Note: Handouts DO NOT replace the book. In most cases, they only provide a guideline on topics and an intuitive feel.

1 Random Variable: Topics

- Chap 2, 2.1 2.4 and Chap 3, 3.1 3.3
- What is a random variable?
- Discrete random variable (r.v.)
 - Probability Mass Function (pmf)
 - pmf of Bernoulli, Binomial, Geometric, Poisson
 - pmf of Y = g(X)
 - Mean and Variance, Computing for Bernoulli, Poisson
- Continuous random variable
 - Probability Density Function (pdf) and connection with pmf
 - Mean and Variance
 - Uniform and exponential random variables
- Cumulative Distribution Function (cdf)
 - Relation with pdf and pmf
 - Connection between Geometric and Exponential **
 - Connection between Binomial and Poisson **
- Gaussian (or Normal) random variable

2 What is a random variable (r.v.)?

- A real valued function of the outcome of an experiment
- Example: Coin tosses. r.v. X = 1 if heads and X = 0 if tails (Bernoulli r.v.).
- A function of a r.v. defines another r.v.
- Discrete r.v.: X takes values from the set of integers

3 Discrete Random Variables & Probability Mass Function (pmf)

• Probability Mass Function (pmf): Probability that the r.v. X takes a value x is pmf of X computed at X = x. Denoted by $p_X(x)$. Thus

$$p_X(x) = P(\{X = x\}) = P(\text{all possible outcomes that result in the event } \{X = x\})$$
 (1)

- Everything that we learnt in Chap 1 for events applies. Let Ω is the sample space (space of all possible values of X in an experiment). Applying the axioms,
 - $-p_X(x) \geq 0$
 - $-P(\{X \in S\}) = \sum_{x \in S} p_X(x)$ (follows from Additivity since different events $\{X = x\}$ are disjoint)
 - $-\sum_{x\in\Omega}p_X(x)=1$ (follows from Additivity and Normalization).
 - Example: X = number of heads in 2 fair coin tosses (p = 1/2). $P(X > 0) = \sum_{x=1}^{2} p_X(x) = 0.75$.
- Can also define a binary r.v. for any event A as: X = 1 if A occurs and X = 0 otherwise. Then X is a Bernoulli r.v. with p = P(A).
- Bernoulli (X = 1 (heads) or X = 0 (tails)) r.v. with probability of heads p

Bernoulli(p):
$$p_X(x) = p^x (1-p)^{1-x}$$
, $x = 0$, or $x = 1$ (2)

• Binomial (X = x heads out of n independent tosses, probability of heads p)

Binomial(n,p):
$$p_X(x) = \binom{n}{x} p^x (1-p)^{n-x}, x = 0, 1, \dots n$$
 (3)

- Geometric r.v., X, with probability of heads p (X= number of coin tosses needed for a head to come up for the first time or number of independent trials needed to achieve the first "success").
 - Example: I keep taking a test until I pass it. Probability of passing the test in the x^{th} try is $p_X(x)$.
 - Easy to see that

Geometric(p):
$$p_X(x) = (1-p)^{x-1}p, \quad x = 0, 1, 2, \dots \infty$$
 (4)

• Poisson r.v. X with expected number of arrivals Λ (e.g. if X= number of arrivals in time τ with arrival rate λ , then $\Lambda=\lambda\tau$)

$$Poisson(\Lambda): \ p_X(x) = \frac{e^{-\Lambda}(\Lambda)^x}{x!}, \ x = 0, 1, \dots \infty$$
 (5)

• Uniform(a,b):

$$p_X(x) = \begin{cases} 1/(b-a+1), & if \ x = a, a+1, \dots b \\ 0, & otherwise \end{cases}$$
 (6)

• pmf of Y = g(X)

$$- p_Y(y) = P(\{Y = y\}) = \sum_{x|g(x) = y} p_X(x)$$

Example $Y = |X|$. Then $p_Y(y) = p_X(y) + p_X(-y)$, if $y > 0$ and $p_Y(0) = p_X(0)$.
Exercise: $X \sim Uniform(-4, 4)$ and $Y = |X|$, find $p_Y(y)$.

- Expectation, mean, variance
 - Motivating example: Read pg 81
 - Expected value of X (or mean of X): $E[X] \triangleq \sum_{x \in \Omega} x p_X(x)$
 - Interpret mean as center of gravity of a bar with weights $p_X(x)$ placed at location x (Fig. 2.7)
 - Expected value of Y = g(X): $E[Y] = E[g(X)] = \sum_{x \in \Omega} g(x) p_X(x)$. Exercise: show this.
 - n^{th} moment of X: $E[X^n]$. n^{th} central moment: $E[(X E[X])^n]$.
 - Variance of X: $var[X] \triangleq E[(X E[X])^2]$ (2nd central moment)
 - -Y = aX + b (linear fn): E[Y] = aE[X] + b, $var[Y] = a^{2}var[X]$
 - Poisson: $E[X] = \Lambda$, $var[X] = \Lambda$ (show this)
 - Bernoulli: E[X] = p, var[X] = p(1-p) (show this)
 - Uniform(a,b): E[X] = (a+b)/2, $var[X] = \frac{(b-a+1)^2-1}{12}$ (show this)
- Application: Computing average time. Example 2.4
- Application: Decision making using expected values. Example 2.8 (Quiz game, compute expected reward with two different strategies to decide which is a better strategy).
- Binomial(n, p) becomes Poisson(np) if time interval between two coin tosses becomes very small (so that n becomes very large and p becomes very small, but $\Lambda = np$ is finite). **

4 Continuous R.V. & Probability Density Function (pdf)

- Example: velocity of a car
- A r.v. X is called **continuous** if there is a function $f_X(x)$ with $f_X(x) \ge 0$, called **probability** density function (pdf), s.t. $P(X \in B) = \int_B f_X(x) dx$ for all subsets B of the real line.
- Specifically, for B = [a, b],

$$P(a \le X \le b) = \int_{x=a}^{b} f_X(x) dx \tag{7}$$

and can be interpreted as the area under the graph of the pdf $f_X(x)$.

- For any single value a, $P({X = a}) = \int_{x=a}^{a} f_X(x)dx = 0$.
- Thus $P(a \le X \le b) = P(a < X < b) = P(a \le X < b) = P(a < X \le b)$
- Sample space $\Omega = (-\infty, \infty)$

- Normalization: $P(\Omega) = P(-\infty < X < \infty) = 1$. Thus $\int_{x=-\infty}^{\infty} f_X(x) dx = 1$
- Interpreting the pdf: For an interval $[x, x + \delta]$ with very small δ ,

$$P([x, x + \delta]) = \int_{t=x}^{x+\delta} f_X(t)dt \approx f_X(x)\delta$$
 (8)

Thus $f_X(x)$ = probability mass per unit length near x. See Fig. 3.2.

- Continuous uniform pdf, Example 3.1
- Piecewise constant pdf, Example 3.2
- Connection with a pmf (explained after cdf is explained) **
- Expected value: $E[X] = \int_{x=-\infty}^{\infty} x f_X(x) dx$. Similarly define E[g(X)] and var[X]
- Mean and variance of uniform, Example 3.4
- Exponential r.v.

$$f_X(x) = \begin{cases} \lambda e^{-\lambda x}, & if \ x \ge 0\\ 0, & otherwise \end{cases}$$
 (9)

- Show it is a legitimate pdf.
- $E[X] = 1/\lambda, \ var[X] = 1/\lambda^2 \ (show).$
- Example: X= amount of time until an equipment breaks down or a bulb burns out.
- Example 3.5 (Note: you need to use the correct time unit in the problem, here days).

5 Cumulative Distribution Function (cdf)

- Cumulative Distribution Function (cdf), $F_X(x) \triangleq P(X \leq x)$ (probability of event $\{X \leq x\}$).
- Defined for discrete and continuous r.v.'s

Discrete:
$$F_X(x) = \sum_{k \le x} p_X(k)$$
 (10)

Continuous:
$$F_X(x) = \int_{-\infty}^x f_X(t)dt$$
 (11)

- Note the pdf $f_X(x)$ is NOT a probability of any event, it can be > 1.
- But $F_X(x)$ is the probability of the event $\{X \leq x\}$ for both continuous and discrete r.v.'s.
- Properties
 - $F_X(x)$ is monotonically nondecreasing in x.
 - $-F_X(x) \to 0$ as $x \to -\infty$ and $F_X(x) \to 1$ as $x \to \infty$
 - $-F_X(x)$ is continuous for continuous r.v.'s and it is piecewise constant for discrete r.v.'s

• Relation to pmf, pdf

Discrete:
$$p_X(k) = F_X(k) - F_X(k-1)$$
 (12)

Continuous:
$$f_X(x) = \frac{dF_X}{dx}(x)$$
 (13)

- Using cdf to compute pmf.
 - Example 3.6: Compute pmf of maximum of 3 r.v.'s: What is the pmf of the maximum score of 3 test scores, when each test score is independent of others and each score takes any value between 1 and 10 with probability 1/10?

Answer: Compute $F_X(k) = P(X \le k) = P(\{X_1 \le k\}, \text{ and } \{X_2 \le k\}, \text{ and } \{X_3 \le k\}) = P(\{X_1 \le k\})P(\{X_2 \le k\})P\{X_3 \le k\})$ (follows from independence of the 3 events) and then compute the pmf using (12).

- For continuous r.v.'s, in almost all cases, the correct way to compute the cdf of a function of a continuous r.v. (or of a set of continuous r.v.'s) is to compute the cdf first and then take its derivative to get the pdf. We will learn this later.
- Connection of a pdf with a pmf **
 - You learnt the Dirac delta function in EE 224. We use it to define a pdf for discrete r.v.
 - The pdf of a discrete r.v. X, $f_X(x) \triangleq \sum_{j=-\infty}^{\infty} p_X(j)\delta(x-j)$.
 - If I integrate this, I get $F_X(x) = \int_{t \le x} f_X(t) dt = \sum_{j \le x} p_X(j)$ which is the same as the cdf definition given in (10)
- Geometric and exponential cdf **
 - Let $X_{geo,p}$ be the number of trials required for the first success (geometric) with probability of success = p. Then we can show that the probability of $\{X_{geo,p} \leq k\}$ is equal to the probability of an exponential r.v. $\{X_{expo,\lambda} \leq k\delta\}$ with parameter λ , if δ satisfies $1-p=e^{-\lambda\delta}$ or $\delta=-\ln(1-p)/\lambda$

Proof: Equate $F_{X_{geo,p}}(k) = 1 - (1-p)^k$ to $F_{X_{expo,\lambda}}(k\delta) = 1 - e^{-\lambda k\delta}$

- Implication: When δ (time interval between two Bernoulli trials (coin tosses)) is small, then $F_{X_{geo,p}}(k) \approx F_{X_{expo,\lambda}}(k\delta)$ with $p = \lambda \delta$ (follows because $e^{-\lambda \delta} \approx 1 \lambda \delta$ for δ small).
- Binomial(n, p) becomes Poisson(np) for small time interval, δ , between coin tosses (Details in Chap 5) **

Proof idea:

- Consider a sequence of n independent coin tosses with probability of heads p in any toss (number of heads $\sim Binomial(n, p)$).
- Assume the time interval between two tosses is δ .
- Then expected value of X in one toss (in time δ) is p.
- When δ small, expected value of X per unit time is $\lambda = p/\delta$.
- The total time duration is $\tau = n\delta$.

- When $\delta \to 0$, but λ and τ are finite, $n \to \infty$ and $p \to 0$.
- When δ small, can show that the pmf of a Binomial(n,p) r.v. is approximately equal to the pmf of $Poisson(\lambda \tau)$ r.v. with $\lambda \tau = np$
- The Poisson process is a continuous time analog of a Bernoulli process (Details in Chap 5) **

6 Normal (Gaussian) Random Variable

- The most commonly used r.v. in Communications and Signal Processing
- X is normal or Gaussian if it has a pdf of the form

$$f_X(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-(x-\mu)^2/2\sigma^2}$$

where one can show that $\mu = E[X]$ and $\sigma^2 = var[X]$.

- Standard normal: Normal r.v. with $\mu = 0, \sigma^2 = 1$.
- Cdf of a standard normal Y, denoted $\Phi(y)$

$$\Phi(y) \triangleq P(Y \le y) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{y} e^{-t^2/2} dt$$

It is recorded as a table (See pg 155).

- Let X is a normal r.v. with mean μ , variance σ^2 . Then can show that $Y = \frac{X-\mu}{\sigma}$ is a standard normal r.v.
- Computing cdf of any normal r.v. X using the table for Φ : $F_X(x) = \Phi(\frac{x-\mu}{\sigma})$. See Example 3.7.
- Signal detection example (computing probability of error): Example 3.8. See Fig. 3.11. A binary message is tx as a signal S which is either -1 or +1. The channel corrupts the tx with additive Gaussian noise, N, with mean zero and variance σ^2 . The received signal, Y = S + N. The receiver concludes that a -1 (or +1) was tx'ed if Y < 0 ($Y \ge 0$). What is the probability of error? Answer: It is given by $P(N \ge 1) = 1 \Phi(1/\sigma)$. How we get the answer will be discussed in class.
- Normal r.v. models the additive effect of many independent factors well **
 - This is formally stated as the central limit theorem (see Chap 7): sum of a large number of independent and identically distributed (not necessarily normal) r.v.'s has an approximately normal cdf.

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1 Multiple Discrete Random Variables: Topics

- Joint PMF, Marginal PMF of 2 and or more than 2 r.v.'s
- PMF of a function of 2 r.v.'s
- Expected value of functions of 2 r.v's
- Expectation is a linear operator. Expectation of sums of n r.v.'s
- Conditioning on an event and on another r.v.
- Bayes rule
- Independence

2 Joint & Marginal PMF, PMF of function of r.v.s, Expectation

- For everything in this handout, you can think in terms of events $\{X = x\}$ and $\{Y = y\}$ and apply what you have learnt in Chapter 1.
- The **joint PMF** of two random variables X and Y is defined as

$$p_{X,Y}(x,y) \triangleq P(X=x,Y=y)$$

where P(X = x, Y = y) is the same as $P({X = x} \cap {Y = y})$.

- Let A be the set of all values of x,y that satisfy a certain property, then $P((X,Y)\in A)=\sum_{(x,y)\in A}p_{X,Y}(x,y)$
- e.g. X = outcome of first die toss, Y is outcome of second die toss, A = sum of outcomes of the two tosses is even.
- Marginal PMF is another term for the PMF of a single r.v. obtained by "marginalizing" the joint PMF over the other r.v., i.e. the marginal PMF of X, $p_X(x)$ can be computed as follows:

Apply Total Probability Theorem to $p_{X,Y}(x,y)$, i.e. sum over $\{Y=y\}$ for different values y (these are a set of disjoint events whose union is the sample space):

$$p_X(x) = \sum_{y} p_{X,Y}(x,y)$$

Similarly the marginal PMF of Y, $p_Y(y)$ can be computed by "marginalizing" over X

$$p_Y(y) = \sum_{x} p_{X,Y}(x,y)$$

• PMF of a function of r.v.'s: If Z = g(X, Y),

$$p_Z(z) = \sum_{(x,y):g(x,y)=z} p_{X,Y}(x,y)$$

- Read the above as $p_Z(z) = P(Z = z) = P(\text{all values of }(X,Y) \text{ for which } g(X,Y) = z)$
- Expected value of functions of multiple r.v.'s If Z = g(X, Y),

$$E[Z] = \sum_{(x,y)} g(x,y) p_{X,Y}(x,y)$$

- See Example 2.9
- More than 2 r.v.s.
 - Joint PMF of n r.v.'s: $p_{X_1,X_2,...X_n}(x_1,x_2,...x_n)$
 - We can **marginalize** over one or more than one r.v.,

e.g.
$$p_{X_1,X_2,...X_{n-1}}(x_1,x_2,...x_{n-1}) = \sum_{x_n} p_{X_1,X_2,...X_n}(x_1,x_2,...x_n)$$

e.g.
$$p_{X_1,X_2}(x_1,x_2) = \sum_{x_3,x_4,\dots x_n} p_{X_1,X_2,\dots X_n}(x_1,x_2,\dots x_n)$$

e.g. $p_{X_1}(x_1) = \sum_{x_2,x_3,\dots x_n} p_{X_1,X_2,\dots X_n}(x_1,x_2,\dots x_n)$

e.g.
$$p_{X_1}(x_1) = \sum_{x_2, x_3, \dots, x_n} p_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n)$$

See book, Page 96, for special case of 3 r.v.'s

• Expectation is a linear operator. Exercise: show this

$$E[a_1X_1 + a_2X_2 + \dots a_nX_n] = a_1E[X_1] + a_2E[X_2] + \dots a_nE[X_n]$$

- Application: Binomial(n, p) is the sum of n Bernoulli r.v.'s. with success probability p, so its expected value is np (See Example 2.10)
- See Example 2.11

Conditioning and Bayes rule

• PMF of r.v. X conditioned on an event A with P(A) > 0

$$p_{X|A}(x) \triangleq P(\{X = x\}|A) = \frac{P(\{X = x\} \cap A)}{P(A)}$$

- $-p_{X|A}(x)$ is a legitimate PMF, i.e. $\sum_{x} p_{X|A}(x) = 1$. Exercise: Show this
- Example 2.12, 2.13
- PMF of r.v. X conditioned on r.v. Y. Replace A by $\{Y = y\}$

$$p_{X|Y}(x|y) \triangleq P(\{X=x\}|\{Y=y\}) = \frac{P(\{X=x\} \cap \{Y=y\})}{P(\{Y=y\})} = \frac{p_{X,Y}(x,y)}{p_{Y}(y)}$$

The above holds for all y for which $p_y(y) > 0$. The above is equivalent to

$$p_{X,Y}(x,y) = p_{X|Y}(x|y)p_Y(y)$$

$$p_{X,Y}(x,y) = p_{Y|X}(y|x)p_X(x)$$

- $-p_{X|Y}(x|y)$ (with $p_Y(y) > 0$) is a legitimate PMF, i.e. $\sum_x p_{X|Y}(x|y) = 1$.
- Similarly, $p_{Y|X}(y|x)$ is also a legitimate PMF, i.e. $\sum_{y} p_{Y|X}(y|x) = 1$. Show this.
- Example 2.14 (I did a modification in class), 2.15
- Bayes rule. How to compute $p_{X|Y}(x|y)$ using $p_X(x)$ and $p_{Y|X}(y|x)$,

$$p_{X|Y}(x|y) = \frac{p_{X,Y}(x,y)}{p_{Y}(y)}$$
$$= \frac{p_{Y|X}(y|x)p_{X}(x)}{\sum_{x'} p_{Y|X}(y|x')p_{X}(x')}$$

• Conditional Expectation given event A

$$E[X|A] = \sum_{x} x p_{X|A}(x)$$

$$E[g(X)|A] = \sum_{x} g(x) p_{X|A}(x)$$

• Conditional Expectation given r.v. Y = y. Replace A by $\{Y = y\}$

$$E[X|Y = y] = \sum_{x} x p_{X|Y}(x|y)$$

Note this is a function of Y = y.

• Total Expectation Theorem

$$E[X] = \sum_{y} p_Y(y)E[X|Y = y]$$

Proof on page 105.

• Total Expectation Theorem for disjoint events $A_1, A_2, \dots A_n$ which form a partition of sample space.

$$E[X] = \sum_{i=1}^{n} P(A_i)E[X|A_i]$$

Note A_i 's are disjoint and $\bigcup_{i=1}^n A_i = \Omega$

- Application: Expectation of a geometric r.v., Example 2.16, 2.17

4 Independence

• Independence of a r.v. & an event A. r.v. X is independent of A with P(A) > 0, iff

$$p_{X|A}(x) = p_X(x)$$
, for all x

- This also implies: $P({X = x} \cap A) = p_X(x)P(A)$.

- See Example 2.19
- Independence of 2 r.v.'s. R.v.'s X and Y are independent iff

$$p_{X|Y}(x|y) = p_X(x)$$
, for all x and for all y for which $p_Y(y) > 0$

This is equivalent to the following two things(show this)

$$p_{X,Y}(x,y) = p_X(x)p_Y(y)$$

$$p_{Y|X}(y|x) = p_Y(y)$$
, for all y and for all x for which $p_X(x) > 0$

- Conditional Independence of r.v.s X and Y given event A with P(A) > 0 ** $p_{X|Y,A}(x|y) = p_{X|A}(x)$ for all x and for all y for which $p_{Y|A}(y) > 0$ or that $p_{X,Y|A}(x,y) = p_{X|A}(x)p_{Y|A}(y)$
- Expectation of product of independent r.v.s.
 - If X and Y are independent, E[XY] = E[X]E[Y].

$$E[XY] = \sum_{y} \sum_{x} xyp_{X,Y}(x,y)$$

$$= \sum_{y} \sum_{x} xyp_{X}(x)p_{Y}(y)$$

$$= \sum_{y} yp_{Y}(y) \sum_{x} xp_{X}(x)$$

$$= E[X]E[Y]$$

- If X and Y are independent, E[g(X)h(Y)] = E[g(X)]E[h(Y)]. (Show).
- If $X_1, X_2, \ldots X_n$ are independent,

$$p_{X_1,X_2,...X_n}(x_1,x_2,...x_n) = p_{X_1}(x_1)p_{X_2}(x_2)...p_{X_n}(x_n)$$

• Variance of sum of 2 independent r.v.'s.

Let X, Y are independent, then Var[X+Y] = Var[X] + Var[Y]. See book page 112 for the proof

• Variance of sum of n independent r.v.'s.

If $X_1, X_2, \dots X_n$ are independent,

$$Var[X_1 + X_2 + \dots X_n] = Var[X_1] + Var[X_2] + \dots Var[X_n]$$

- .
- Application: Variance of a Binomial, See Example $2.20\,$

Binomial r.v. is a sum of n independent Bernoulli r.v.'s. So its variance is np(1-p)

- Application: Mean and Variance of Sample Mean, Example 2.21

Let $X_1, X_2, ... X_n$ be independent and *identically distributed*, i.e. $p_{X_i}(x) = p_{X_1}(x)$ for all i. Thus all have the same mean (denote by a) and same variance (denote by v). Sample mean is defined as $S_n = \frac{X_1 + X_2 + ... X_n}{n}$.

Since E[.] is a linear operator, $E[S_n] = \sum_{i=1}^n \frac{1}{n} E[X_i] = \frac{na}{n} = a$.

Since the X_i 's are independent, $Var[S_n] = \sum_{i=1}^n \frac{1}{n^2} Var[X_i] = \frac{nv}{n^2} = \frac{v}{n}$

- Application: Estimating Probabilities by Simulation, See Example 2.22

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1 Multiple Continuous Random Variables: Topics

- Conditioning on an event
- Joint and Marginal PDF
- Expectation, Independence, Joint CDF, Bayes rule
- Derived distributions
 - Function of a Single random variable: Y = g(X) for any function g
 - Function of a Single random variable: Y = g(X) for linear function g
 - Function of a Single random variable: Y = g(X) for strictly monotonic g
 - Function of Two random variables: Z = g(X, Y) for any function g

2 Conditioning on an event

• Read the book Section 3.4

3 Joint and Marginal PDF

- Two r.v.s X and Y are **jointly continuous** iff there is a function $f_{X,Y}(x,y)$ with $f_{X,Y}(x,y) \ge 0$, called the **joint PDF**, s.t. $P((X,Y) \in B) = \int_B f_{X,Y}(x,y) dx dy$ for all subsets B of the 2D plane.
- Specifically, for $B = [a, b] \times [c, d] \triangleq \{(x, y) : a \le x \le b, c \le y \le d\},\$

$$P(a \le X \le b, c \le Y \le d) = \int_{u=c}^{d} \int_{x=a}^{b} f_{X,Y}(x,y) dx dy$$

• Interpreting the joint PDF: For small positive numbers δ_1, δ_2 ,

$$P(a \le X \le a + \delta_1, c \le Y \le c + \delta_2) = \int_{y=c}^{c+\delta_2} \int_{x=a}^{a+\delta_1} f_{X,Y}(x,y) dx dy \approx f_{X,Y}(a,c) \delta_1 \delta_2$$

Thus $f_{X,Y}(a,c)$ is the probability mass per unit area near (a,c).

• Marginal PDF: The PDF obtained by integrating the joint PDF over the entire range of one r.v. (in general, integrating over a set of r.v.'s)

$$P(a \le X \le b) = P(a \le X \le b, -\infty \le Y \le \infty) = \int_{x=a}^{b} \int_{y=-\infty}^{\infty} f_{X,Y}(x,y) dy dx$$

$$\implies f_X(x) = \int_{y=-\infty}^{\infty} f_{X,Y}(x,y) dy$$

• Example 3.12, 3.13

4 Conditional PDF

• Conditional PDF of X given that Y = y is defined as

$$f_{X|Y}(x|y) \triangleq \frac{f_{X,Y}(x,y)}{f_{Y}(y)}$$

- For any y, $f_{X|Y}(x|y)$ is a legitimate PDF: integrates to 1.
- Example 3.15
- Interpretation: For small positive numbers δ_1, δ_2 , consider the probability that X belongs to a small interval $[x, x + \delta_1]$ given that Y belongs to a small interval $[y, y + \delta_2]$

$$P(x \le X \le x + \delta_1 | y \le Y \le y + \delta_2) = \frac{P(x \le X \le x + \delta_1, y \le Y \le y + \delta_2)}{P(y \le Y \le y + \delta_2)}$$

$$\approx \frac{f_{X,Y}(x,y)\delta_1\delta_2}{f_Y(y)\delta_2}$$

$$= f_{X|Y}(x|y)\delta_1$$

• Since $f_{X|Y}(x|y)\delta_1$ does not depend on δ_2 , we can think of the limiting case when $\delta_2 \to 0$ and so we get

$$P(x \le X \le x + \delta_1 | Y = y) = \lim_{\delta_2 \to 0} P(x \le X \le x + \delta_1 | y \le Y \le y + \delta_2) \approx f_{X|Y}(x|y)\delta_1 \quad \delta_1 \text{ small } x \in X \le x + \delta_1 | y \le Y \le y + \delta_2$$

• In general, for any region A, we have that

$$P(X \in A|Y = y) = \lim_{\delta \to 0} P(X \in A|y \le Y \le y + \delta) = \int_{x \in A} f_{X|Y}(x|y) dx$$

5 Expectation, Independence, Joint & Conditional CDF, Bayes rule

- Expectation: See page 172 for E[g(X)|Y=y], E[g(X,Y)|Y=y] and total expectation theorem for E[g(X)] and for E[g(X,Y)].
- Independence: X and Y are independent iff $f_{X|Y} = f_X$ (or iff $f_{X,Y} = f_X f_Y$, or iff $f_{Y|X} = f_Y$)
- If X and Y independent, any two events $\{X \in A\}$ and $\{Y \in B\}$ are independent.
- If X and Y independent, E[g(X)h(Y)] = E[g(X)]E[h(Y)] and Var[X+Y] = Var[X] + Var[Y]Exercise: show this.
- Joint CDF:

$$F_{X,Y}(x,y) = P(X \le x, Y \le y) = \int_{t=-\infty}^{y} \int_{s=-\infty}^{x} f_{X,Y}(s,t) ds dt$$

• Obtain joint PDF from joint CDF:

$$f_{X,Y}(x,y) = \frac{\partial^2 F_{X,Y}}{\partial x \partial y}(x,y)$$

• Conditional CDF:

$$F_{X|Y}(x|y) = P(X \le x|Y = y) = \lim_{\delta \to 0} P(X \le x|y \le Y \le y + \delta) = \int_{t = -\infty}^{x} f_{X|Y}(t|y)dt$$

- Bayes rule when unobserved phenomenon is continuous. Pg 175 and Example 3.18
- Bayes rule when unobserved phenomenon is discrete. Pg 176 and Example 3.19. For e.g., say discrete r.v. N is the unobserved phenomenon. Then for δ small,

$$P(N = i | X \in [x, x + \delta]) = P(N = i | X \in [x, x + \delta])$$

$$= \frac{P(n = i)P(X \in [x, x + \delta]|N = i)}{P(X \in [x, x + \delta])}$$

$$\approx \frac{p_N(i)f_{X|N=i}(x)\delta}{\sum_j p_N(j)f_{X|N=j}(x)\delta}$$

$$= \frac{p_N(i)f_{X|N=i}(x)}{\sum_j p_N(j)f_{X|N=j}(x)}$$

Notice that the right hand side is independent of δ . Thus we can take $\lim_{\delta\to 0}$ on both sides and the right side will not change. Thus we get

$$P(N = i | X = x) = \lim_{\delta \to 0} P(N = i | X \in [x, x + \delta]) = \frac{p_N(i) f_{X|N=i}(x)}{\sum_i p_N(j) f_{X|N=i}(x)}$$

• More than 2 random variables (Pg 178, 179) **

6 Derived distributions: PDF of g(X) and of g(X,Y)

- Obtaining PDF of Y = g(X). ALWAYS use the following 2 step procedure:
 - Compute CDF first. $F_Y(y) = P(g(X) \le y) = \int_{x|g(x) \le y} f_X(x) dx$
 - Obtain PDF by differentiating F_Y , i.e. $f_Y(y) = \frac{\partial F_Y}{\partial y}(y)$
- Example 3.20, 3.21, 3.22
- Special Case 1: Linear Case: Y = aX + b. Can show that

$$f_Y(y) = \frac{1}{|a|} f_X(\frac{y-b}{a})$$

Proof: see Pg 183.

- Example 3.23, 3.24
- Special Case 2: Strictly Monotonic Case.

- Consider Y = g(X) with g being a **strictly monotonic** function of X.
- Thus g is a one to one function.
- Thus there exists a function h s.t. y = g(x) iff x = h(y) (i.e. h is the inverse function of g, often denotes as $h \triangleq g^{-1}$).
- Then can show that

$$f_Y(y) = f_X(h(y)) \left| \frac{dh}{dy}(y) \right|$$

- Proof for strictly monotonically increasing g: $F_Y(y) = P(g(X) \le Y) = P(X \le h(Y)) = F_X(h(y)).$ Differentiate both sides w.r.t y (apply chain rule on the right side) to get:

$$f_Y(y) = \frac{dF_Y}{dy}(y) = \frac{dF_X(h(y))}{dy} = f_X(h(y))\frac{dh}{dy}(y)$$

For strictly monotonically decreasing g, using a similar procedure, we get $f_Y(y) = -f_X(h(y))\frac{dh}{dy}(y)$

- See Figure 3.22, 3.23 for intuition
- Example 3.21 (page 186)
- Functions of two random variables. Again use the 2 step procedure, first compute CDF of Z = g(X, Y) and then differentiate to get the PDF.
- CDF of Z is computed as: $F_Z(z) = P(g(X,Y) \le z) = \int_{x,y:g(x,y) \le z} f_{X,Y}(x,y) dy dx$.
- Example 3.26, 3.27
- Example 3.28
- Special case 1: PDF of $Z = e^{sX}$ (moment generating function): Chapter 4, 4.1
- Special case 2: PDF of Z = X + Y when X, Y are independent: convolution of PDFs of X and Y: Chapter 4, 4.2