(G)$

$\Leftarrow \inf \overline{\text{PCO}}(K) \subseteq K^{\Sigma_u, M}, \text{ and } \inf \overline{\text{PCO}}(K) \subseteq L(G).$

(\Rightarrow) induction on length of traces.

base step (length of trace = 0): $\varepsilon \in \inf \overline{\text{PCO}}(K)$ ✓

induction step: Pick $sr \in (K^{\Sigma_u})^M \cap L(G)$. From induction hyp. $\delta \in \inf \overline{\text{PCO}}(K)$.

Since $sr \in (K^{\Sigma_u})^M \cap L(G) \subseteq (K^{\Sigma_u})^M = \text{supp } P[\tilde{M}^{-1} \tilde{M}(K^{\Sigma_u})] \subseteq \tilde{M}^{-1} \tilde{M}(K^{\Sigma_u})$

$\exists tr \in K^{\Sigma_u} = \text{pr}(K) \Sigma_u^*$ s.t. $M(t) = M(s)$

Then either $tr \in \text{pr}(K)$ or $t \in \text{pr}(K)$ and $r \in \Sigma_u$.

(i) $tr \in \text{pr}(K) \subseteq \inf \overline{\text{PCO}}(K), M(t) = M(s), sr \in L(G) \Rightarrow \delta sr \in \inf \overline{\text{PCO}}(K)$ (obs.)

(ii) $r \in \Sigma_u, \delta \in \inf \overline{\text{PCO}}(K), sr \in L(G) \Rightarrow \delta sr \in \inf \overline{\text{PCO}}(K)$ (ctrl.)

On-line control computation with linear complexity

① Initialize: $\hat{z} := \{z_0\}$, $Elist := \text{ordered}(\Sigma - \Sigma_u)$
 If $R_{\Sigma_u}(\hat{z}) \not\subseteq Z_g$, then ERROR and STOP

② Control computation: (a) $\hat{\Sigma} := \Sigma_u$, $pt := 0$

(b) If $pt = |Elist|$, then $ACT := \hat{\Sigma}$ and goto 3.

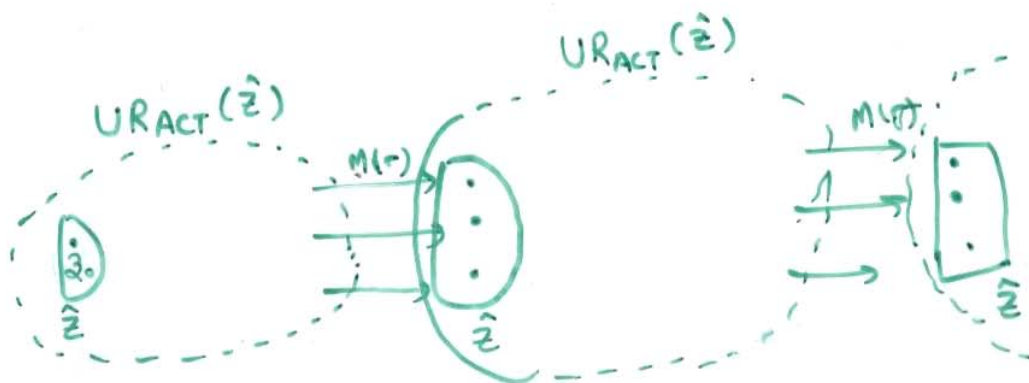
(c) $pt := pt + 1$, $\hat{\Sigma} := \hat{\Sigma} \cup \{Elist.pt\}$,

If $UR_{\hat{\Sigma}}(\hat{z}) \not\subseteq Z_g$, then $\hat{\Sigma} := \hat{\Sigma} - \{Elist.pt\}$. Goto 2(b)

If $UR_{\hat{\Sigma} \cup \{Elist.pt\}}(\hat{z}) \subseteq Z_g$, then $\hat{\Sigma} = \hat{\Sigma} \cup \{Elist.pt\}$. Goto 2(b)

③ Update state-estimate: Wait for observable $M(r)$ to occur, then

$\hat{z} := \gamma(UR_{ACT}(\hat{z}), M^{-1}M(r))$ and goto 2.



Enable $\Sigma_{ACT} \subseteq \Sigma$ s.t. $UR_{+ACT}(\hat{z}) \subseteq Z_g$

~~If blocking is not an issue (spec. is safety spec. \rightarrow prefix closed)~~

then $Z_{nb} = Z_g$.

- No known algorithm for $\max RCO(k)$.
- Computation of each "ACT" set has $O(mn)$ complexity, and it is a function of only the state estimate \hat{z} (which has cardinality of 2^{mn}).