

# **CprE 281: Digital Logic**

**Instructor: Alexander Stoytchev**

**<http://www.ece.iastate.edu/~alexs/classes/>**

# Serial Adder

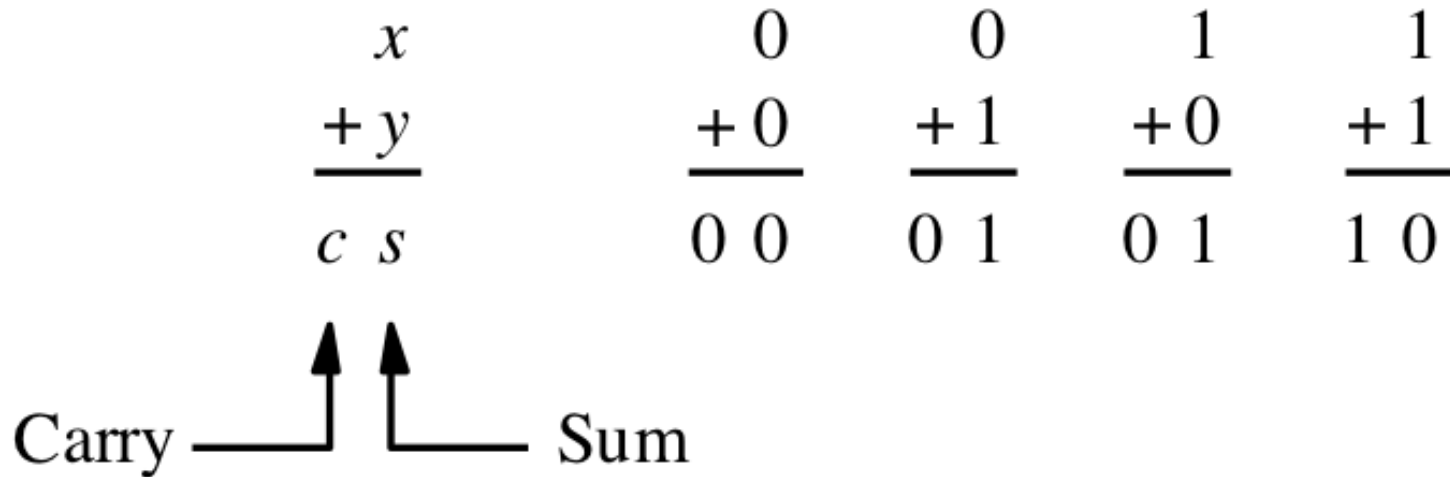
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# **Administrative Stuff**

- **Homework 11 is due on Monday Nov 18 @ 10pm**

# **Quick Review**

# Adding two bits (there are four possible cases)



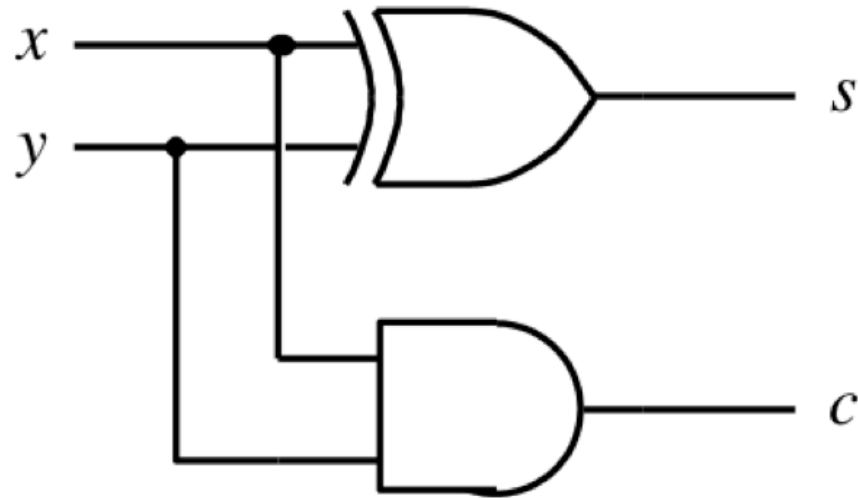
[ Figure 3.1a from the textbook ]

# Adding two bits (the truth table)

$x$	$y$	Carry $c$	Sum
0	0	0	0
0	1	0	1
1	0	0	1
1	1	1	0

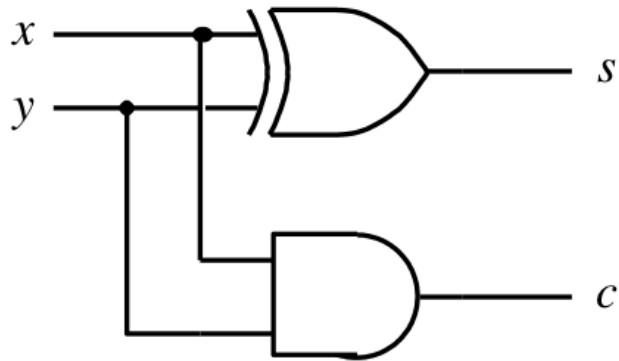
[ Figure 3.1b from the textbook ]

# Adding two bits (the logic circuit)



[ Figure 3.1c from the textbook ]

# The Half-Adder



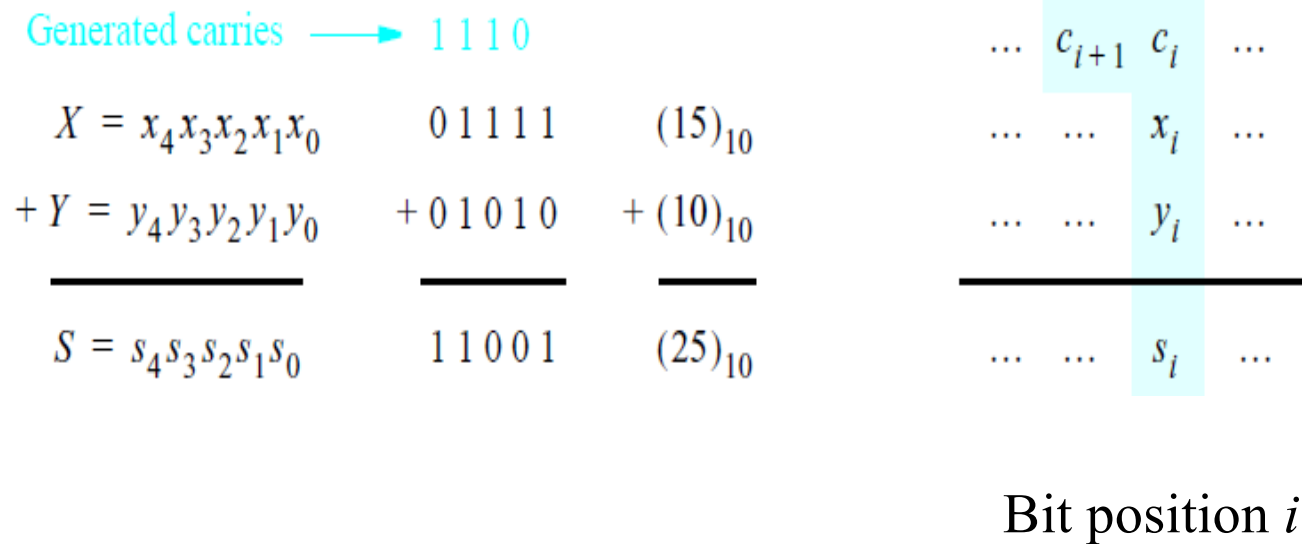
(c) Circuit



(d) Graphical symbol



# Addition of multibit numbers



[ Figure 3.2 from the textbook ]

# Problem Statement and Truth Table

...	$c_{l+1}$	$c_l$	...
...	...	$x_l$	...
...	...	$y_l$	...
...	...	$s_l$	...

$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

[ Figure 3.2b from the textbook ]

[ Figure 3.3a from the textbook ]

# Let's fill-in the two K-maps

$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

$c_i \backslash x_i y_i$	00	01	11	10
0				
1				

$s_i =$

$c_i \backslash x_i y_i$	00	01	11	10
0				
1				

$c_{i+1} =$

[ Figure 3.3a-b from the textbook ]

# Let's fill-in the two K-maps

$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

$c_i \backslash x_i y_i$	00	01	11	10
0		1		1
1	1		1	

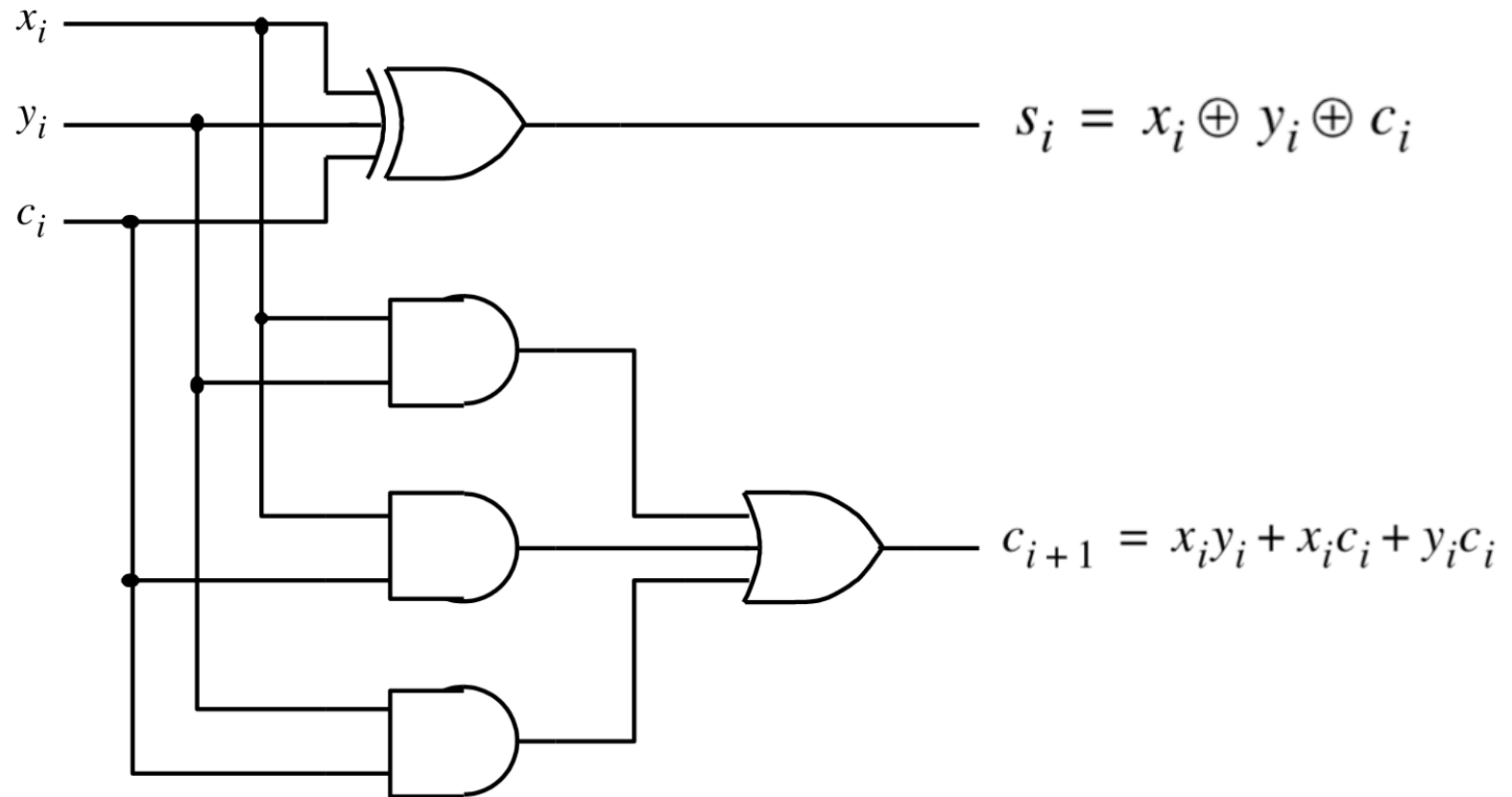
$$s_i = x_i \oplus y_i \oplus c_i$$

$c_i \backslash x_i y_i$	00	01	11	10
0			1	
1		1	1	1

$$c_{i+1} = x_i y_i + x_i c_i + y_i c_i$$

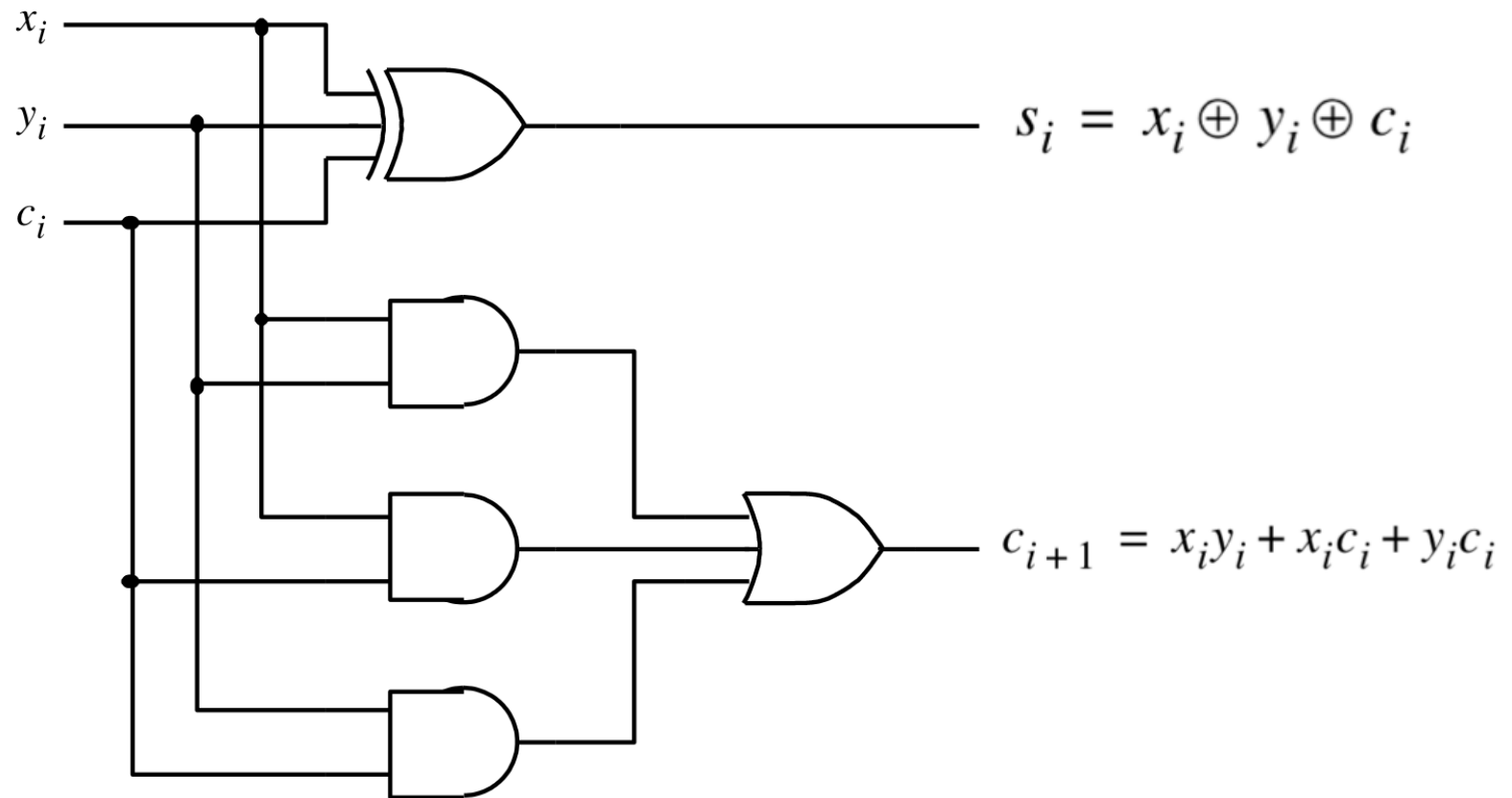
[ Figure 3.3a-b from the textbook ]

# The circuit for the two expressions



[ Figure 3.3c from the textbook ]

# This is called the Full-Adder



[ Figure 3.3c from the textbook ]

# XOR Magic

$$s_i = \bar{x}_i y_i \bar{c}_i + x_i \bar{y}_i \bar{c}_i + \bar{x}_i \bar{y}_i c_i + x_i y_i c_i$$

# XOR Magic

$$s_i = \bar{x}_i y_i \bar{c}_i + x_i \bar{y}_i \bar{c}_i + \bar{x}_i \bar{y}_i c_i + x_i y_i c_i$$

$$s_i = (\bar{x}_i y_i + x_i \bar{y}_i) \bar{c}_i + (\bar{x}_i \bar{y}_i + x_i y_i) c_i$$

$$= (x_i \oplus y_i) \bar{c}_i + \overline{(x_i \oplus y_i)} c_i$$

$$= (x_i \oplus y_i) \oplus c_i$$



# XOR Magic

$$s_i = \bar{x}_i y_i \bar{c}_i + x_i \bar{y}_i \bar{c}_i + \bar{x}_i \bar{y}_i c_i + x_i y_i c_i$$

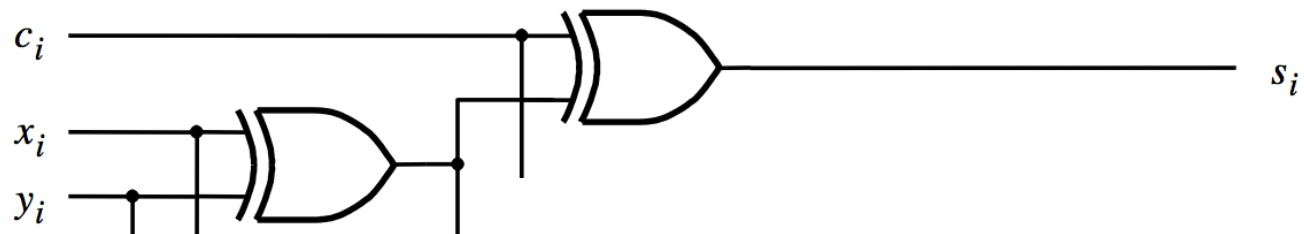
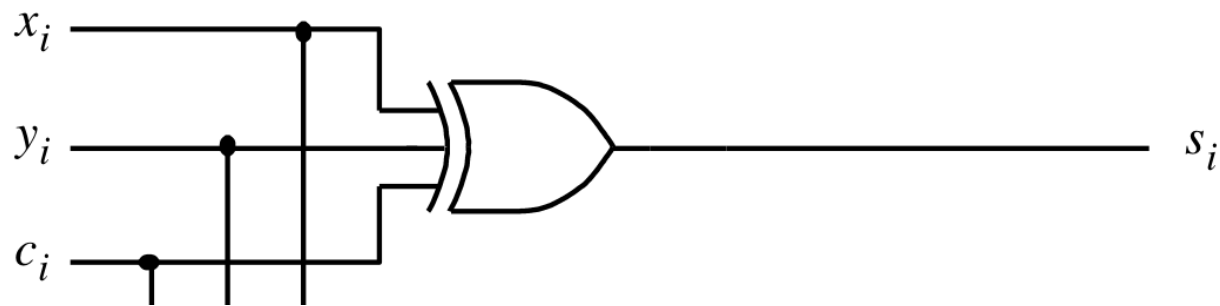
Can you prove this?

$$\begin{aligned} s_i &= (\bar{x}_i y_i + x_i \bar{y}_i) \bar{c}_i + (\bar{x}_i \bar{y}_i + x_i y_i) c_i \\ &= (x_i \oplus y_i) \bar{c}_i + \overline{(x_i \oplus y_i)} c_i \\ &= (x_i \oplus y_i) \oplus c_i \end{aligned}$$

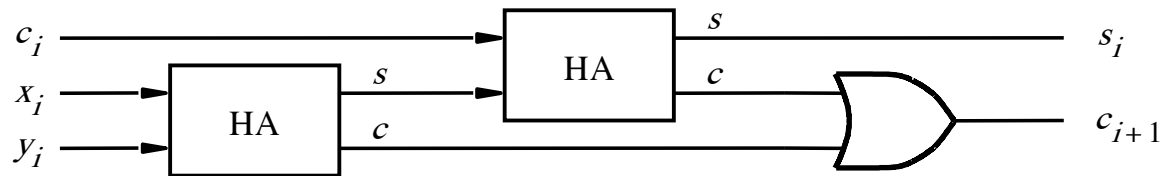
# XOR Magic

( $s_i$  can be implemented in two different ways)

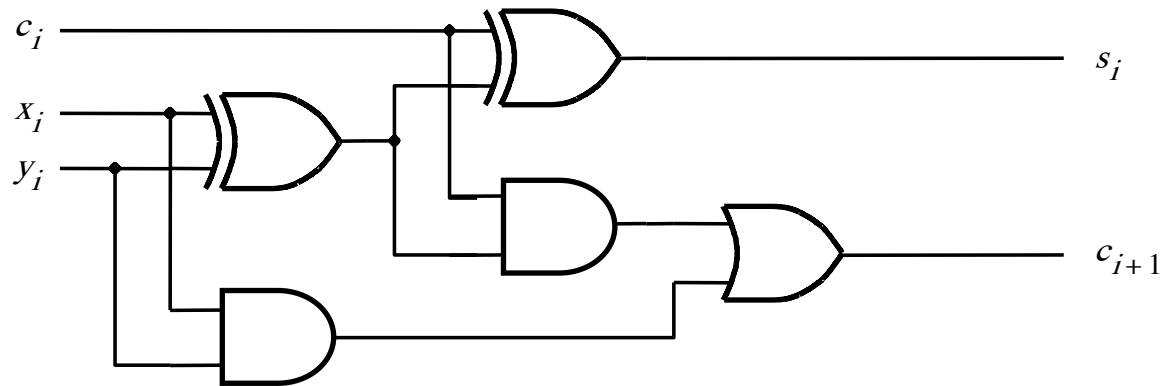
$$s_i = x_i \oplus y_i \oplus c_i$$



# A decomposed implementation of the full-adder circuit



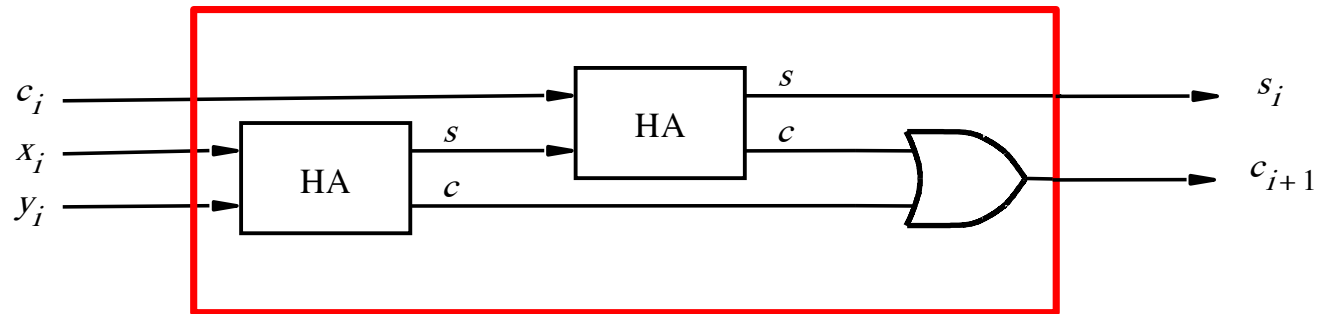
(a) Block diagram



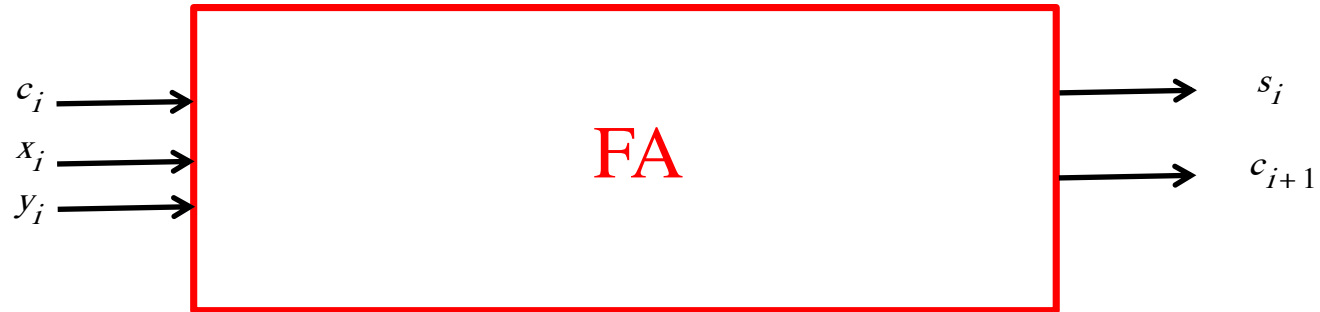
(b) Detailed diagram

[ Figure 3.4 from the textbook ]

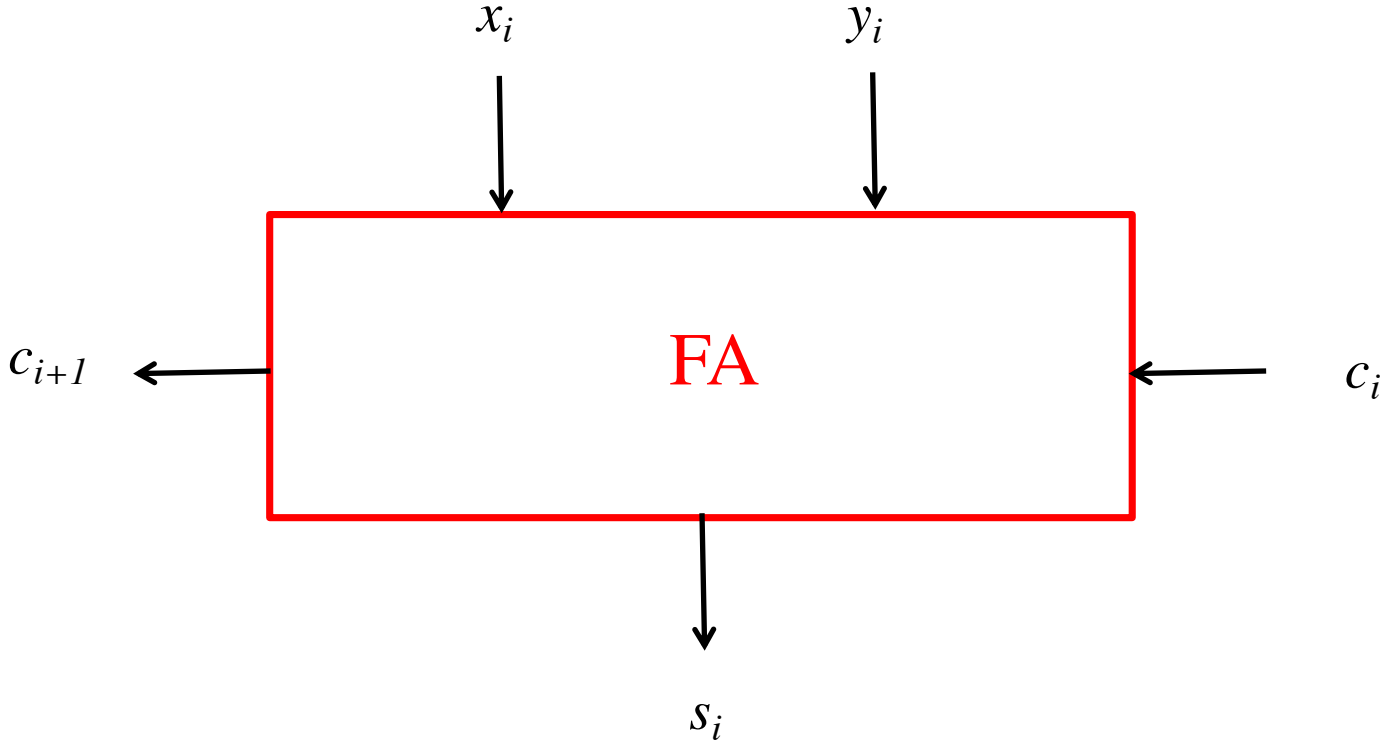
# The Full-Adder Abstraction



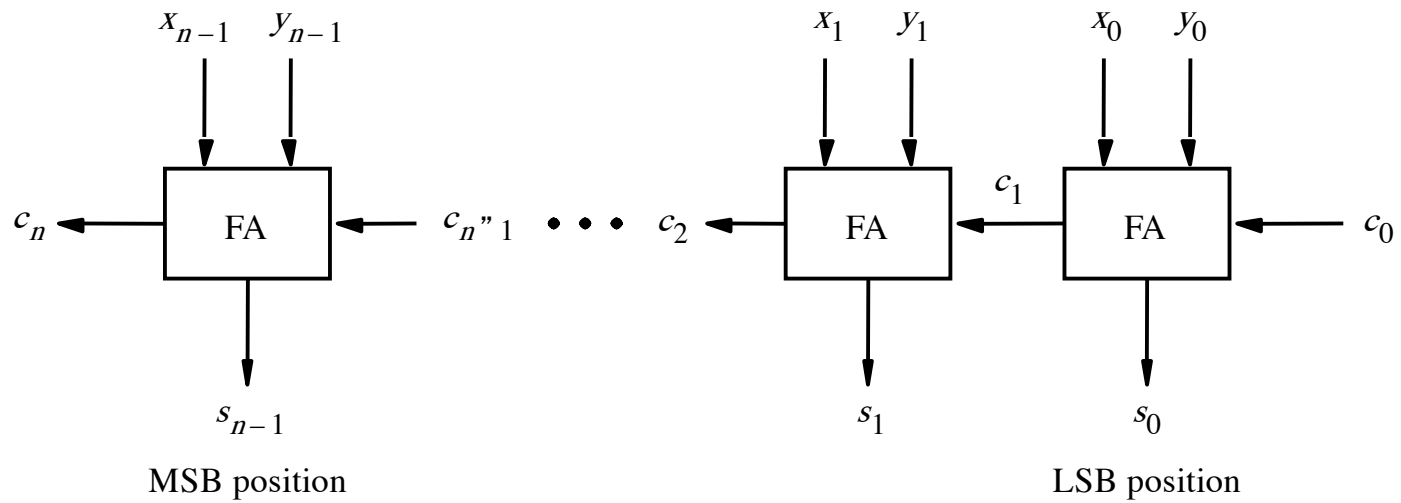
# The Full-Adder Abstraction



**We can place the arrows anywhere**

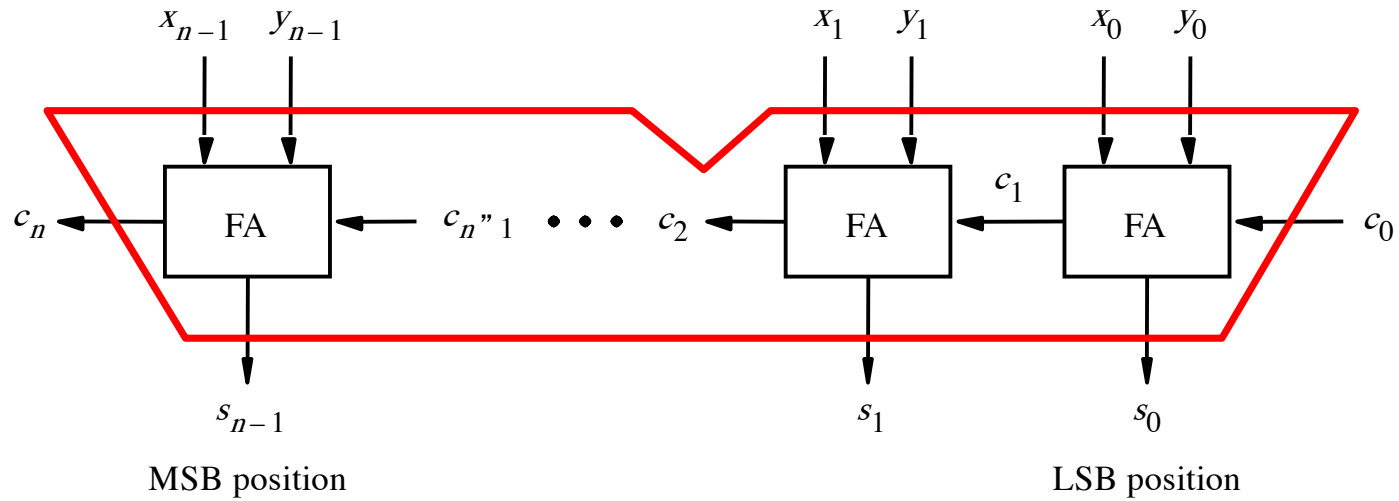


# $n$ -bit ripple-carry adder



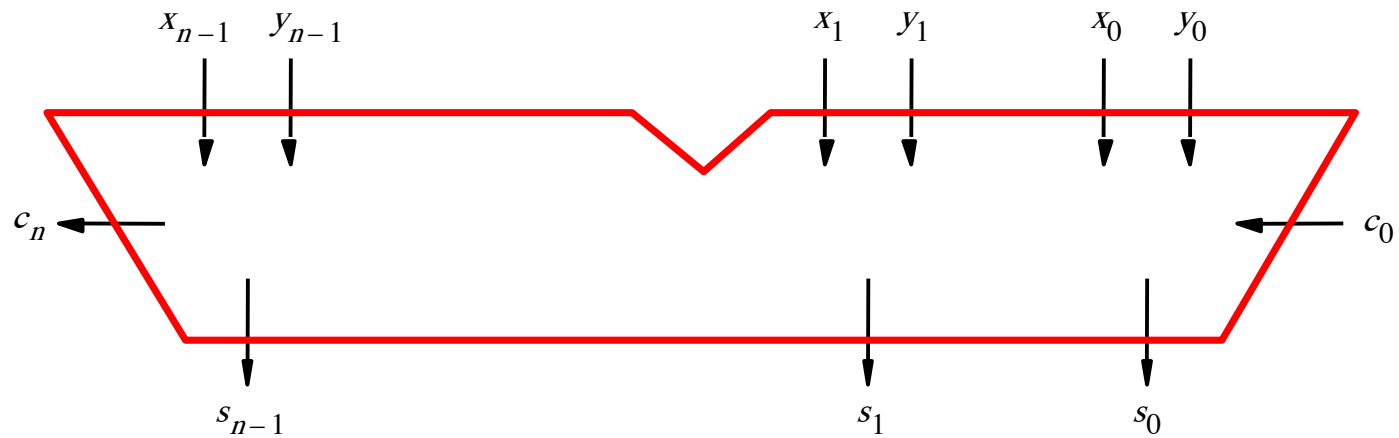
[ Figure 3.5 from the textbook ]

# $n$ -bit ripple-carry adder abstraction





# *n*-bit ripple-carry adder abstraction

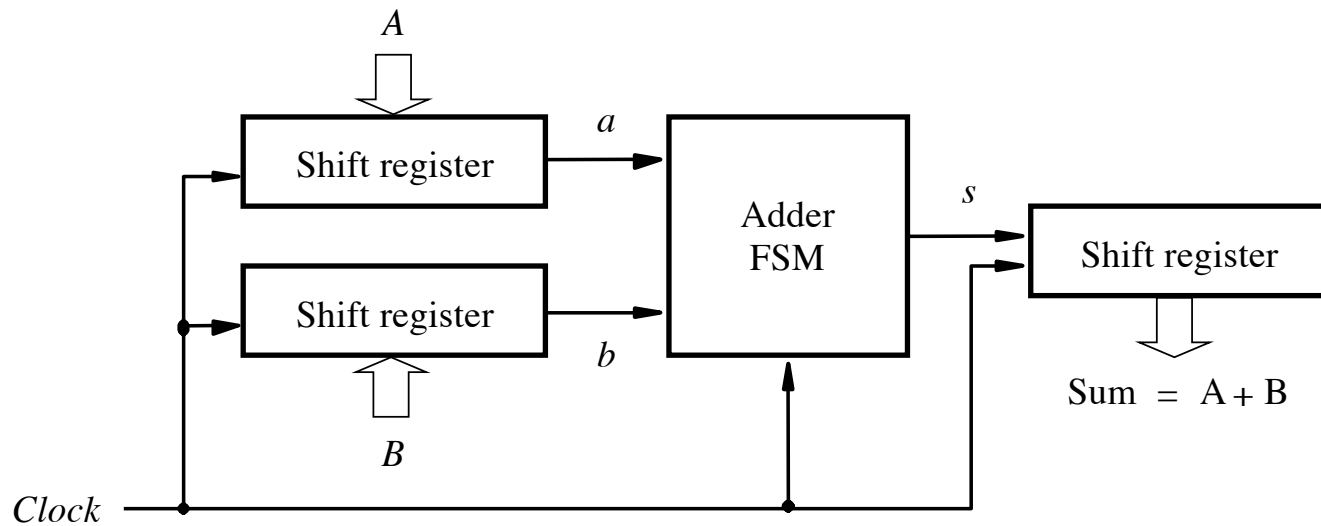




# Serial Adder

- **The n-bit adder requires all bits to be provided at the same time.**
- **In some cases, we may want to add the numbers as the bits come in.**
- **Also, with an n-bit adder we are limited to n-bits. Circuits for larger n are more complex.**
- **Can we add arbitrarily long numbers.**

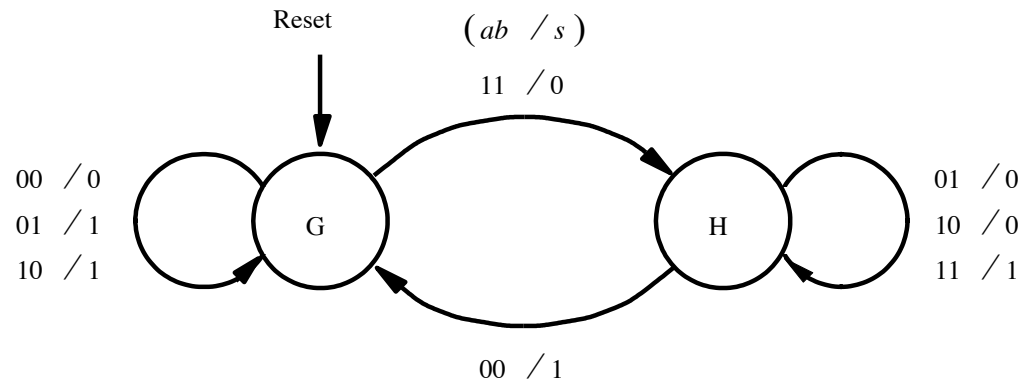
# Block diagram for the serial adder



[ Figure 6.39 from the textbook ]

# **Mealy Machine Implementation**

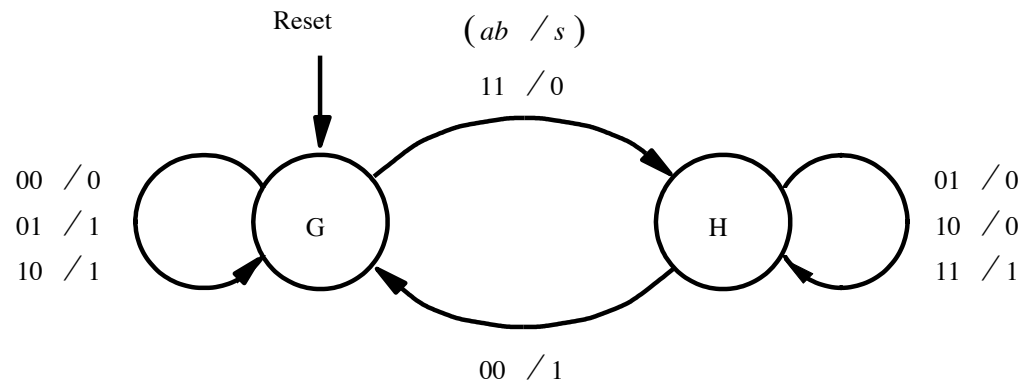
# State diagram for the serial adder FSM



G: carry-in = 0  
H: carry-in = 1

[ Figure 6.40 from the textbook ]

# State diagram for the serial adder FSM

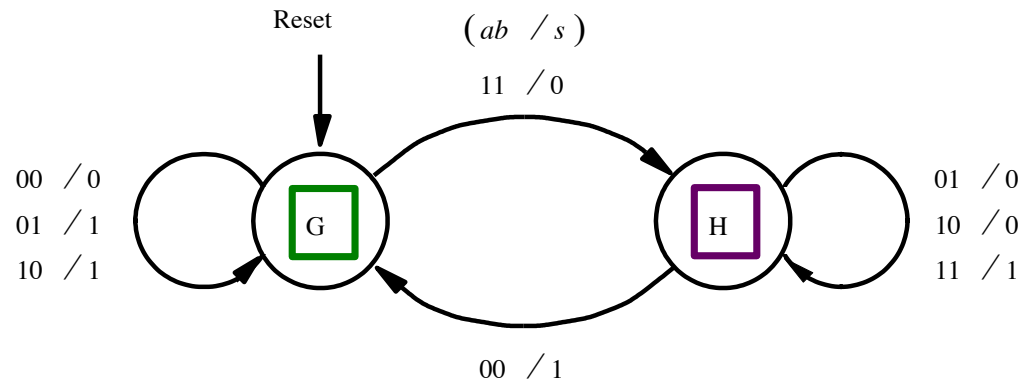


$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

G: carry-in = 0  
 H: carry-in = 1

[ Figure 6.40 from the textbook ]

# State diagram for the serial adder FSM



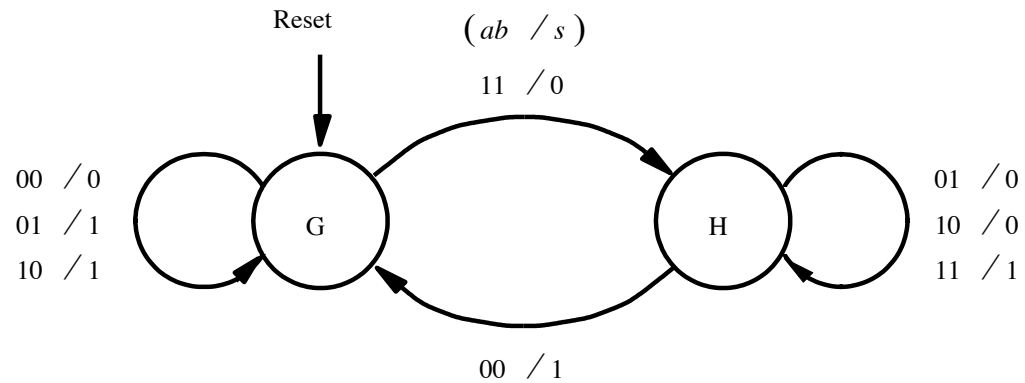
$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

G: carry-in = 0  
H: carry-in = 1

[ Figure 6.40 from the textbook ]



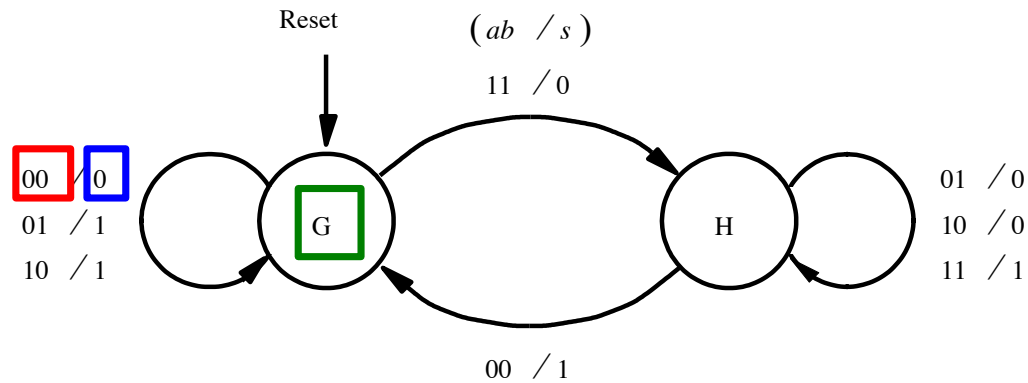
# State diagram for the serial adder FSM



$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

G: carry-in = 0  
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# State diagram for the serial adder FSM

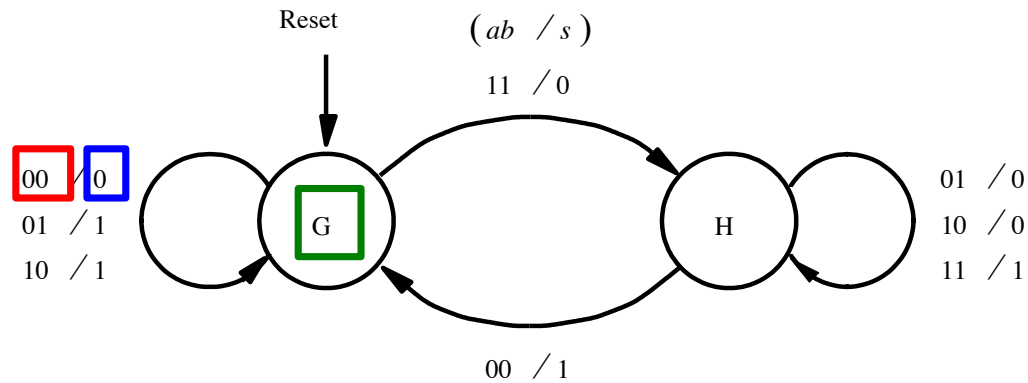


$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

G: carry-in = 0

H: carry-in = 1

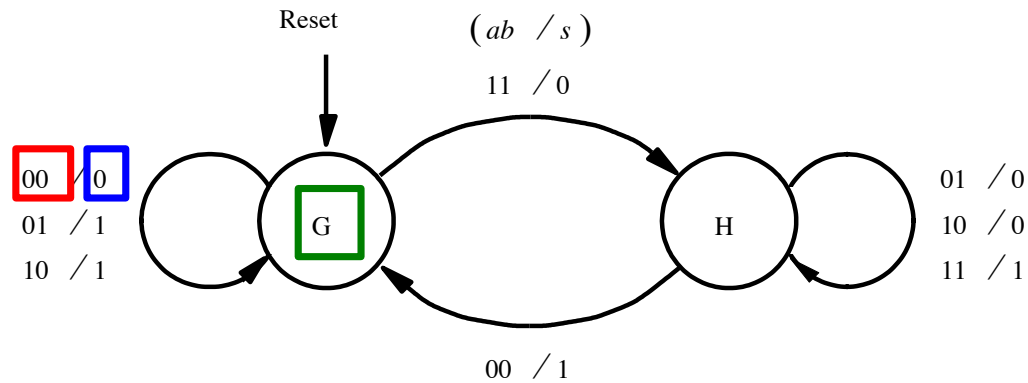
# State diagram for the serial adder FSM



$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

G: carry-in = 0  
H: carry-in = 1

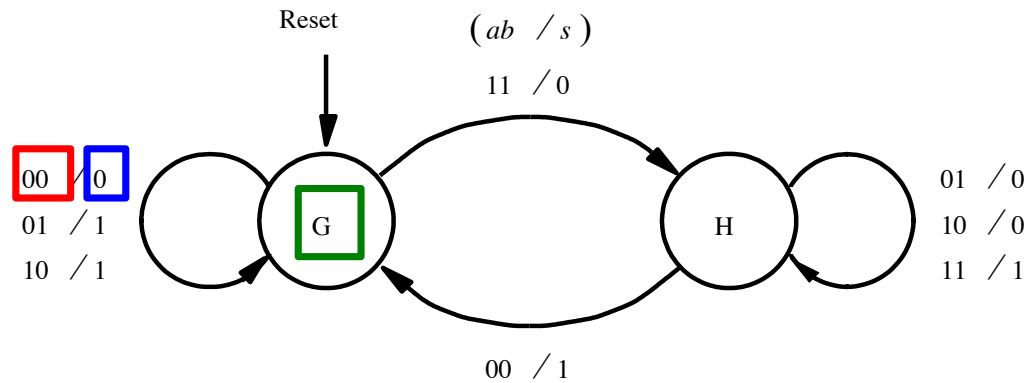
# State diagram for the serial adder FSM



$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
G	0	0	G	0
G	0	1	G	1
G	1	0	G	1
G	1	1	H	0
H	0	0	G	1
H	0	1	H	0
H	1	0	H	0
H	1	1	H	1

G: carry-in = 0  
 H: carry-in = 1

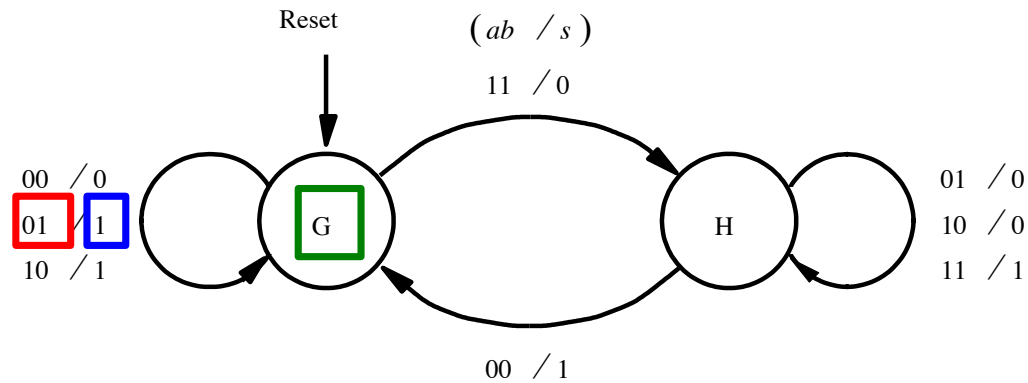
# State diagram for the serial adder FSM



$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
G	0	0	G	0
G	0	1	G	1
G	1	0	G	1
G	1	1	H	0
H	0	0	G	1
H	0	1	H	0
H	1	0	H	0
H	1	1	H	1

G: carry-in = 0  
H: carry-in = 1

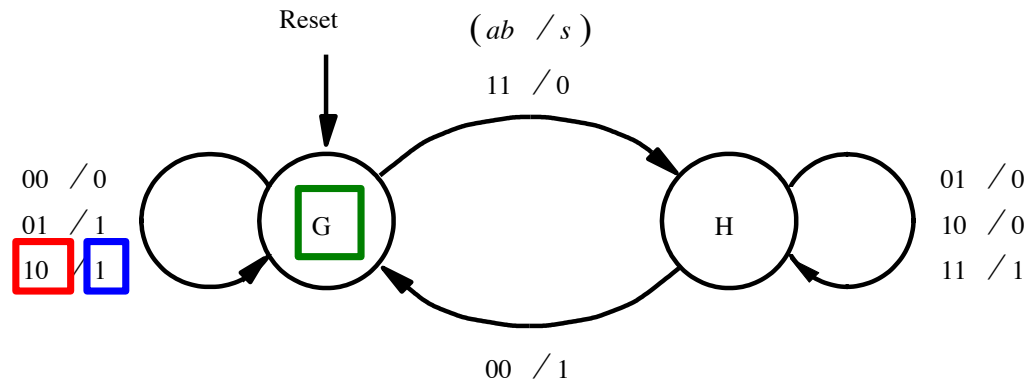
# State diagram for the serial adder FSM



$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
G	0	0	G	0
G	0	1	G	1
G	1	0	G	1
G	1	1	H	0
H	0	0	G	1
H	0	1	H	0
H	1	0	H	0
H	1	1	H	1

G: carry-in = 0  
H: carry-in = 1

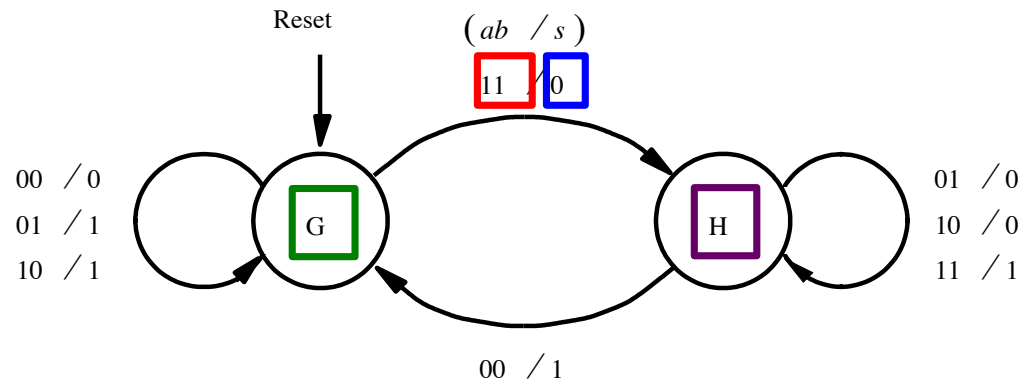
# State diagram for the serial adder FSM



$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
G	0	0	G	0
G	0	1	G	1
G	1	0	G	1
G	1	1	H	0
H	0	0	G	1
H	0	1	H	0
H	1	0	H	0
H	1	1	H	1

G: carry-in = 0  
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# State diagram for the serial adder FSM

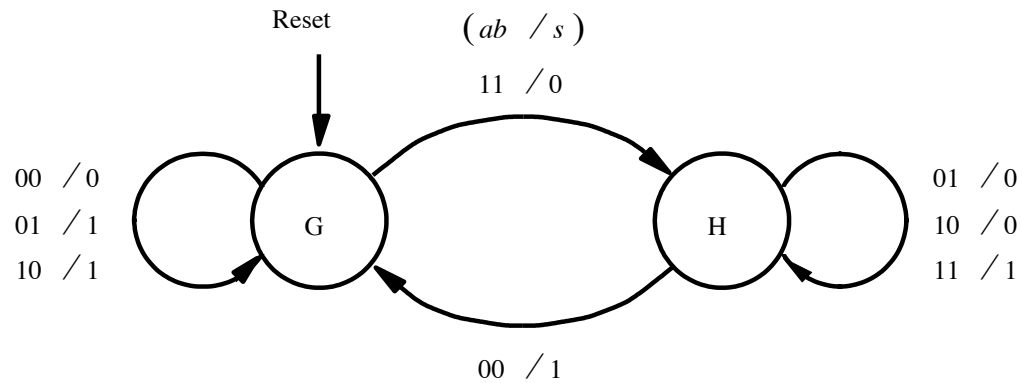


$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
G	0	0	G	0
G	0	1	G	1
G	1	0	G	1
G	1	1	H	0
H	0	0	G	1
H	0	1	H	0
H	1	0	H	0
H	1	1	H	1

G: carry-in = 0  
 H: carry-in = 1



## State diagram for the serial adder FSM

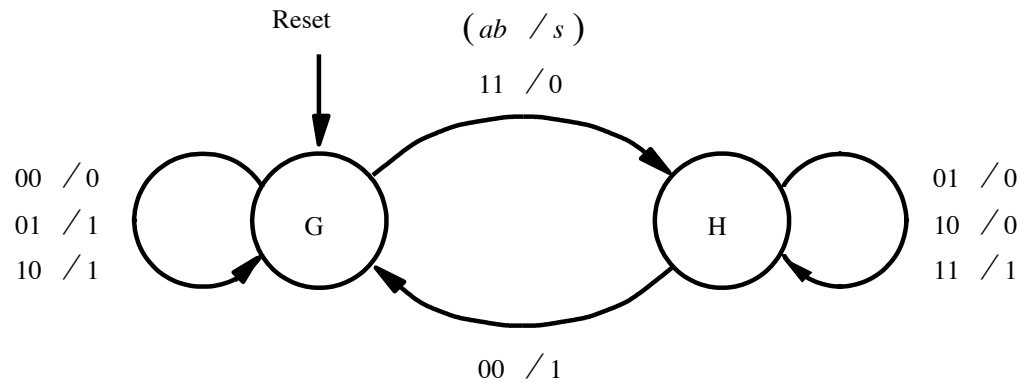


## State table for the serial adder FSM

Present state	Next state				Output $s$			
	$ab = 00$	01	10	11	00	01	10	11
G								
H								

[ Figure 6.40 & 6.41 from the textbook ]

## State diagram for the serial adder FSM

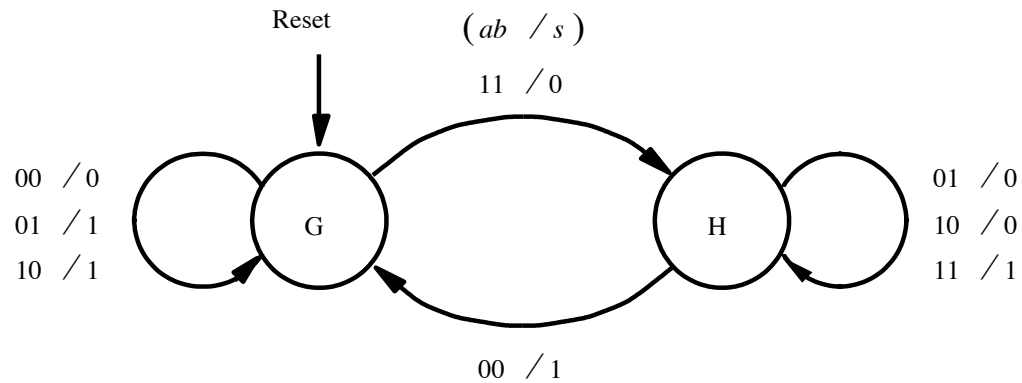


## State table for the serial adder FSM

Present state	Next state				Output $s$			
	$ab = 00$	01	10	11	00	01	10	11
G	G	G	G	H				
H	G	H	H	H				

[ Figure 6.40 & 6.41 from the textbook ]

## State diagram for the serial adder FSM



## State table for the serial adder FSM

Present state	Next state				Output $s$			
	$ab = 00$	01	10	11	00	01	10	11
G	G	G	G	H	0	1	1	0
H	G	H	H	H	1	0	0	1

[ Figure 6.40 & 6.41 from the textbook ]

## State table for the serial adder FSM

Present state	Next state				Output $s$			
	$ab = 00$	01	10	11	00	01	10	11
G	G	G	G	H	0	1	1	0
H	G	H	H	H	1	0	0	1

[ Figure 6.41 from the textbook ]

## State table for the serial adder FSM

Present state	Next state				Output $s$			
	$ab = 00$	01	10	11	00	01	10	11
G	G	G	G	H	0	1	1	0
H	G	H	H	H	1	0	0	1

## State-assigned table for the serial adder

Present state	Next state				Output			
	$ab = 00$	01	10	11	00	01	10	11
$y$	$Y$				$s$			
0								
1								

[ Figure 6.41 & 6.42 from the textbook ]

## State table for the serial adder FSM

Present state	Next state				Output $s$			
	$ab = 00$	01	10	11	00	01	10	11
G	G	G	G	H	0	1	1	0
H	G	H	H	H	1	0	0	1

## State-assigned table for the serial adder

Present state	Next state				Output			
	$ab = 00$	01	10	11	00	01	10	11
$y$	$Y$				$s$			
0	0	0	0	1				
1	0	1	1	1				

[ Figure 6.41 & 6.42 from the textbook ]

## State table for the serial adder FSM

Present state	Next state				Output $s$			
	$ab = 00$	01	10	11	00	01	10	11
G	G	G	G	H	0	1	1	0
H	G	H	H	H	1	0	0	1

## State-assigned table for the serial adder

Present state	Next state				Output			
	$ab = 00$	01	10	11	00	01	10	11
$y$	$Y$				$s$			
0	0	0	0	1	0	1	1	0
1	0	1	1	1	1	0	0	1

[ Figure 6.41 & 6.42 from the textbook ]

# Derivation of Y and s

Present state	Next state				Output			
	$ab = 00$	01	10	11	00	01	10	11
$y$	$Y$				$s$			
0	0	0	0	1	0	1	1	0
1	0	1	1	1	1	0	0	1



# Derivation of Y and s

Present state	Next state				Output			
	$ab=00$	01	10	11	00	01	10	11
$y$	$Y$				$s$			
0	0	0	0	1	0	1	1	0
1	0	1	1	1	1	0	0	1

$y$	$a$	$b$	$Y$	$s$
0	0	0		
0	0	1		
0	1	0		
0	1	1		
1	0	0		
1	0	1		
1	1	0		
1	1	1		

# Derivation of Y and s

Present state	Next state				Output			
	$ab=00$	01	10	11	00	01	10	11
$y$	$Y$				$s$			
0	0	0	0	1	0	1	1	0
1	0	1	1	1	1	0	0	1

$y$	$a$	$b$	$Y$	$s$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

# Derivation of Y and s

Present state	Next state				Output			
	$ab=00$	01	10	11	00	01	10	11
$y$	$Y$				$s$			
0	0	0	0	1	0	1	1	0
1	0	1	1	1	1	0	0	1

$y$	$a$	$b$	$Y$	$s$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

$Y$

$y$	$a$				
$b$		00	01	11	10
0					
1					

$s$

$y$	$a$				
$b$		00	01	11	10
0					
1					

# Derivation of Y and s

Present state	Next state				Output			
	$ab=00$	01	10	11	00	01	10	11
$y$	$Y$				$s$			
0	0	0	0	1	0	1	1	0
1	0	1	1	1	1	0	0	1

$y$	$a$	$b$	$Y$	$s$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

$Y$

$y$	$a$				
$b$		00	01	11	10
0		0	0	1	0
1		0	1	1	1

$s$

$y$	$a$				
$b$		00	01	11	10
0		0	1	0	1
1		1	0	1	0

# Derivation of Y and s

Present state	Next state				Output			
	$ab=00$	01	10	11	00	01	10	11
$y$	$Y$				$s$			
0	0	0	0	1	0	1	1	0
1	0	1	1	1	1	0	0	1

$y$	$a$	$b$	$Y$	$s$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

$Y$

$y$	$a$	00	01	11	10
0	0	0	0	1	0
1	0	1	1	1	1

$s$

$y$	$a$	00	01	11	10
0	0	0	1	0	1
1	1	1	0	1	0

# Derivation of Y and s

Present state	Next state				Output			
	$ab=00$	01	10	11	00	01	10	11
$y$	$Y$				$s$			
0	0	0	0	1	0	1	1	0
1	0	1	1	1	1	0	0	1

$y$	$a$	$b$	$Y$	$s$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

$Y$

$y$	$a$	00	01	11	10
$b$	0	0	0	1	0
1	0	1	1	1	1

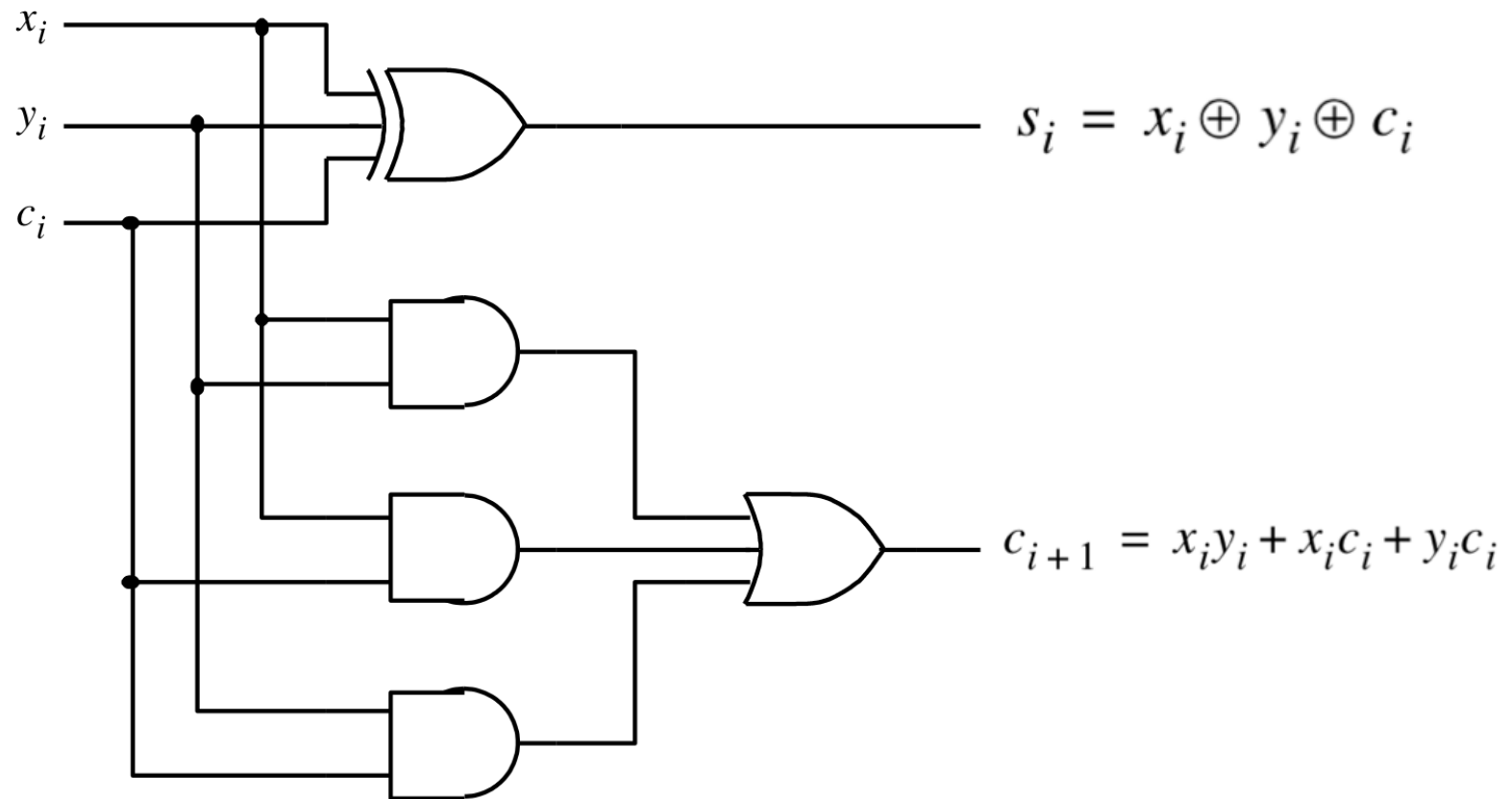
$s$

$y$	$a$	00	01	11	10
$b$	0	0	1	0	1
1	1	1	0	1	0

$$Y = ab + ay + by$$

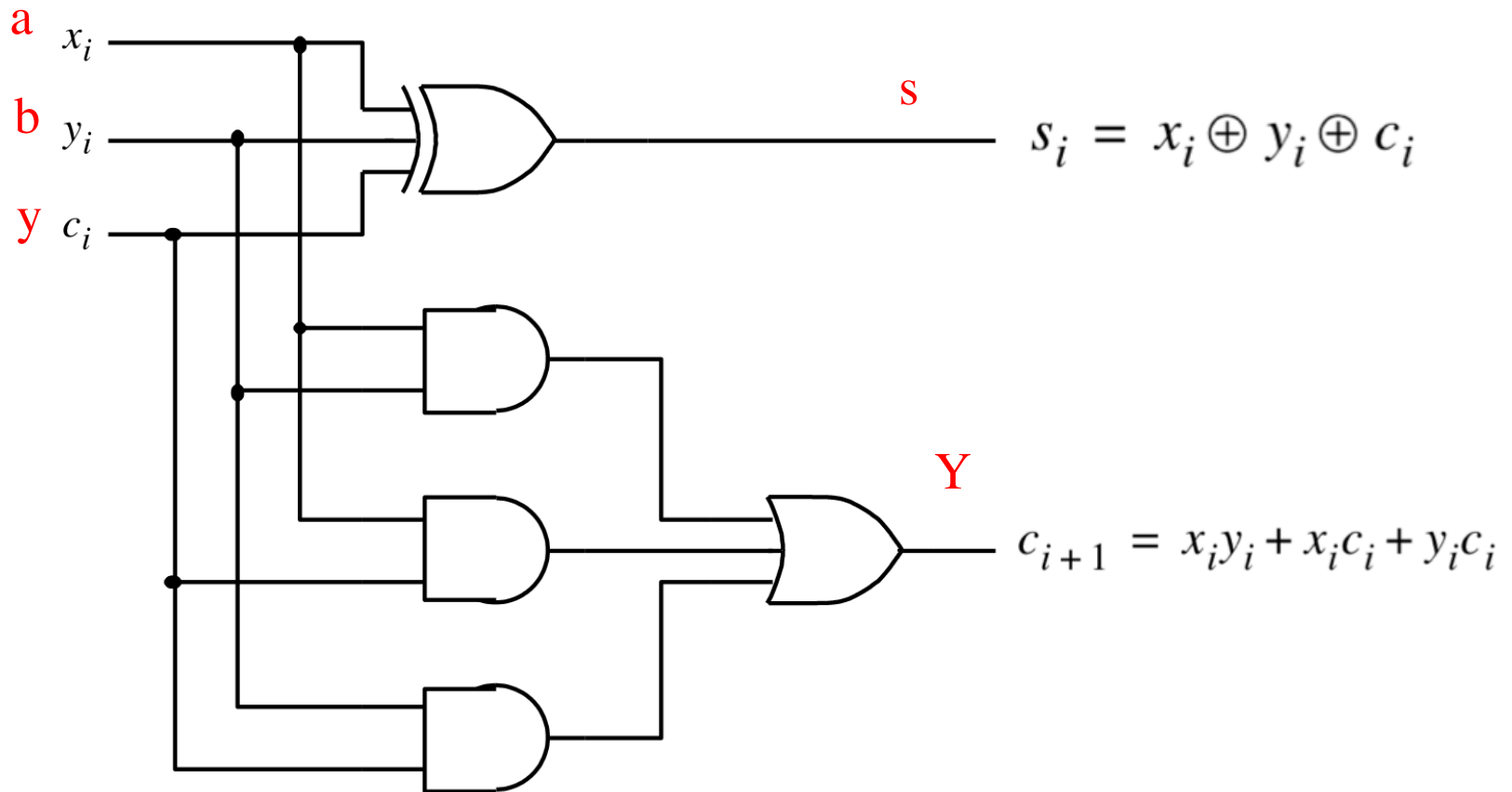
$$s = \text{XOR}(\text{XOR}(a, b), y)$$

# The circuit for the two expressions



[ Figure 3.3c from the textbook ]

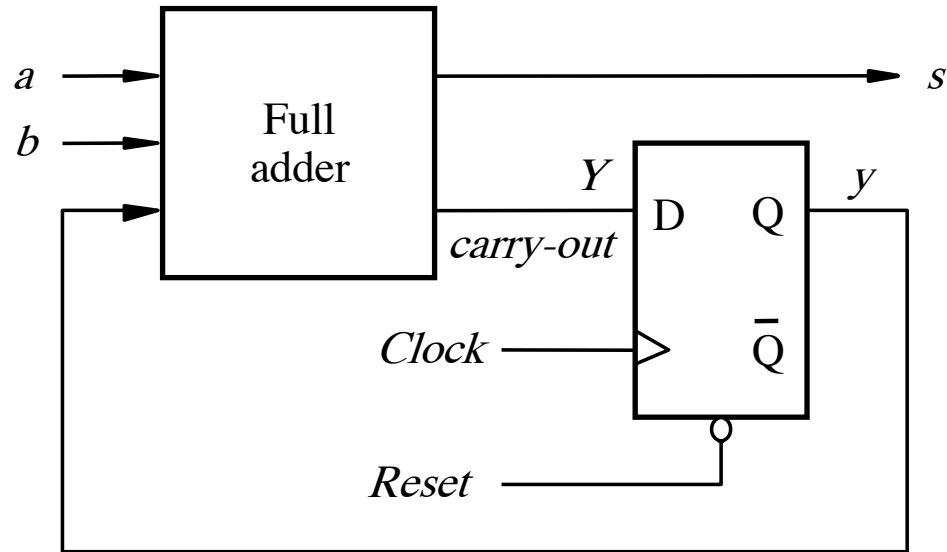
# The circuit for the two expressions



[ Figure 3.3c from the textbook ]



# Circuit for the serial adder FSM



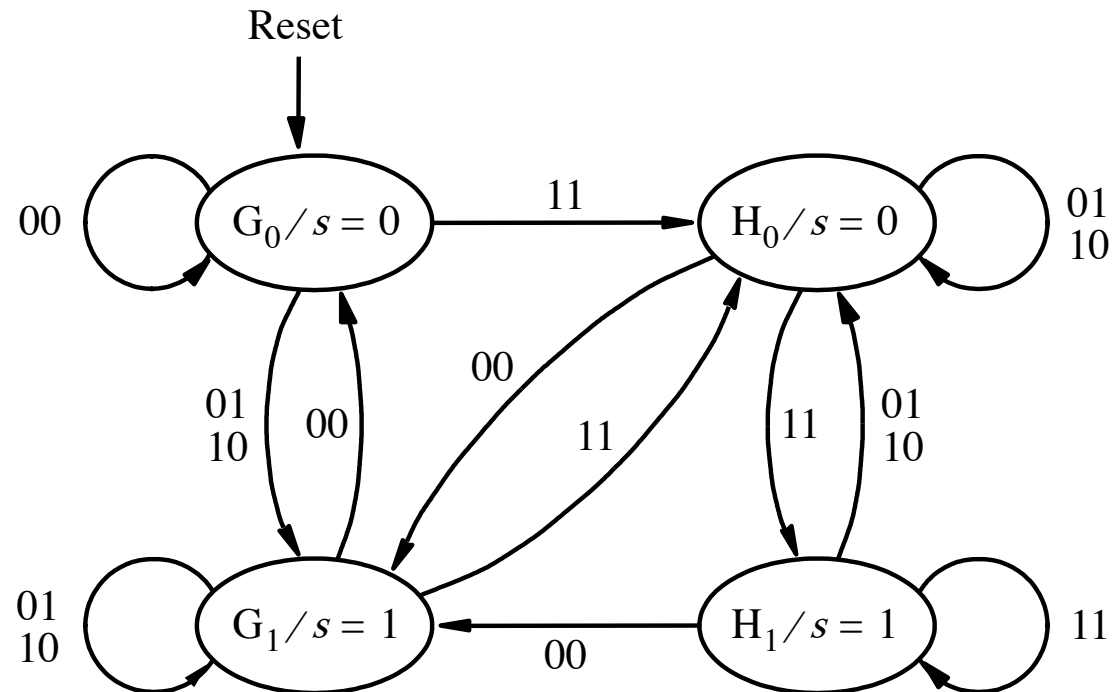
$$Y = ab + ay + by \quad \text{(carry bit from FA)}$$

$$s = \text{XOR}(\text{XOR}(a, b), y) \quad \text{(sum bit from FA)}$$

[ Figure 6.43 from the textbook ]

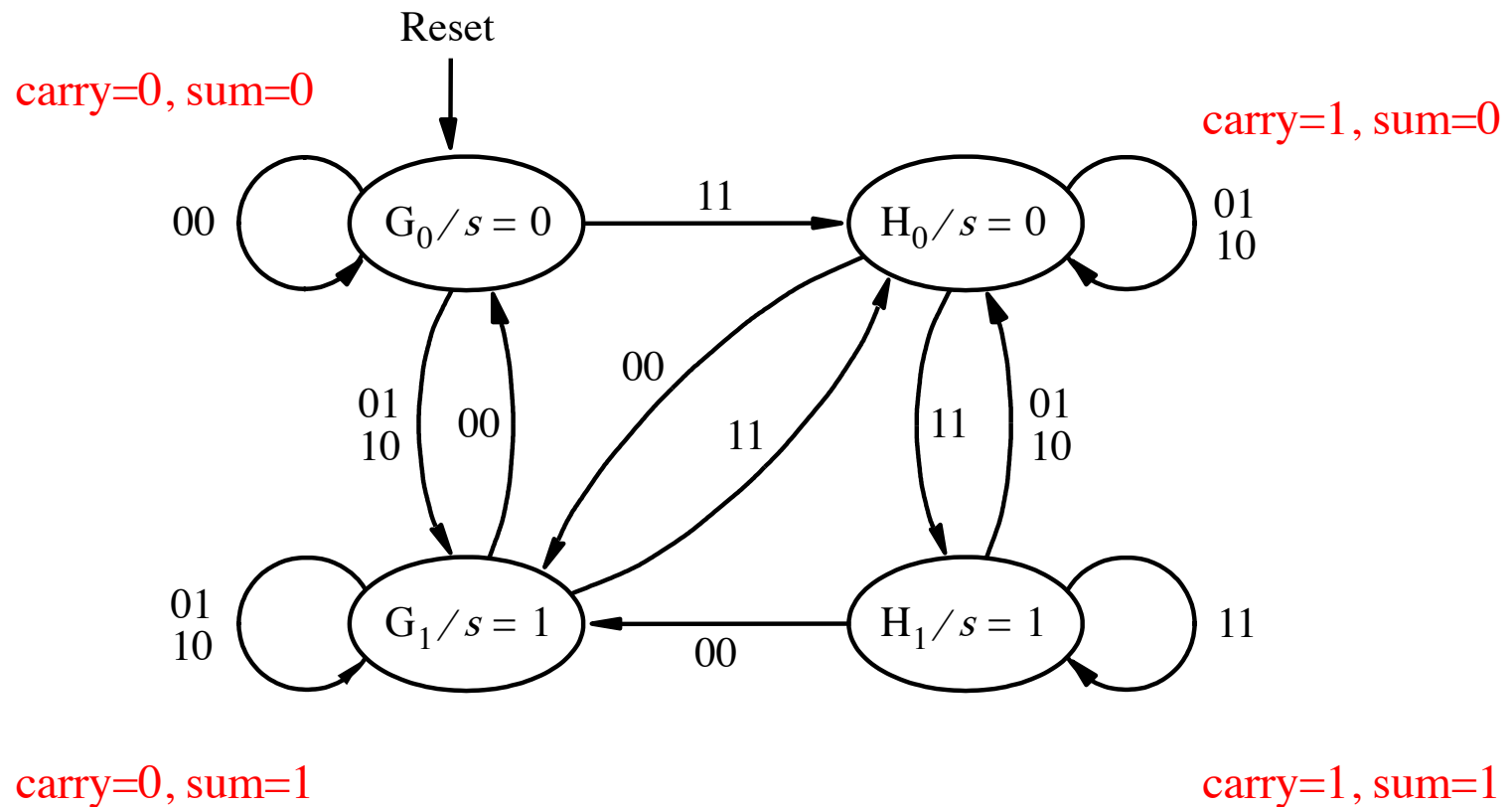
# **Moore Machine Implementation**

# State diagram for the Moore-type serial adder FSM



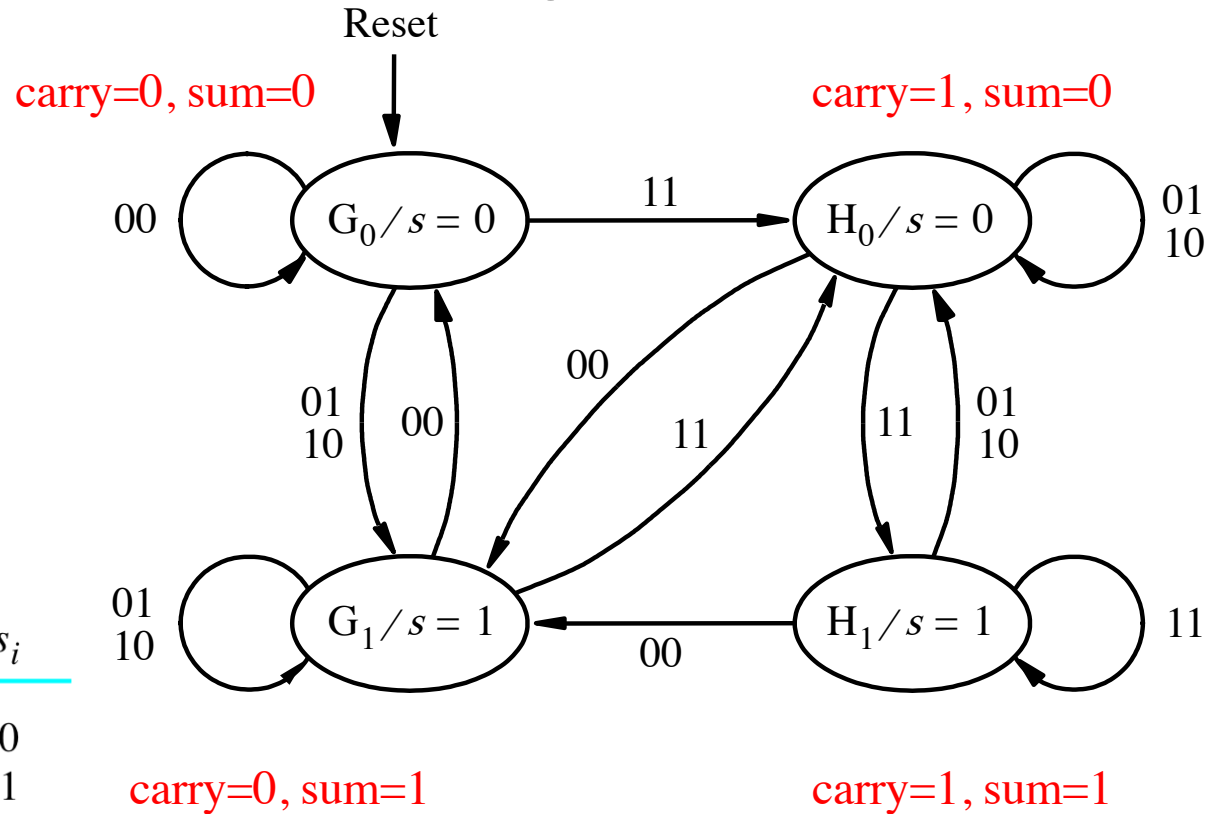
[ Figure 6.44 from the textbook ]

# State diagram for the Moore-type serial adder FSM



[ Figure 6.44 from the textbook ]

# State diagram for the Moore-type serial adder FSM

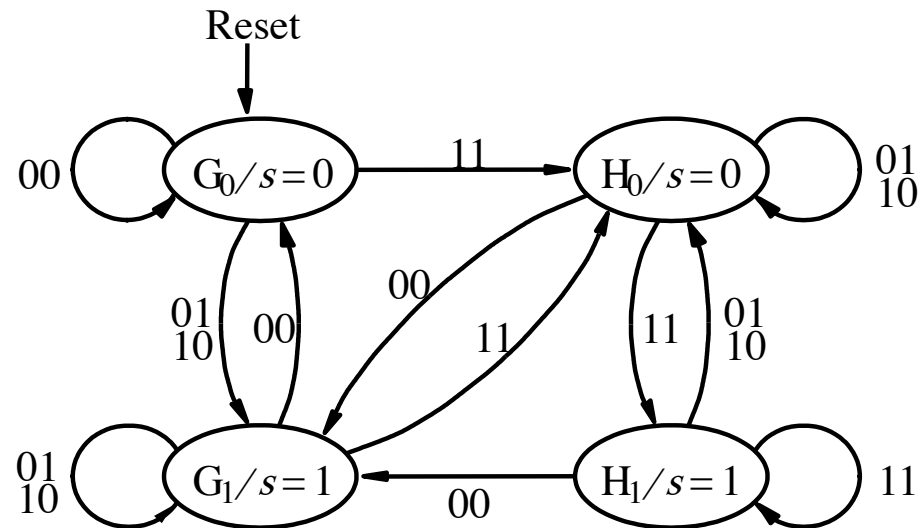


$c_i$	$x_i$	$y_i$	$c_{i+1}$	$s_i$
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

[ Figure 6.44 from the textbook ]

## State table for the Moore-type serial adder FSM

Present state	Next state				Output $s$
	$ab = 00$	01	10	11	
$G_0$	$G_0$	$G_1$	$G_1$	$H_0$	0
$G_1$	$G_0$	$G_1$	$G_1$	$H_0$	1
$H_0$	$G_1$	$H_0$	$H_0$	$H_1$	0
$H_1$	$G_1$	$H_0$	$H_0$	$H_1$	1



[ Figure 6.45 from the textbook ]

## State table for the Moore-type serial adder FSM

Present state	Next state				Output $s$
	$ab = 00$	01	10	11	
$G_0$	$G_0$	$G_1$	$G_1$	$H_0$	0
$G_1$	$G_0$	$G_1$	$G_1$	$H_0$	1
$H_0$	$G_1$	$H_0$	$H_0$	$H_1$	0
$H_1$	$G_1$	$H_0$	$H_0$	$H_1$	1

[ Figure 6.45 from the textbook ]

## State table for the Moore-type serial adder FSM

Present state	Next state				Output $s$
	$ab = 00$	01	10	11	
$G_0$	$G_0$	$G_1$	$G_1$	$H_0$	0
$G_1$	$G_0$	$G_1$	$G_1$	$H_0$	1
$H_0$	$G_1$	$H_0$	$H_0$	$H_1$	0
$H_1$	$G_1$	$H_0$	$H_0$	$H_1$	1

Present state $y_2y_1$	Next state				Output $s$
	$ab = 00$	01	10	11	
	$Y_2Y_1$				
00					
01					
10					
11					

[ Figure 6.45 & 6.46 from the textbook ]



## State table for the Moore-type serial adder FSM

Present state	Next state				Output $s$
	$ab = 00$	01	10	11	
$G_0$	$G_0$	$G_1$	$G_1$	$H_0$	0
$G_1$	$G_0$	$G_1$	$G_1$	$H_0$	1
$H_0$	$G_1$	$H_0$	$H_0$	$H_1$	0
$H_1$	$G_1$	$H_0$	$H_0$	$H_1$	1

Present state $y_2y_1$	Next state				Output $s$
	$ab = 00$	01	10	11	
	$Y_2Y_1$				
00	00	01	01	10	0
01	00	01	01	10	1
10	01	10	10	11	0
11	01	10	10	11	1

[ Figure 6.45 & 6.46 from the textbook ]

# State-assigned table for the Moore-type serial adder FSM

Present state $y_2y_1$	Next state				Output $s$
	$ab = 00$	01	10	11	
	$Y_2Y_1$				
00	00	01	01	10	0
01	00	01	01	10	1
10	01	10	10	11	0
11	01	10	10	11	1

[ Figure 6.46 from the textbook ]

# Deriving Y1, Y2, and s

Present state $y_2y_1$	Next state				Output $s$
	$ab = 00$	01	10	11	
	$Y_2Y_1$				
00	00	01	01	10	0
01	00	01	01	10	1
10	01	10	10	11	0
11	01	10	10	11	1

$y_2$	$y_1$	$a$	$b$	$Y_1$	$Y_2$
0	0	0	0		
0	0	0	1		
0	0	1	0		
0	0	1	1		
0	1	0	0		
0	1	0	1		
0	1	1	0		
0	1	1	1		
1	0	0	0		
1	0	0	1		
1	0	1	0		
1	0	1	1		
1	1	0	0		
1	1	0	1		
1	1	1	0		
1	1	1	1		

# Deriving $Y_1$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_1$				
00	0	1	1	0	0
01	0	1	1	0	1
10	1	0	0	1	0
11	1	0	0	1	1

$y_2$	$y_1$	$a$	$b$	$Y_1$	$Y_2$
0	0	0	0		
0	0	0	1		
0	0	1	0		
0	0	1	1		
0	1	0	0		
0	1	0	1		
0	1	1	0		
0	1	1	1		
1	0	0	0		
1	0	0	1		
1	0	1	0		
1	0	1	1		
1	1	0	0		
1	1	0	1		
1	1	1	0		
1	1	1	1		

# Deriving $Y_1$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_1$				
00	0	1	1	0	0
01	0	1	1	0	1
10	1	0	0	1	0
11	1	0	0	1	1

$y_2$	$y_1$	$a$	$b$	$Y_1$	$Y_2$
0	0	0	0	0	
0	0	0	1	1	
0	0	1	0	1	
0	0	1	1	0	
0	1	0	0	0	
0	1	0	1	1	
0	1	1	0	1	
0	1	1	1	0	
1	0	0	0	1	
1	0	0	1	0	
1	0	1	0	0	
1	0	1	1	1	
1	1	0	0	1	
1	1	0	1	0	
1	1	1	0	0	
1	1	1	1	1	

# Deriving $Y_1$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_1$				
00	0	1	1	0	0
01	0	1	1	0	1
10	1	0	0	1	0
11	1	0	0	1	1

	$y_2y_1$			
$ab$	00	01	11	10
00				
01				
11				
10				

$y_2$	$y_1$	$a$	$b$	$Y_1$	$Y_2$
0	0	0	0	0	
0	0	0	1	1	
0	0	1	0	1	
0	0	1	1	0	
0	1	0	0	0	
0	1	0	1	1	
0	1	1	0	1	
0	1	1	1	0	
1	0	0	0	1	
1	0	0	1	0	
1	0	1	0	0	
1	0	1	1	1	
1	1	0	0	1	
1	1	0	1	0	
1	1	1	0	0	
1	1	1	1	1	

# Deriving $Y_1$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_1$				
00	0	1	1	0	0
01	0	1	1	0	1
10	1	0	0	1	0
11	1	0	0	1	1

		$y_2y_1$			
		00	01	11	10
$ab$	00	0	0	1	1
	01	1	1	0	0
	11	0	0	1	1
	10	1	1	0	0

$y_2$	$y_1$	$a$	$b$	$Y_1$	$Y_2$
0	0	0	0	0	
0	0	0	1	1	
0	0	1	0	1	
0	0	1	1	0	
0	1	0	0	0	
0	1	0	1	1	
0	1	1	0	1	
0	1	1	1	0	
1	0	0	0	1	
1	0	0	1	0	
1	0	1	0	0	
1	0	1	1	1	
1	1	0	0	1	
1	1	0	1	0	
1	1	1	0	0	
1	1	1	1	1	

# Deriving $Y_1$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_1$				
00	0	1	1	0	0
01	0	1	1	0	1
10	1	0	0	1	0
11	1	0	0	1	1

$a b$		$y_2y_1$			
		00	01	11	10
$y_2y_1$	00	0	0	1	1
	01	1	1	0	0
	11	0	0	1	1
	10	1	1	0	0

$$Y_1 = a \oplus b \oplus y_2$$

$y_2$	$y_1$	$a$	$b$	$Y_1$	$Y_2$
0	0	0	0	0	
0	0	0	1	1	
0	0	1	0	1	
0	0	1	1	0	
0	1	0	0	0	
0	1	0	1	1	
0	1	1	0	1	
0	1	1	1	0	
1	0	0	0	1	
1	0	0	1	0	
1	0	1	0	0	
1	0	1	1	1	
1	1	0	0	1	
1	1	0	1	0	
1	1	1	0	0	
1	1	1	1	1	



# Deriving $Y_2$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_2$ <input type="checkbox"/>				
00	0 <input type="checkbox"/>	0 <input type="checkbox"/>	0 <input type="checkbox"/>	1 <input type="checkbox"/>	0
01	0 <input type="checkbox"/>	0 <input type="checkbox"/>	0 <input type="checkbox"/>	1 <input type="checkbox"/>	1
10	0 <input type="checkbox"/>	1 <input type="checkbox"/>	1 <input type="checkbox"/>	1 <input type="checkbox"/>	0
11	0 <input type="checkbox"/>	1 <input type="checkbox"/>	1 <input type="checkbox"/>	1 <input type="checkbox"/>	1

$y_2$	$y_1$	$a$	$b$	$Y_1$	$Y_2$
0	0	0	0	0	
0	0	0	1	1	
0	0	1	0	1	
0	0	1	1	0	
0	1	0	0	0	
0	1	0	1	1	
0	1	1	0	1	
0	1	1	1	0	
1	0	0	0	1	
1	0	0	1	0	
1	0	1	0	0	
1	0	1	1	1	
1	1	0	0	1	
1	1	0	1	0	
1	1	1	0	0	
1	1	1	1	1	

# Deriving $Y_2$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_2$ <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>				
00	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0
01	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1
10	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0
11	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1

$y_2$	$y_1$	$a$	$b$	$Y_1$	$Y_2$
0	0	0	0	0	0
0	0	0	1	1	0
0	0	1	0	1	0
0	0	1	1	0	1
0	1	0	0	0	0
0	1	0	1	1	0
0	1	1	0	1	0
0	1	1	1	0	1
1	0	0	0	1	0
1	0	0	1	0	1
1	0	1	0	0	1
1	0	1	1	1	1
1	1	0	0	1	0
1	1	0	1	0	1
1	1	1	0	0	1
1	1	1	1	1	1

# Deriving $Y_2$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_2$ <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>				
00	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0
01	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1
10	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0
11	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1

		$y_2y_1$			
	$ab$				
		00	01	11	10
00					
01					
11					
10					

$y_2$	$y_1$	$a$	$b$	$Y_1$	$Y_2$
0	0	0	0	0	0
0	0	0	1	1	0
0	0	1	0	1	0
0	0	1	1	0	1
0	1	0	0	0	0
0	1	0	1	1	0
0	1	1	0	1	0
0	1	1	1	0	1
1	0	0	0	1	0
1	0	0	1	0	1
1	0	1	0	0	1
1	0	1	1	1	1
1	1	0	0	1	0
1	1	0	1	0	1
1	1	1	0	0	1
1	1	1	1	1	1

# Deriving $Y_2$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_2$ <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>				
00	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0
01	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1
10	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0
11	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1

		$y_2y_1$			
		00	01	11	10
$ab$	00	0	0	0	0
	01	0	0	1	1
	11	1	1	1	1
	10	0	0	1	1

$y_2$	$y_1$	$a$	$b$	$Y_1$	$Y_2$
0	0	0	0	0	0
0	0	0	1	1	0
0	0	1	0	1	0
0	0	1	1	0	1
0	1	0	0	0	0
0	1	0	1	1	0
0	1	1	0	1	0
0	1	1	1	0	1
1	0	0	0	1	0
1	0	0	1	0	1
1	0	1	0	0	1
1	0	1	1	1	1
1	1	0	0	1	0
1	1	0	1	0	1
1	1	1	0	0	1
1	1	1	1	1	1

# Deriving $Y_2$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_2$ <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>				
00	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0
01	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1
10	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0
11	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1

		$y_2y_1$			
$ab$		00	01	11	10
	00		0	0	0
01		0	0	1	1
11		1	1	1	1
10		0	0	1	1

$y_2$	$y_1$	$a$	$b$	$Y_1$	$Y_2$
0	0	0	0	0	0
0	0	0	1	1	0
0	0	1	0	1	0
0	0	1	1	0	1
0	1	0	0	0	0
0	1	0	1	1	0
0	1	1	0	1	0
0	1	1	1	0	1
1	0	0	0	1	0
1	0	0	1	0	1
1	0	1	0	0	1
1	0	1	1	1	1
1	1	0	0	1	0
1	1	0	1	0	1
1	1	1	0	0	1
1	1	1	1	1	1

# Deriving $Y_2$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_2$ <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>				
00	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0
01	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1
10	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	0
11	0 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1 <span style="border: 1px solid black; display: inline-block; width: 1em; height: 1em; vertical-align: middle;"></span>	1

		$y_2y_1$			
		00	01	11	10
$ab$	00	0	0	0	0
	01	0	0	1	1
	11	1	1	1	1
	10	0	0	1	1

$$Y_2 = ab + ay_2 + by_2$$

$y_2$	$y_1$	$a$	$b$	$Y_1$	$Y_2$
0	0	0	0	0	0
0	0	0	1	1	0
0	0	1	0	1	0
0	0	1	1	0	1
0	1	0	0	0	0
0	1	0	1	1	0
0	1	1	0	1	0
0	1	1	1	0	1
1	0	0	0	1	0
1	0	0	1	0	1
1	0	1	0	0	1
1	0	1	1	1	1
1	1	0	0	1	0
1	1	0	1	0	1
1	1	1	0	0	1
1	1	1	1	1	1

# Deriving $s$

Present state $y_2y_1$	Next state				Output $s$
	$ab = 00$	01	10	11	
	$Y_2Y_1$				
00	00	01	01	10	0
01	00	01	01	10	1
10	01	10	10	11	0
11	01	10	10	11	1

$y_2$	$y_1$	$s$
0	0	
0	1	
1	0	
1	1	

# Deriving $s$

Present state $y_2y_1$	Next state				Output $s$
	$ab = 00$	01	10	11	
	$Y_2Y_1$				
00	00	01	01	10	0
01	00	01	01	10	1
10	01	10	10	11	0
11	01	10	10	11	1

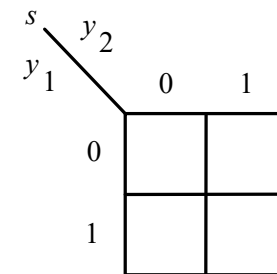
$y_2$	$y_1$	$s$
0	0	0
0	1	1
1	0	0
1	1	1



# Deriving $s$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_2Y_1$				
00	00	01	01	10	0
01	00	01	01	10	1
10	01	10	10	11	0
11	01	10	10	11	1

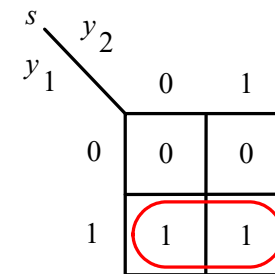
$y_2$	$y_1$	$s$
0	0	0
0	1	1
1	0	0
1	1	1



# Deriving $s$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_2Y_1$				
00	00	01	01	10	0
01	00	01	01	10	1
10	01	10	10	11	0
11	01	10	10	11	1

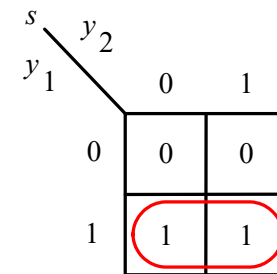
$y_2$	$y_1$	$s$
0	0	0
0	1	1
1	0	0
1	1	1



# Deriving $s$

Present state $y_2y_1$	Next state				Output $s$
	$ab=00$	01	10	11	
	$Y_2Y_1$				
00	00	01	01	10	0
01	00	01	01	10	1
10	01	10	10	11	0
11	01	10	10	11	1

$y_2$	$y_1$	$s$
0	0	0
0	1	1
1	0	0
1	1	1



$$s = y_1$$

# State-assigned table for the Moore-type serial adder FSM

Present state $y_2y_1$	Next state				Output $s$
	$ab = 00$	01	10	11	
	$Y_2Y_1$				
00	00	01	01	10	0
01	00	01	01	10	1
10	01	10	10	11	0
11	01	10	10	11	1

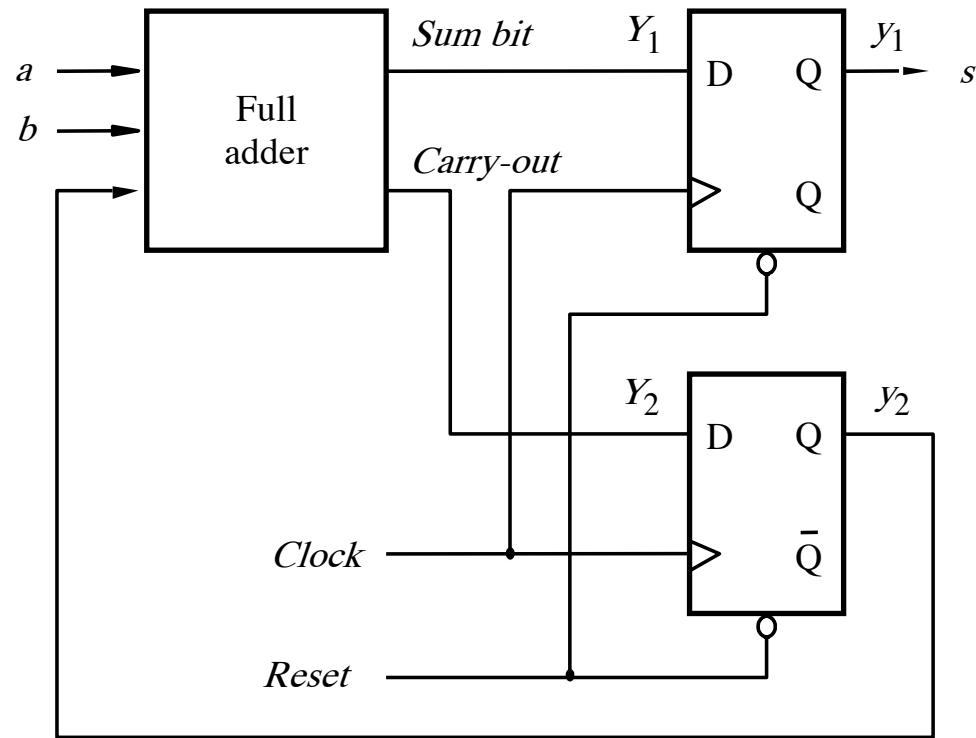
$$Y_1 = a \oplus b \oplus y_2$$

$$Y_2 = ab + ay_2 + by_2$$

$$s = y_1$$

[ Figure 6.46 from the textbook ]

# Circuit for the Moore-type serial adder FSM



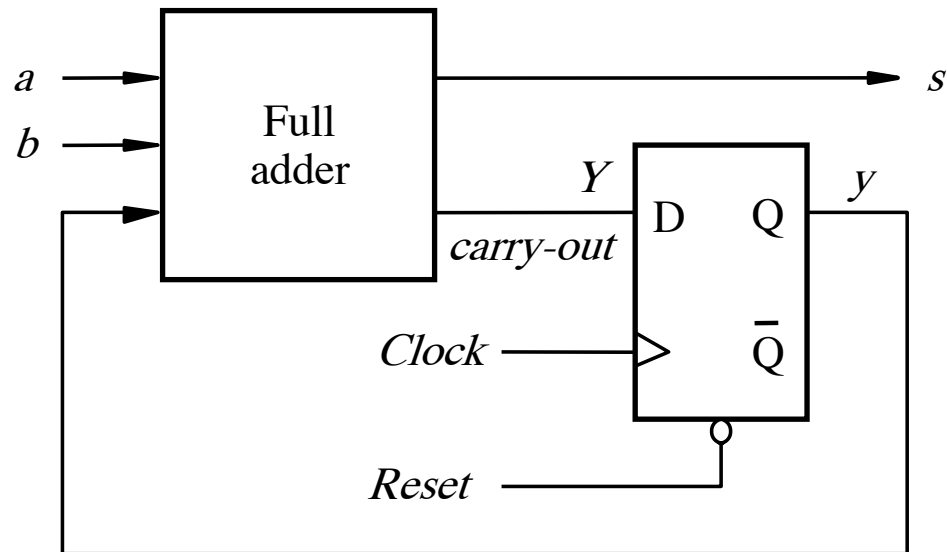
$$Y_1 = a \oplus b \oplus y_2 \quad (\text{sum bit from FA})$$

$$Y_2 = ab + ay_2 + by_2 \quad (\text{carry bit from FA})$$

$$s = y_1$$

[ Figure 6.47 from the textbook ]

# Circuit for the Mealy-type serial adder FSM

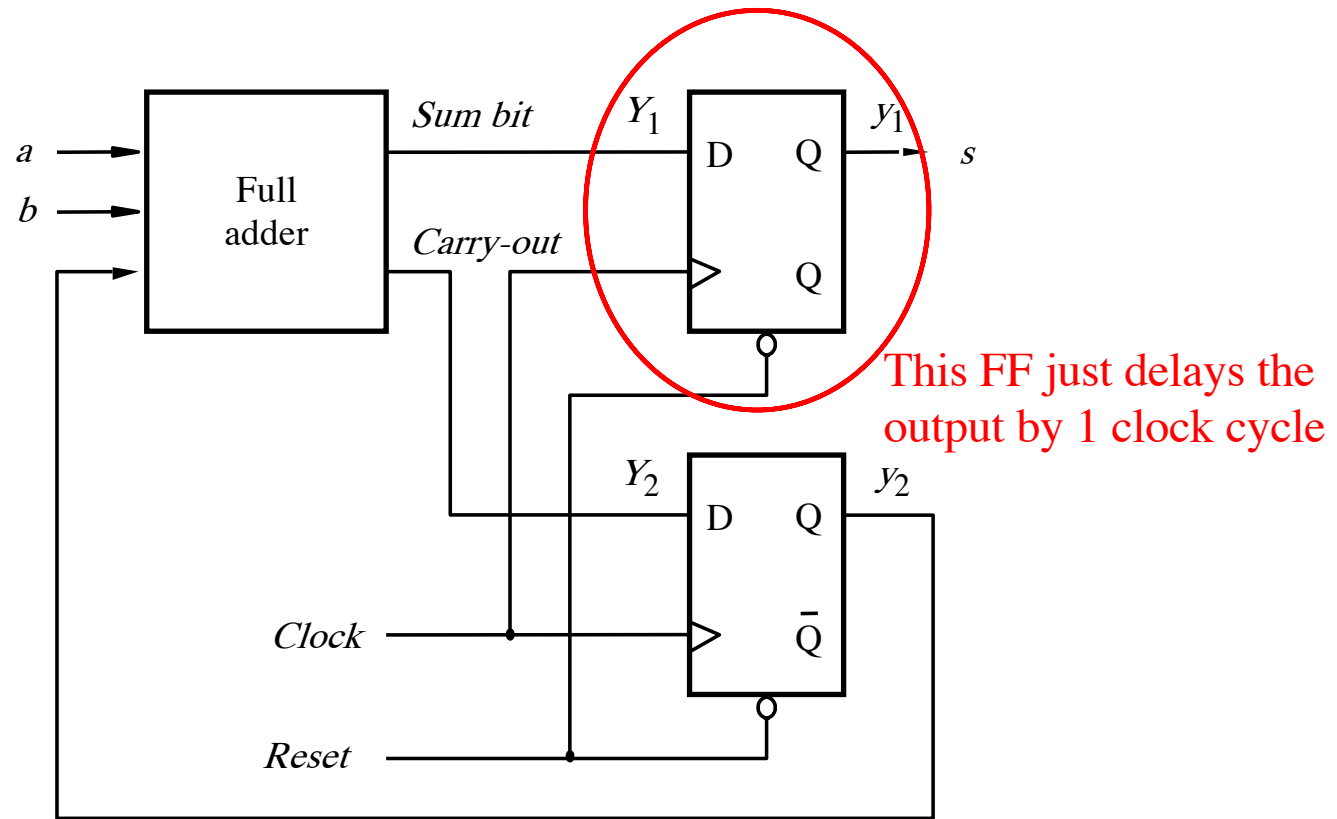


$$s = \text{XOR}(\text{XOR}(a, b), y) \quad (\text{sum bit from FA})$$

$$Y = ab + ay + by \quad (\text{carry bit from FA})$$

[ Figure 6.43 from the textbook ]

# Circuit for the Moore-type serial adder FSM



$$Y_1 = a \oplus b \oplus y_2 \quad (\text{sum bit from FA})$$

$$Y_2 = ab + ay_2 + by_2 \quad (\text{carry bit from FA})$$

$$s = y_1$$

[ Figure 6.47 from the textbook ]

# **Arbiter Circuit**



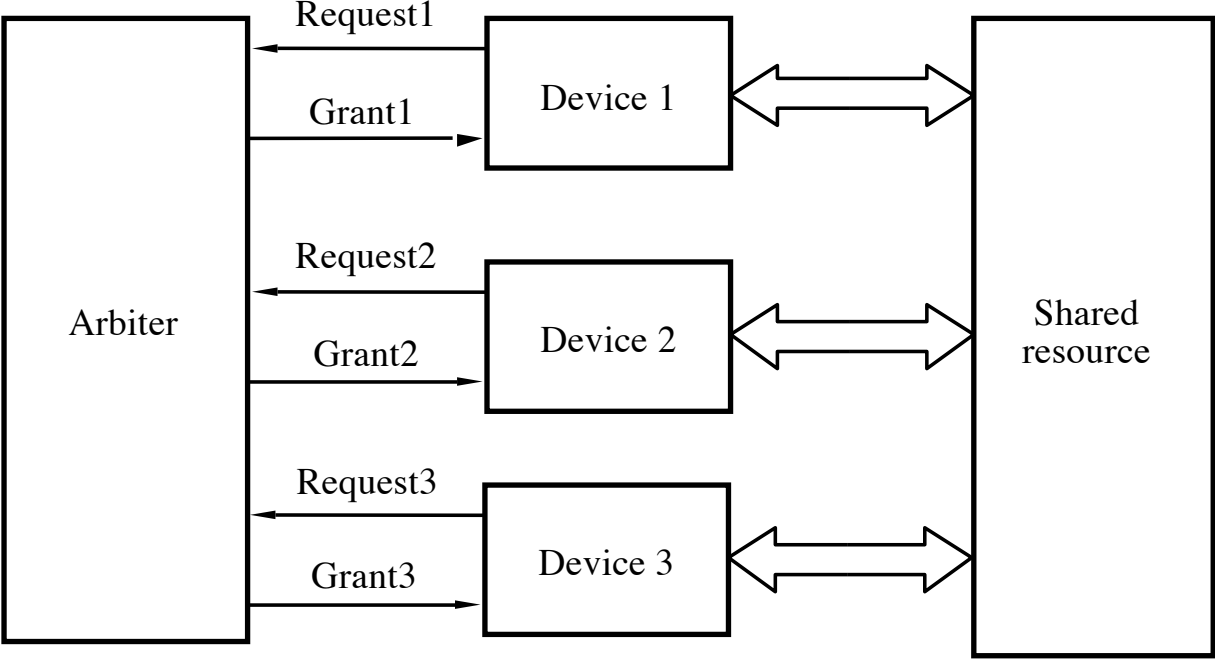
# Goal

- **Design a machine that controls access by several devices to a shared resource.**
- **The resource can be used by only one device at a time.**
- **Any changes can occur only on the positive edge of the clock signal.**
- **Each device provides one input to the FSM, which is called a request.**
- **The FSM produces one output for each device, which is called a grant.**

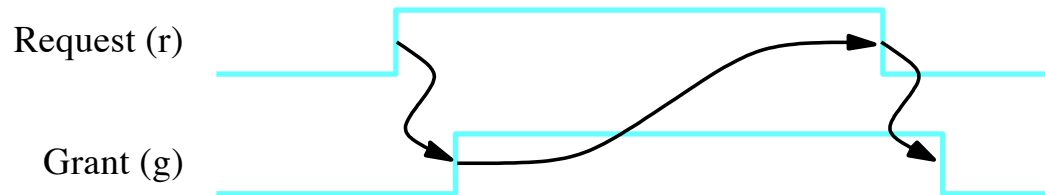
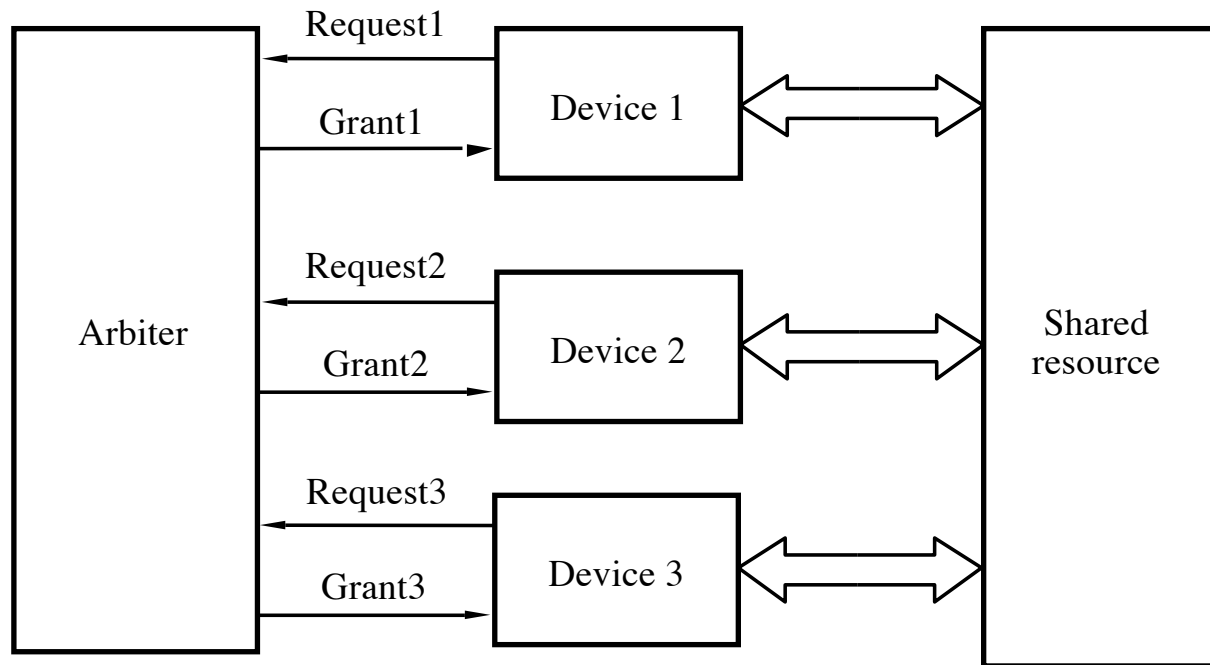
# Goal

- **The requests from the devices are prioritized.**
- **If two requests are active at the same time, then only the device with the highest priority will be given access to the shared resource.**
- **After a device is done with the shared resource, it must make its request signal equal to 0.**
- **If there are no outstanding requests, then the FSM stays in an Idle state.**

# Conceptual Diagram

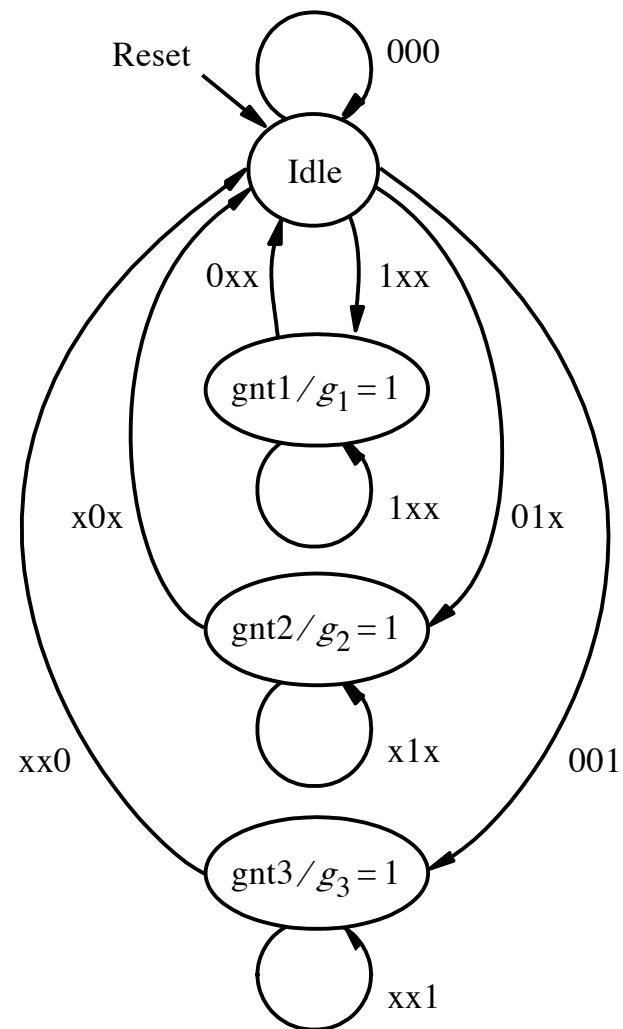


# Conceptual Diagram



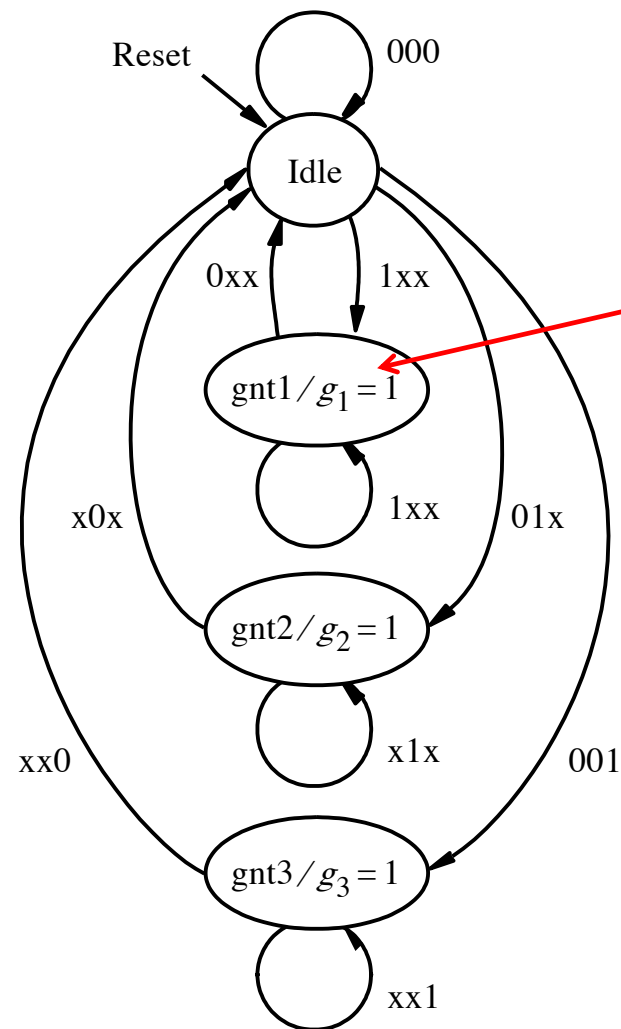
[ Figure 9.20 from the textbook ]

# State diagram for the arbiter



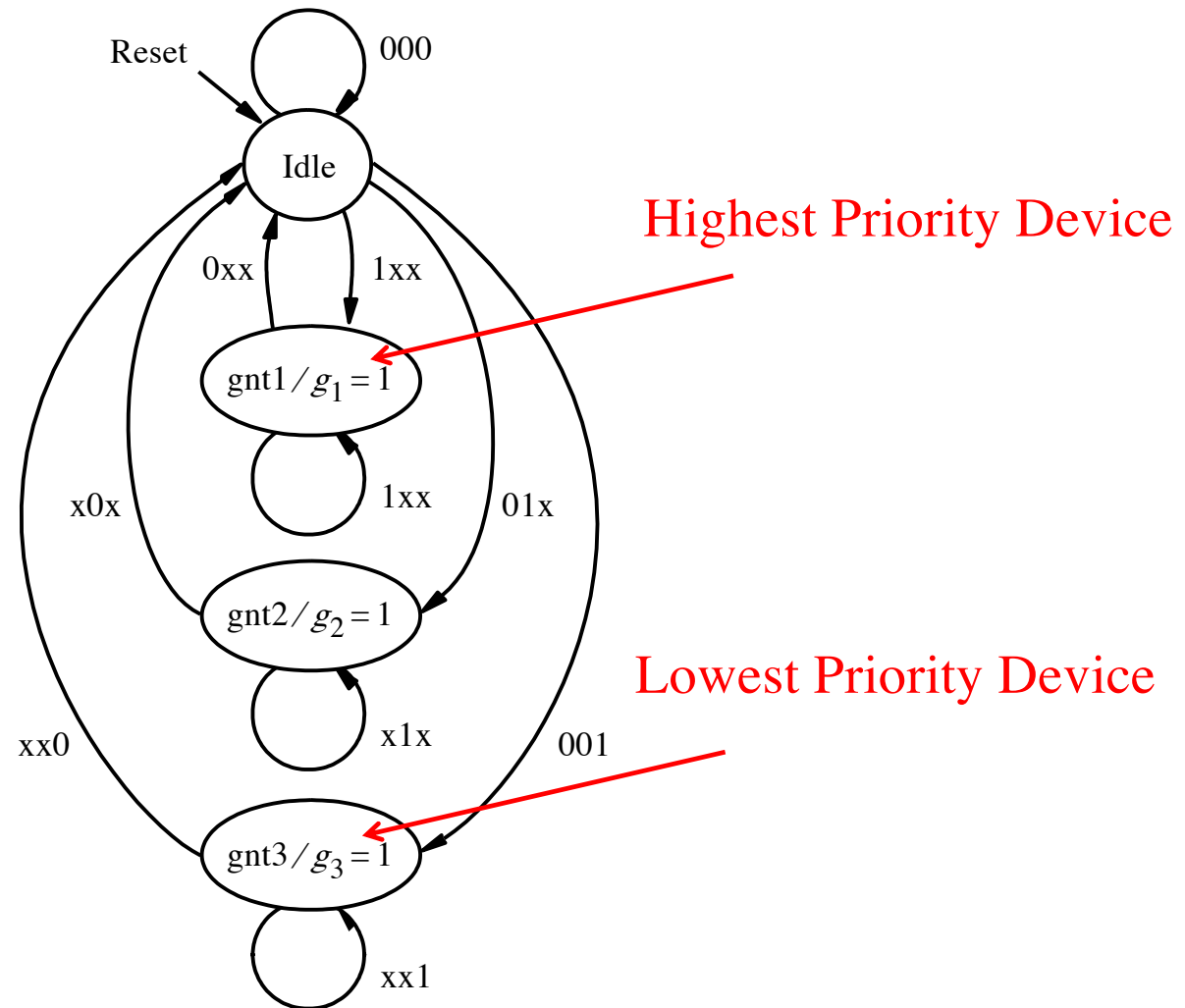
[ Figure 6.72 from the textbook ]

# State diagram for the arbiter

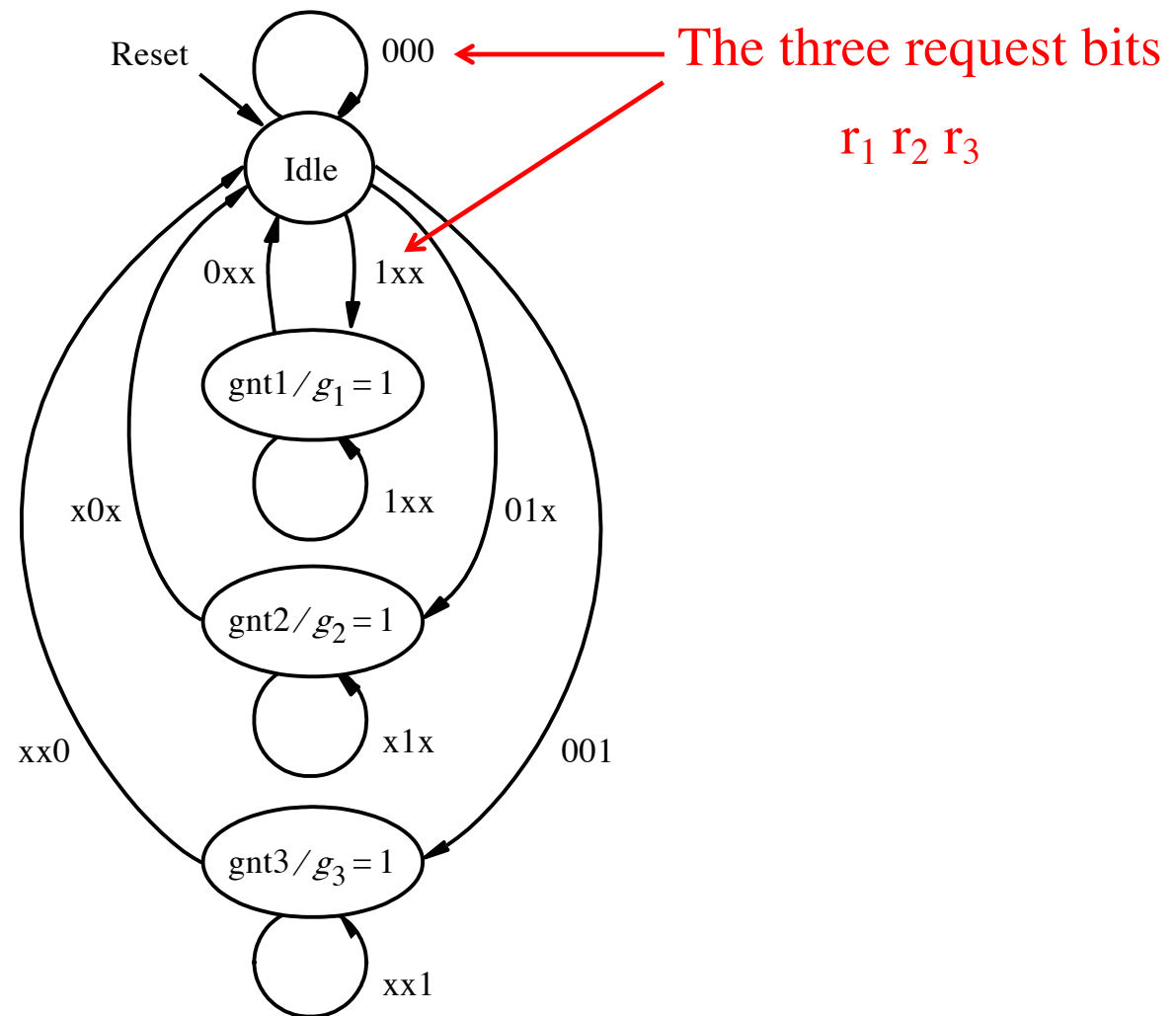


Highest Priority Device

# State diagram for the arbiter



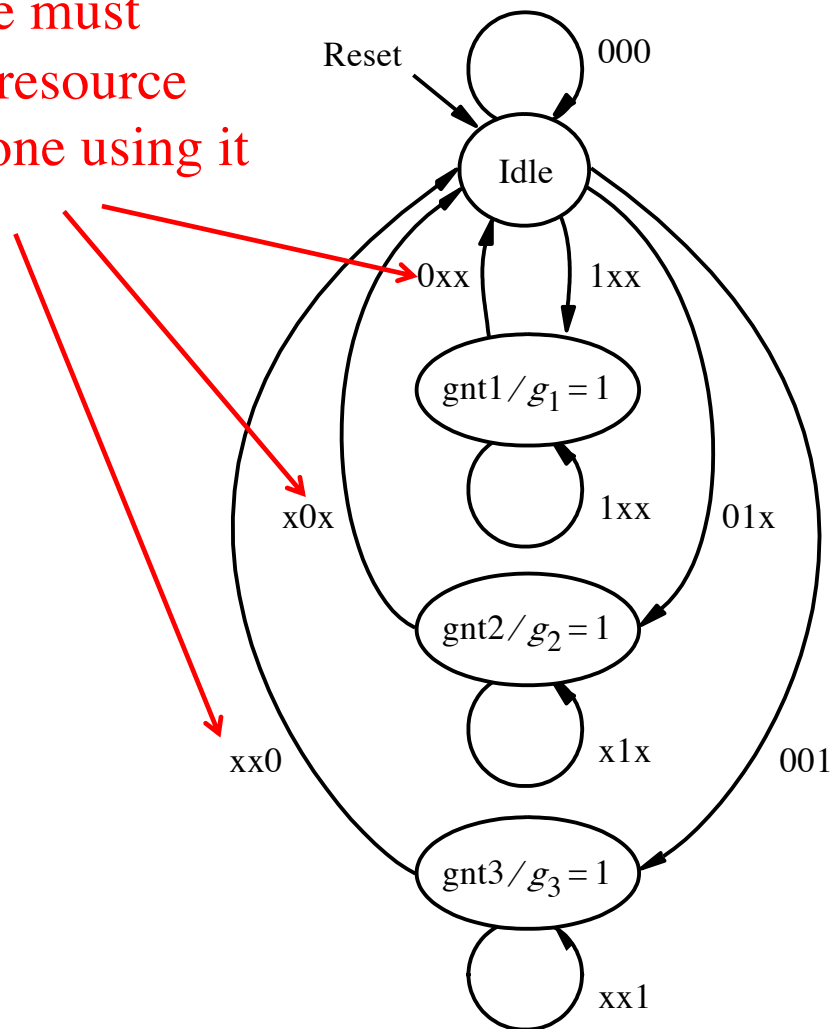
# State diagram for the arbiter



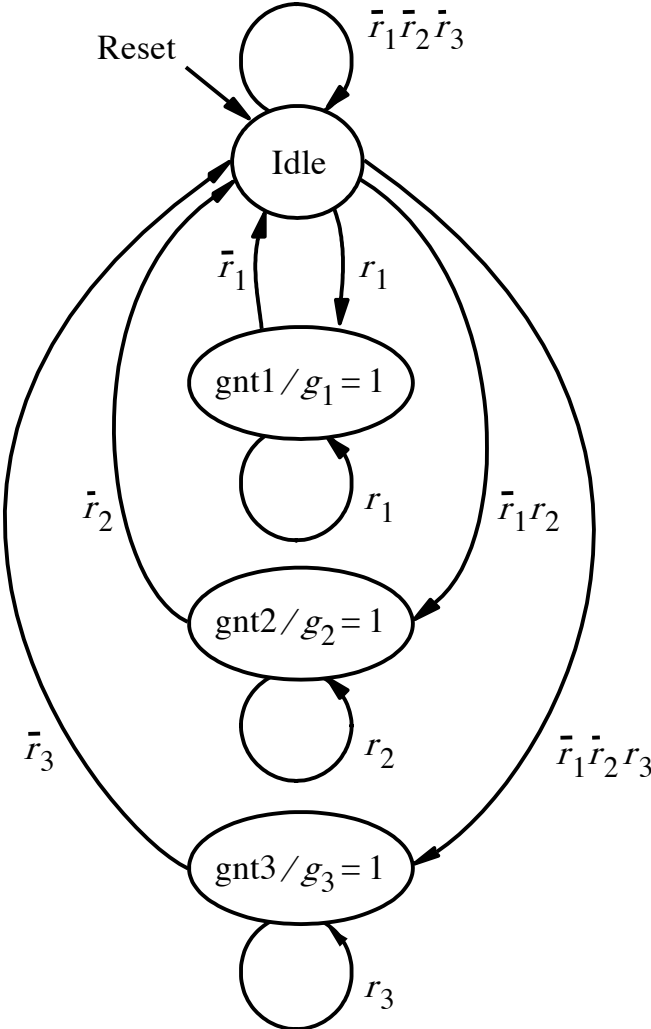


# State diagram for the arbiter

Each device must release the resource after it is done using it



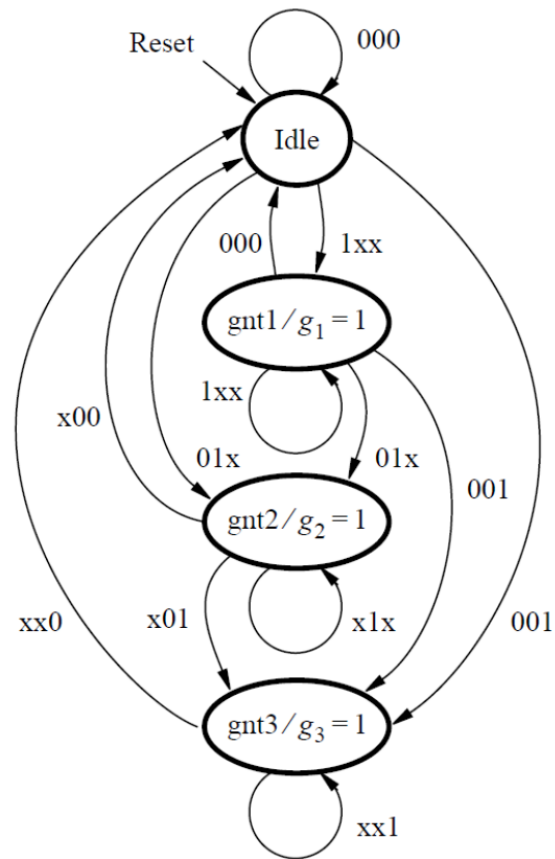
# Alternative style of state diagram for the arbiter



[ Figure 6.73 from the textbook ]

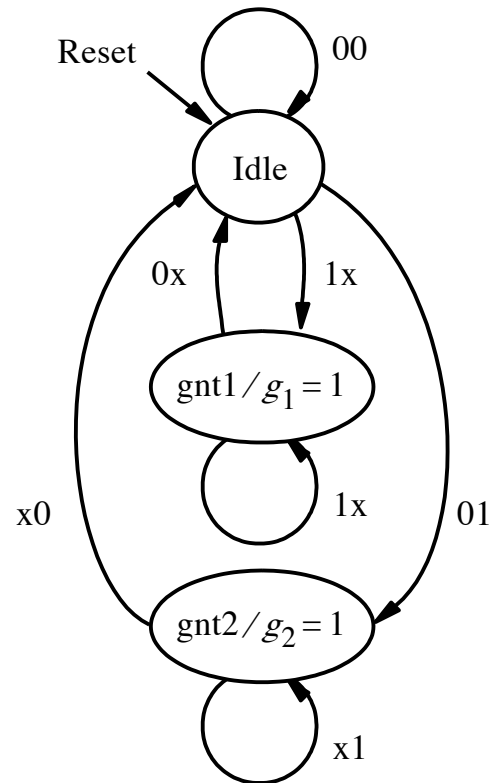
**This design has one flaw:  
If device1 and device2 raise requests all the  
time, then device3 will never get serviced.**

**This state diagram solves this problem**

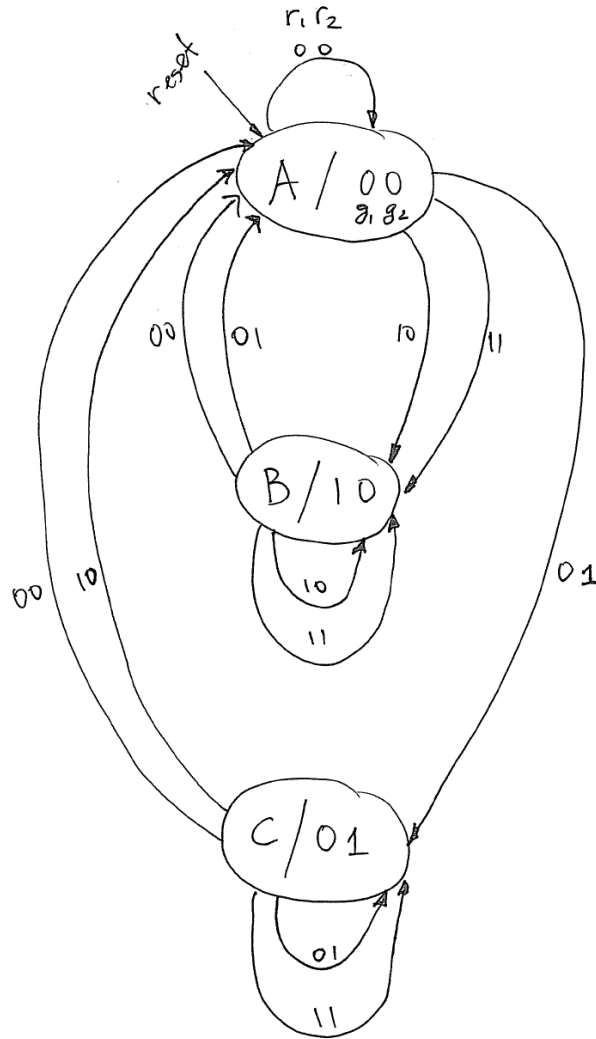


**Let's look at a simpler example with  
only two devices that need to use  
the shared resource**

# State diagram for the simpler arbiter



# State diagram for the arbiter circuit



# State Table

	$r_1 r_2 = 00$	01	10	11	Output
A	A	C	B	B	00
B	A	A	B	B	10
C	A	C	A	C	01



# State-Assigned Table

	Present state $y_2 y_1$	Next state				Output $g_1 g_2$
		$r_1 r_2 = 00$	01	10	11	
		$Y_2 Y_1$				
A	00	00	10	01	01	00
B	01	00	00	01	01	10
C	10	00	10	00	10	01
	11	dd	dd	dd	dd	dd

# Output Expressions

Output expressions

$$g_1 = Y_1$$

$$g_2 = Y_2$$

# Next State Expressions

$Y_2$

		$Y_2 Y_1$			
		00	01	11	10
$r_1 r_2$	00	0	0	d	0
	01	1	0	d	1
	11	0	0	d	1
	10	0	0	d	0

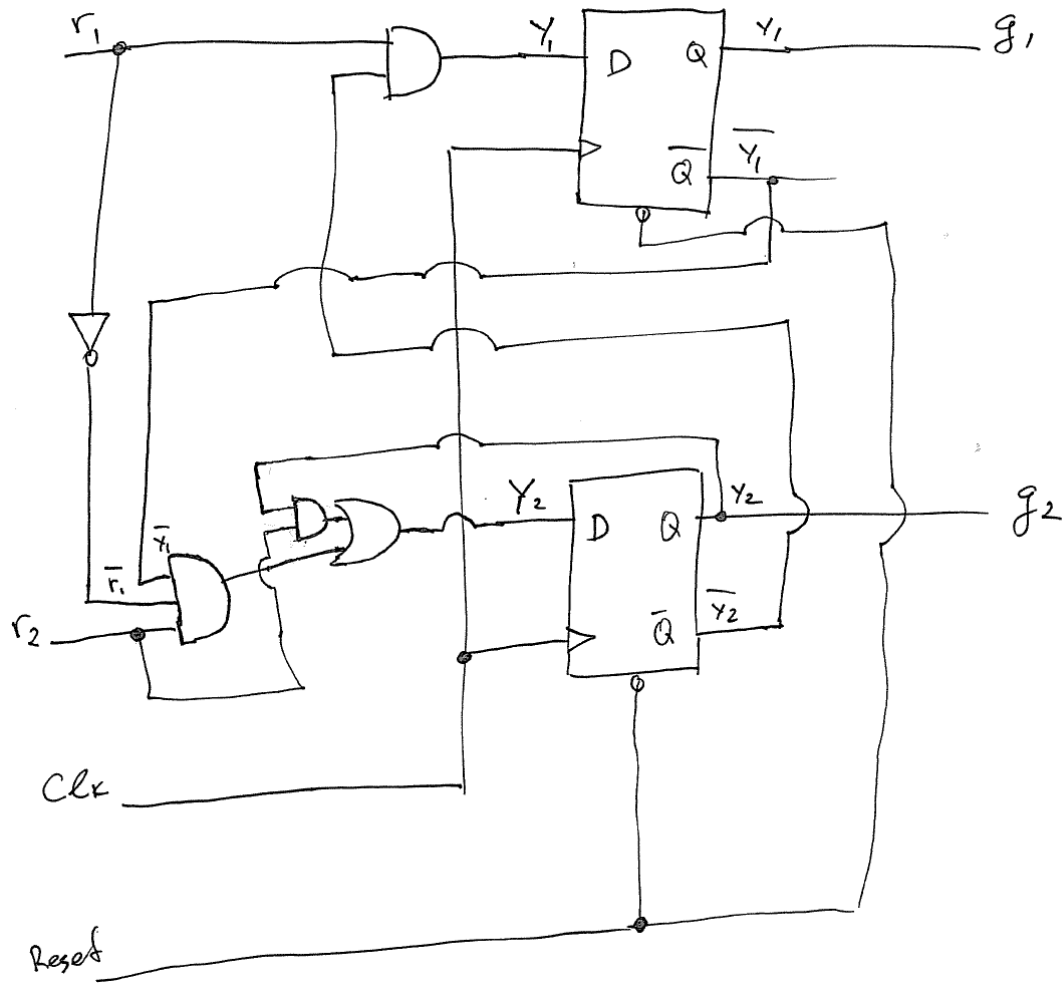
$$Y_2 = r_2 Y_2 + \bar{r}_1 r_2 \bar{Y}_1$$

$Y_1$

		$Y_2 Y_1$			
		00	01	11	10
$r_1 r_2$	00	0	0	d	0
	01	0	0	d	0
	11	1	1	d	0
	10	1	1	d	0

$$Y_1 = r_1 \bar{Y}_2$$

# Circuit Diagram



**Questions?**

**THE END**