Duality #1

1.0 Second iteration for HW problem

Recall our LP example problem we have been working on, in equality form, is given below.

\[
\begin{align*}
\text{max } F &= 3x_1 + 5x_2 \\
\text{s.t. } & \begin{align*}
x_1 + x_3 &= 4 \\
2x_2 + x_4 &= 12 \\
3x_1 + 2x_2 + x_5 &= 18
\end{align*}
\end{align*}
\]

\[x_1 \geq 0, x_2 \geq 0, x_3 \geq 0, x_4 \geq 0, x_5 \geq 0\]

which, when written in a slightly different form, is

\[
\begin{align*}
F - 3x_1 - 5x_2 &= 0 \\
x_1 + x_3 &= 4 \\
2x_2 + x_4 &= 12 \\
3x_1 + 2x_2 + x_5 &= 18
\end{align*}
\]

Recall that we performed the first iteration of the simplex method for it, which resulted in the following Tableau:
Tableau 1

<table>
<thead>
<tr>
<th>Basic variable</th>
<th>Eq. #</th>
<th>Coefficients of</th>
<th>Right side</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>$F$  $x_1$  $x_2$  $x_3$  $x_4$  $x_5$</td>
<td></td>
</tr>
<tr>
<td>$F$</td>
<td>0</td>
<td>1    -3    0      0      2.5     0      30</td>
<td></td>
</tr>
<tr>
<td>$x_3$</td>
<td>1</td>
<td>0    1      0      1      0       0      4</td>
<td></td>
</tr>
<tr>
<td>$x_2$</td>
<td>2</td>
<td>0    0      1      0      0.5     0      6</td>
<td></td>
</tr>
<tr>
<td>$x_5$</td>
<td>3</td>
<td>0    3      0      0      -1      1      6</td>
<td></td>
</tr>
</tbody>
</table>

Then when we tested for optimality, we discovered that we must do another iteration because the coefficient of $x_1$ is negative in the above tableau. I asked you to do this for homework. I will do it here, to provide you with the solution to the homework.

So our only choice for the entering variable is $x_1$. To determine the leaving variable, we identify the constraints that most limit the increase in $x_1$, as shown in Tableau 2 below.

Tableau 2

<table>
<thead>
<tr>
<th>Basic variable</th>
<th>Eq. #</th>
<th>Coefficients of</th>
<th>Right side</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>$F$  $x_1$  $x_2$  $x_3$  $x_4$  $x_5$</td>
<td></td>
</tr>
<tr>
<td>$F$</td>
<td>0</td>
<td>1    -3    0      0      2.5     0      30</td>
<td></td>
</tr>
<tr>
<td>$x_3$</td>
<td>1</td>
<td>0    1      0      1      0       0      4</td>
<td></td>
</tr>
<tr>
<td>$x_2$</td>
<td>2</td>
<td>0    0      1      0      0.5     0      6</td>
<td></td>
</tr>
<tr>
<td>$x_5$</td>
<td>3</td>
<td>0    3      0      0      -1      1      6</td>
<td></td>
</tr>
</tbody>
</table>

And so the constraint identifying the leaving variable is the last one, since its ratio is smallest (2<4).
The leaving variable is therefore $x_5$, since it is the variable in the last constraint which gets pushed to 0 as $x_1$ increases. And so the tableau is shown below with the pivot row, pivot column, and pivot element identified. We have also modified the last basic variable (column 1) to be $x_1$.

Tableau 3

<table>
<thead>
<tr>
<th>Basic variable</th>
<th>Eq. #</th>
<th>Coefficients of</th>
<th>Right side</th>
</tr>
</thead>
<tbody>
<tr>
<td>$F$</td>
<td></td>
<td>$F$ $x_1$ $x_2$ $x_3$ $x_4$ $x_5$</td>
<td>$30$</td>
</tr>
<tr>
<td>$x_3$</td>
<td>1</td>
<td>0 1 0 1 0</td>
<td>4</td>
</tr>
<tr>
<td>$x_2$</td>
<td>2</td>
<td>0 0 1 1 0</td>
<td>6</td>
</tr>
<tr>
<td>$x_1$</td>
<td>3</td>
<td>1 0 0 0 1</td>
<td>2</td>
</tr>
</tbody>
</table>

Dividing the last equation by 3, we obtain:

Tableau 4

<table>
<thead>
<tr>
<th>Basic variable</th>
<th>Eq. #</th>
<th>Coefficients of</th>
<th>Right side</th>
</tr>
</thead>
<tbody>
<tr>
<td>$F$</td>
<td></td>
<td>$F$ $x_1$ $x_2$ $x_3$ $x_4$ $x_5$</td>
<td>$30$</td>
</tr>
<tr>
<td>$x_3$</td>
<td>1</td>
<td>0 1 0 1 0</td>
<td>4</td>
</tr>
<tr>
<td>$x_2$</td>
<td>2</td>
<td>0 0 1 1 0</td>
<td>6</td>
</tr>
<tr>
<td>$x_1$</td>
<td>3</td>
<td>1 0 0 0 1</td>
<td>2</td>
</tr>
</tbody>
</table>

Using the last equation to eliminate the -3 in the top equation, we get:

Tableau 5

<table>
<thead>
<tr>
<th>Basic variable</th>
<th>Eq. #</th>
<th>Coefficients of</th>
<th>Right side</th>
</tr>
</thead>
<tbody>
<tr>
<td>$F$</td>
<td></td>
<td>$F$ $x_1$ $x_2$ $x_3$ $x_4$ $x_5$</td>
<td>$30$</td>
</tr>
<tr>
<td>$x_3$</td>
<td>1</td>
<td>0 1 0 1 0</td>
<td>4</td>
</tr>
<tr>
<td>$x_2$</td>
<td>2</td>
<td>0 0 1 1 0</td>
<td>6</td>
</tr>
<tr>
<td>$x_1$</td>
<td>3</td>
<td>1 0 0 0 1</td>
<td>2</td>
</tr>
</tbody>
</table>
Using the last equation to eliminate the 1 from the second equation, we get:

**Tableau 6**

<table>
<thead>
<tr>
<th>Basic variable</th>
<th>Eq. #</th>
<th>Coefficients of</th>
<th>Right side</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>$x_1$</td>
<td>$x_2$</td>
</tr>
<tr>
<td>$F$</td>
<td>0</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>$x_3$</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>$x_2$</td>
<td>2</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>$x_1$</td>
<td>3</td>
<td>0</td>
<td>1</td>
</tr>
</tbody>
</table>

The solution above is optimal because all coefficients in the objective function expression are positive.

### 2.0 Introduction to duality

Let’s consider that our linear programming problem is actually a resource allocation problem where the various constraints are actually constraints on our resources. Recalling the original form of the problem, and giving it the name “Problem P”:

**Problem P**

\[
\begin{align*}
\text{max } F &= 3x_1 + 5x_2 \\
\text{s.t. } x_1 &\leq 4 \\
2x_2 &\leq 12 \\
3x_1 + 2x_2 &\leq 18 \\
x_1, x_2 &\geq 0
\end{align*}
\]

we see that our new interpretation indicates that 4, 12, and 18 represent the maximum amount of each kind of resource that we have.
Now the question could very well arise: *how might we gain the most, in terms of the value of our optimized objective function, by increasing one resource or another?*

In order to provide a basis of comparison, let’s allow each resource to increase by 1 unit. What will be the effect on the objective function?

To answer this question, I first solved the original LP, (1), in CPLEX. As we would expect, I got the answer 

\[ F_1^* = 36, \]

consistent with Tableau 6 above. (The subscript on \( F \), which is “1” in this case, indicates it is the solution to the LP defined by (1) above).

Then I used CPLEX to solve LP (2).

\[
\begin{align*}
\text{max } F &= 3x_1 + 5x_2 \\
\text{s.t. } x_1 &\leq 5 \\
& 2x_2 \leq 12 \\
& 3x_1 + 2x_2 \leq 18 \\
& x_1 \geq 0, x_2 \geq 0
\end{align*}
\]

(2)

where the only difference, relative to (1), is that the upper bound on the first constraint was increased from 4 to 5. CPLEX provides the answer 

\[ F_2^* = 36. \]

Apparently, increasing resources on this constraint has no effect.
Then I used CPLEX to solve LP (3):
\[
\begin{align*}
\text{max } F &= 3x_1 + 5x_2 \\
s.t. \quad x_1 &\leq 4 \\
2x_2 &\leq 13 \\
3x_1 + 2x_2 &\leq 18 \\
x_1 &\geq 0, x_2 \geq 0
\end{align*}
\]
(3)
where the only difference, relative to (1), is that the upper bound on the second constraint was increased from 12 to 13. CPLEX provides the answer \( F_3^* = 37.5 \). Here, increasing the second resource by 1 unit provides that the objective function improves by an amount equal to 1.5.

Finally, I used CPLEX to solve LP (4):
\[
\begin{align*}
\text{max } F &= 3x_1 + 5x_2 \\
s.t. \quad x_1 &\leq 4 \\
2x_2 &\leq 12 \\
3x_1 + 2x_2 &\leq 19 \\
x_1 &\geq 0, x_2 \geq 0
\end{align*}
\]
(4)
where the only difference, relative to (1), is that the upper bound on the third constraint was increased from 18 to 19. CPLEX provides the answer \( F_4^* = 37 \). Here, increasing the third resource by 1 unit provides that the objective function improves by an amount equal to 1.
And so increasing the resources, i.e., the right hand sides of the first, second, and third constraints, by 1 unit, improve the optimal value of the objective function by 0, 1.5, and 1, respectively. In other words,

\[
\frac{\Delta F^*}{\Delta b_1} = 0
\]

\[
\frac{\Delta F^*}{\Delta b_2} = 1.5
\]

\[
\frac{\Delta F^*}{\Delta b_3} = 1
\]

This is quite useful information, in that it could guide our future allocation (or reallocation) or resources. In other words, assume \( F^* \) represents my optimal profits, and I find I have a little extra money to spend. Then (5) tells me it is better to spend that money to increase resource 2 than to increase resource 3, and that it will do me no good at all to increase resource 1. It is of interest to inspect Tableau 6 at this point.

Tableau 6

<table>
<thead>
<tr>
<th>Basic variable</th>
<th>Eq. #</th>
<th>Coefficients of</th>
<th>Right side</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>( F )</td>
<td>( x_1 )</td>
</tr>
<tr>
<td>( F )</td>
<td>0</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>( x_3 )</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>( x_2 )</td>
<td>2</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>( x_1 )</td>
<td>3</td>
<td>0</td>
<td>1</td>
</tr>
</tbody>
</table>

Notice one very interesting thing:
The coefficients of the slack variables in this final tableau are exactly the same as the right-hand-sides of (5): 0, 1.5, and 1. These values are circled in Tableau 6.

This is no coincidence. In fact, it will always happen. That is:

*The coefficients of the slack variables in the objective function expression of the final tableau give the improvement in the objective for a unit increase in the right-hand-sides of the corresponding constraints.*

It is of interest to examine the units of these coefficients, an exercise most effectively accomplished by returning to (5) where we can see that they have units of (units of $F$)/(units of $b$). For example, if $F$ is measured in dollars, and $b$ is measured in, say, pipe fittings, then these coefficients would have units of $\$/pipe fitting.

These slack variable coefficients have names. They are called the *dual variables*. We will see why they are called dual variables later. They are also called *shadow prices*. For now, let’s give them the nomenclature $\lambda_i$ corresponding to the $i^{th}$ constraint.
One note of caution, here. Recalling that $\lambda_3=1$ in our problem, we understand that if we increase $b_3$ by 1, from 18 to 19, we will improve our objective function value (at the optimum) by 1, from 36 to 37, and that is indeed the case.

But what if we increase $b_3$ by 6, making it 24? Will we see an increase in $F^*$ to 42? Use of CPLEX indicates this does turn out to be the case.

However, if we increase $b_3$ to 26, we still obtain $F^*=42$, a result which suggests that somewhere between $b_3=24$ and $b_3=26$, the third constraint became no longer binding (it was no longer one of the two constraints that defined the corner point).

This is a result of the fact that whenever one has multiple resources, each of which is constrained, it will be the case that only a subset of the resources actually limit the objective. For example, you may have labor hours, trucks, & pipe fittings as your resources, each of which are individually constrained. You have a large truck fleet and a whole warehouse of pipe fittings, but you don’t have enough labor. And so you increase labor until you hit your limit on pipe fitting inventory. You then begin increasing pipe fitting inventory, but soon you hit the limit on trucks.
3.0 Motivating the dual problem

Consider again our original problem.

\[
\begin{align*}
\text{max } F &= 3x_1 + 5x_2 \\
\text{s.t. } x_1 &\leq 4 \\
&
2x_2 &\leq 12 \\
&
3x_1 + 2x_2 &\leq 18 \\
&
x_1 &\geq 0, x_2 &\geq 0
\end{align*}
\]  \hspace{1cm} (6)

Let’s express linear combinations of multiples of the constraints, where the multipliers on the constraints are denoted \( \lambda_i \) on the \( i^{th} \) constraint. The below problem illustrates (the \( \lambda_i \) must be nonnegative):

\[
\begin{align*}
\text{max } F &= 3x_1 + 5x_2 \\
\text{s.t. } (x_1 &\leq 4)\lambda_1 \\
&
+ (2x_2 &\leq 12)\lambda_2 \\
&
+ (3x_1 + 2x_2 &\leq 18)\lambda_3
\end{align*}
\] \hspace{1cm} (7)

\[
(x_1\lambda_1 + 3x_1\lambda_3) + (2x_2\lambda_2 + 2x_2\lambda_3) \leq 4\lambda_1 + 12\lambda_2 + 18\lambda_3 
\]

The last relation can be rewritten as follows:

\[
\begin{align*}
\text{max } F &= 3x_1 + 5x_2 \\
\text{s.t. } (x_1 &\leq 4)\lambda_1 \\
&
+ (2x_2 &\leq 12)\lambda_2 \\
&
+ (3x_1 + 2x_2 &\leq 18)\lambda_3
\end{align*}
\] \hspace{1cm} (8)

\[
(\lambda_1 + 3\lambda_3)x_1 + (2\lambda_2 + 2\lambda_3)x_2 \leq 4\lambda_1 + 12\lambda_2 + 18\lambda_3 
\]
The left-hand-side of the composite inequality, being a linear combination of our original inequalities, **must hold** at any feasible solution \((x_1,x_2)\), and in particular, at the optimal solution \((x_1^*,x_2^*)\). That is, it is a necessary condition for satisfying the inequalities from which it came\(^1\).

Write the objective function expression together with the composite inequality:
\[
F = 3x_1 + 5x_2
\]
\[
(\lambda_1 + 3\lambda_3)x_1 + (2\lambda_2 + 2\lambda_3)x_2 \leq 4\lambda_1 + 12\lambda_2 + 18\lambda_3 \quad (9)
\]
Let’s develop criteria for selecting \(\lambda_1, \lambda_2, \lambda_3\).

Consider the following 5 concepts… **watch closely**: Concept 1: Make sure that our choices of \(\lambda_1, \lambda_2, \lambda_3\) are such that each coefficient of \(x_i\) in the composite inequality is at least as great as the corresponding coefficient in the objective function expression, i.e.,
\[
\lambda_1 + 3\lambda_3 \geq 3 \\
2\lambda_2 + 2\lambda_3 \geq 5
\]
(10)

This guarantees that any solution \((x_1,x_2)\) results in a value \(F\) which is less than or equal to the left-hand-side of the composite inequality.

\(^1\) Although necessary, it is not sufficient. A simple example will show this. Choose \(\lambda_1 = \lambda_2 = \lambda_3 = 1\), and the combined inequality is then \(4x_1 + 4x_2 \leq 34\). All values of \((x_1, x_2)\) that satisfy the original inequalities must satisfy this one, but there will be some that satisfy this one that do not satisfy one or more of the original inequalities, for example, \((4,4)\) results here in \(32 \leq 34\), but the third inequality of the original ones results in \(3(4)+2(4)=20\) which is greater than its right-hand-side of 18.
Concept 2: Because the left-hand side of the composite inequality is less than or equal to the right hand side of the composite inequality, we can also say that any solution \((x_1, x_2)\) results in a value \(F\) which is less than or equal to the right-hand-side of the composite inequality.

Concept 3: Concept 2 implies the right-hand-side of the composite inequality is an upper bound on the value that \(F\) may take. This is true for any value of \(F\), even the maximum value \(F^*\). In other words, if we look at the value \(F^*\) and the right-hand-side of the composite inequality on the real number line, they appear as below, with \(F^*\) to the left, and there would be some difference \(\Delta\) between them.

![Diagram showing relationship between \(F^*\) and the right-hand-side of the composite inequality]

Concept 4: Now choose \(\lambda_1, \lambda_2, \lambda_3\) to minimize the right-hand-side of the composite inequality, subject to constraints (10). This creates a least upper bound to \(F^*\), i.e., it pushes the right-hand-side of the composite inequality as far left as possible, while guaranteeing right-hand-side remains greater than or equal to \(F^*\) (due to enforcement of constraints (10)).

Concept 5: Given that the right-hand-side of the composite inequality is an upper bound to \(F^*\), then finding its minimum, subject to (10), implies \(\Delta=0\).
Concept 5 tells us that if we solve the following problem, call it Problem D,

\begin{align*}
\text{Problem D} \\
\min G &= 4\lambda_1 + 12\lambda_2 + 18\lambda_3 \\
\text{subject to} \\
\lambda_1 + 3\lambda_3 &\geq 3 \\
2\lambda_2 + 2\lambda_3 &\geq 5 \\
\lambda_1 &\geq 0, \lambda_2 &\geq 0, \lambda_3 &\geq 0
\end{align*}

that the value of the obtained objective function, at the optimum, will be the same as the value of the original objective function at its optimum, i.e., \( F^* = G^* \).

In other words, solving Problem D is equivalent to solving Problem P.

\begin{align*}
\text{Problem P} \\
\max F &= 3x_1 + 5x_2 \\
\text{s.t. } x_1 &\leq 4 \\
2x_2 &\leq 12 \\
3x_1 + 2x_2 &\leq 18 \\
x_1 &\geq 0, x_2 &\geq 0
\end{align*}

\begin{align*}
\text{Problem D} \\
\min G &= 4\lambda_1 + 12\lambda_2 + 18\lambda_3 \\
\text{subject to} \\
\lambda_1 + 3\lambda_3 &\geq 3 \\
2\lambda_2 + 2\lambda_3 &\geq 5 \\
\lambda_1 &\geq 0, \lambda_2 &\geq 0, \lambda_3 &\geq 0
\end{align*}

Problem P is called the primal problem. Problem D is called the dual problem. They are precisely equivalent. To show this, let’s use CPLEX to solve Problem D.
The CPLEX code to do it is below (note I am using $y$ instead of $\lambda$):

```plaintext
minimize
  1 y1 + 12 y2 + 18 y3
subject to
  1 y1 + 3 y3 >= 3
  2 y2 + 2 y3 >=5
  y1 >= 0
  y2 >= 0
  y3 >= 0
end
```

The solution gives

- $G^* = 36$
- $\lambda_1 = 0$
- $\lambda_2 = 1.5$
- $\lambda_3 = 1$

It is of interest to inspect Tableau 6 of the primal.

<table>
<thead>
<tr>
<th>Basic variable</th>
<th>Eq. #</th>
<th>Coefficients of</th>
<th>Right side</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>$F$</td>
<td>$x_1$</td>
</tr>
<tr>
<td>$F$</td>
<td>0</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>$x_3$</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>$x_2$</td>
<td>2</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>$x_1$</td>
<td>3</td>
<td>0</td>
<td>1</td>
</tr>
</tbody>
</table>

We note the values of the decision variables obtained for the dual problem are exactly the coefficients of the slack variables in the primal problem.
We also note that $G^*=F^*=36$.

One last thing that is very interesting here. Using CPLEX, following solution of the dual, we can also obtain the coefficients for the dual problem slack variables (the slack variables to problem D), in the objective function row, using the following command,

\[
\text{display solution dual -}
\]

and they are:

\[
\begin{align*}
\lambda_4 & \rightarrow 2.0 \\
\lambda_5 & \rightarrow 6.0
\end{align*}
\]

which is precisely the solution of the primal problem, $x_1=2$, $x_2=6$, as can be read off from Tableau 6 above.

Caution to avoid confusion: The above values for $\lambda_4$ and $\lambda_5$ are not the values of the slack variables. They are the coefficients of the slack variables of the objective function expression in the last tableau of the dual problem.

This suggests that there is a certain circular relationship here, which can be stated as

*The dual of the dual to a primal is the primal.*

That is, if you called Problem D our primal problem, and took its dual, you would get our original primal problem back, as illustrated below.
Problem D
\[ \min G = 4\lambda_1 + 12\lambda_2 + 18\lambda_3 \]
subject to
\[ \lambda_1 + 3\lambda_3 \geq 3 \]
\[ 2\lambda_2 + 2\lambda_3 \geq 5 \]
\[ \lambda_1 \geq 0, \lambda_2 \geq 0, \lambda_3 \geq 0 \]

Problem P
\[ \max F = 3x_1 + 5x_2 \]
s.t. \[ x_1 \quad \leq 4 \]
\[ 2x_2 \leq 12 \]
\[ 3x_1 + 2x_2 \leq 18 \]
\[ x_1 \geq 0, x_2 \geq 0 \]

\[ \begin{array}{c}
\text{Primal Problem} \\
\text{Dual Problem}
\end{array} \]

### 4.0 Obtaining the dual from the primal

It is useful to make the following observations:
1. Number of decision variables and constraints:
   - Number of dual decision variables is number of primal constraints.
   - Number of dual constraints is number of primal decision variables.
2. Coefficients of decision variables in dual objective are right-hand-sides of primal constraints.

<table>
<thead>
<tr>
<th>Problem P</th>
<th>Problem D</th>
</tr>
</thead>
<tbody>
<tr>
<td>[ \max F = 3x_1 + 5x_2 ]</td>
<td>[ \min G = 4\lambda_1 + 12\lambda_2 + 18\lambda_3 ]</td>
</tr>
<tr>
<td>s.t. [ x_1 \quad \leq 4 ]</td>
<td>subject to [ \lambda_1 + 3\lambda_3 \geq 3 ]</td>
</tr>
<tr>
<td>[ 2x_2 \leq 12 ]</td>
<td>[ 2\lambda_2 + 2\lambda_3 \geq 5 ]</td>
</tr>
<tr>
<td>[ 3x_1 + 2x_2 \leq 18 ]</td>
<td>[ \lambda_1 \geq 0, \lambda_2 \geq 0, \lambda_3 \geq 0 ]</td>
</tr>
<tr>
<td>[ x_1 \geq 0, x_2 \geq 0 ]</td>
<td>[ \text{Primal Problem} ]</td>
</tr>
</tbody>
</table>
3. Coefficients of decision variables in primal objective are right-hand-sides of dual constraints.

<table>
<thead>
<tr>
<th>Problem P</th>
<th>Problem D</th>
</tr>
</thead>
<tbody>
<tr>
<td>max ( F = 3x_1 + 5x_2 )</td>
<td>min ( G = 4\lambda_1 + 12\lambda_2 + 18\lambda_3 )</td>
</tr>
<tr>
<td>s.t. ( x_1 \leq 4 )</td>
<td>subject to ( \lambda_1 + 3\lambda_3 \geq 3 )</td>
</tr>
<tr>
<td>( 2x_2 \leq 12 )</td>
<td>( 2\lambda_2 + 2\lambda_3 \geq 5 )</td>
</tr>
<tr>
<td>( 3x_1 + 2x_2 \leq 18 )</td>
<td>( \lambda_1 \geq 0, \lambda_2 \geq 0, \lambda_3 \geq 0 )</td>
</tr>
<tr>
<td>( x_1 \geq 0, x_2 \geq 0 )</td>
<td>Dual Problem</td>
</tr>
</tbody>
</table>

4. Coefficients of one variable across multiple primal constraints are coefficients of multiple variables in one dual constraint.

<table>
<thead>
<tr>
<th>Problem P</th>
<th>Problem D</th>
<th>Problem D</th>
</tr>
</thead>
<tbody>
<tr>
<td>max ( F = 3x_1 + 5x_2 )</td>
<td>min ( G = 4\lambda_1 + 12\lambda_2 + 18\lambda_3 )</td>
<td>min ( G = 4\lambda_1 + 12\lambda_2 + 18\lambda_3 )</td>
</tr>
<tr>
<td>s.t. ( x_1 \leq 4 )</td>
<td>subject to ( \lambda_1 + 3\lambda_3 \geq 3 )</td>
<td>subject to ( \lambda_1 + 3\lambda_3 \geq 3 )</td>
</tr>
<tr>
<td>( 2x_2 \leq 12 )</td>
<td>( 2\lambda_2 + 2\lambda_3 \geq 5 )</td>
<td>( 2\lambda_2 + 2\lambda_3 \geq 5 )</td>
</tr>
<tr>
<td>( 3x_1 + 2x_2 \leq 18 )</td>
<td>( \lambda_1 \geq 0, \lambda_2 \geq 0, \lambda_3 \geq 0 )</td>
<td>( \lambda_1 \geq 0, \lambda_2 \geq 0, \lambda_3 \geq 0 )</td>
</tr>
<tr>
<td>( x_1 \geq 0, x_2 \geq 0 )</td>
<td>Dual Problem</td>
<td>Dual Problem</td>
</tr>
</tbody>
</table>
5. Coefficients of one variable across multiple dual constraints are coefficients of multiple variables in one primal constraint.

\[
\begin{align*}
\text{Problem P} & \quad \text{Problem D} \\
\max F &= 3x_1 + 5x_2 & \min G &= 4\lambda_1 + 12\lambda_2 + 18\lambda_3 \\
\text{s.t. } x_1 &\leq 4 \quad \text{subject to} \\
2x_2 &\leq 12 \quad \lambda_1 + 3\lambda_3 &\geq 3 \\
3x_1 + 2x_2 &\leq 18 \quad 2\lambda_2 + 2\lambda_3 &\geq 5 \\
x_1 &\geq 0, x_2 &\geq 0 \quad \lambda_1, \lambda_2, \lambda_3 &\geq 0
\end{align*}
\]

\[
\begin{align*}
\text{Primal Problem} & \quad \text{Dual Problem} \\
\text{Problem P} & \quad \text{Problem D} \\
\max F &= 3x_1 + 5x_2 & \min G &= 4\lambda_1 + 12\lambda_2 + 18\lambda_3 \\
\text{s.t. } x_1 &\leq 4 & \text{subject to} \\
2x_2 &\leq 12 & \lambda_1 + 3\lambda_3 &\geq 3 \\
3x_1 + 2x_2 &\leq 18 & 2\lambda_2 + 2\lambda_3 &\geq 5 \\
x_1 &\geq 0, x_2 &\geq 0 & \lambda_1, \lambda_2, \lambda_3 &\geq 0
\end{align*}
\]
6. If primal objective is maximization, then dual objective is minimization.
7. If primal constraints are $\leq$, dual constraints are $\geq$.
From the above, we should be able to immediately write down the dual given the primal.

**Example:**
Let’s return to the example we used to illustrate use of CPLEX in the notes called “Intro_CPLEX.”

$$\max F = 5x_1 + 4x_2 + 3x_3$$

Subject to

$$2x_1 + 3x_2 + x_3 \leq 5$$
$$4x_1 + x_2 + 2x_3 \leq 11$$
$$3x_1 + 4x_2 + 2x_3 \leq 8$$
$$x_1 \geq 0, x_2 \geq 0, x_3 \geq 0$$

The dual problem can be written down by inspection.

$$\min G = 5\lambda_1 + 11\lambda_2 + 8\lambda_3$$

Subject to

$$2\lambda_1 + 4\lambda_2 + 3\lambda_3 \geq 5$$
$$3\lambda_1 + \lambda_2 + 4\lambda_3 \geq 4$$
$$\lambda_1 + 2\lambda_2 + 2\lambda_3 \geq 3$$
$$\lambda_1 \geq 0, \lambda_2 \geq 0, \lambda_3 \geq 0$$
We can use CPLEX to check. First, we solve the primal problem using the below code:

maximize
5 \cdot x_1 + 4 \cdot x_2 + 3 \cdot x_3
subject to
2 \cdot x_1 + 3 \cdot x_2 + x_3 \leq 5
4 \cdot x_1 + x_2 + 2 \cdot x_3 \leq 11
3 \cdot x_1 + 4 \cdot x_2 + 2 \cdot x_3 \leq 8
x_1 \geq 0
x_2 \geq 0
x_3 \geq 0
end

The solution is \((x_1, x_2, x_3) = (2, 0, 1)\), \(F^* = 13\).
The dual variables are: \((\lambda_1, \lambda_2, \lambda_3) = (1, 0, 1)\)

Now, solve the dual problem using the below code:

minimize
5 \cdot y_1 + 11 \cdot y_2 + 8 \cdot y_3
subject to
2 \cdot y_1 + 4 \cdot y_2 + 3 \cdot y_3 \geq 5
3 \cdot y_1 + y_2 + 4 \cdot y_3 \geq 4
1 \cdot y_1 + 2 \cdot y_2 + 2 \cdot y_3 \geq 3
y_1 \geq 0
y_2 \geq 0
y_3 \geq 0
end

The solution is \((\lambda_1, \lambda_2, \lambda_3) = (1, 0, 1)\), \(G^* = 13\).
The dual variables are: \((x_1, x_2, x_3) = (2, 0, 1)\).
5.0 Viewing the primal-dual relationship

Another way to view the relationship between the primal and the dual is via use of the primal-dual table. Although this offers no new information relative to what we have already learned, you might find it helpful in remembering the structural aspects to the relationship.

Let’s consider the following generalized primal-dual problems.

\[
\begin{align*}
\text{max } F &= c_1x_1 + c_2x_2 + \ldots + c_nx_n \\
s.t. \\
a_{11}x_1 + a_{12}x_2 + \ldots + a_{1n}x_n &\leq b_1 \\
a_{21}x_1 + a_{22}x_2 + \ldots + a_{2n}x_n &\leq b_2 \\
\vdots & \quad \vdots \quad \vdots \\
a_{m1}x_1 + a_{m2}x_2 + \ldots + a_{mn}x_n &\leq b_m \\
x_1, x_2, \ldots, x_n &\geq 0
\end{align*}
\]

\[
\begin{align*}
\text{min } G &= b_1\lambda_1 + b_2\lambda_2 + \ldots + b_m\lambda_m \\
s.t. \\
a_{11}\lambda_1 + a_{21}\lambda_2 + \ldots + a_{m1}\lambda_m &\geq c_1 \\
a_{12}\lambda_1 + a_{22}\lambda_2 + \ldots + a_{m2}\lambda_m &\geq c_2 \\
\vdots & \quad \vdots \quad \vdots \\
a_{1n}\lambda_1 + a_{2n}\lambda_2 + \ldots + a_{mn}\lambda_m &\geq c_n \\
\lambda_1, \lambda_2, \ldots, \lambda_n &\geq 0
\end{align*}
\]

The primal-dual table is shown below.
For example, our previous example problem has a primal-dual table as shown below.
<table>
<thead>
<tr>
<th>Dual Problem</th>
<th>Coefficients of $\lambda_1$</th>
<th>Coefficients of $\lambda_2$</th>
<th>Coefficients of $\lambda_3$</th>
<th>Right side</th>
</tr>
</thead>
<tbody>
<tr>
<td>Primal Problem</td>
<td>Coefficients of $x_1$</td>
<td>$x_2$</td>
<td>$x_3$</td>
<td>$\leq 5$</td>
</tr>
<tr>
<td>$x_1$</td>
<td>2</td>
<td>3</td>
<td>1</td>
<td>$\leq 5$</td>
</tr>
<tr>
<td>$x_2$</td>
<td>4</td>
<td>1</td>
<td>2</td>
<td>$\leq 11$</td>
</tr>
<tr>
<td>$x_3$</td>
<td>3</td>
<td>4</td>
<td>2</td>
<td>$\leq 8$</td>
</tr>
<tr>
<td>Right side</td>
<td>$\forall$</td>
<td>$\forall$</td>
<td>$\forall$</td>
<td></td>
</tr>
<tr>
<td>$\leq 5$</td>
<td>5</td>
<td>4</td>
<td>3</td>
<td></td>
</tr>
</tbody>
</table>

Coefficients for dual objective function

Coefficients for primal objective function
6.0 The duality theorem

We have already been using this theorem, and so now we merely formalize it….

**Duality theorem:** If the primal problem has an optimal solution $x^*$, then the dual problem has an optimal solution $\lambda^*$ such that

\[ G(\lambda^*) = F(x^*) \]

The proof is given in [1, pp. 58-59].

The duality theorem raises an interesting question. What if the primal does not have an optimal solution? Then what happens in the dual?

To answer this, we must first consider what are the alternatives for finding an optimal solution to the primal? There are two:

1. The primal is unbounded.
2. The primal is infeasible.
7.0 Unbounded primal

We have already seen an example of an unbounded primal, illustrated by the problem below and its corresponding feasible region.

\[ \text{max } F = 3x_1 + 5x_2 \]
\[ \text{s.t. } x_1 \leq 4 \]
\[ 4x_1 \leq 12 \]
\[ 3x_1 \leq 18 \]
\[ x_1 \geq 0, x_2 \geq 0 \]
Recall that the objective function for the dual establishes an upper bound for the objective function of the primal, i.e.,

\[ G(\lambda) \geq F(x) \]

for any sets of feasible solutions \( \lambda \) and \( x \).

If \( F(x) \) is unbounded, then the only possibility for \( G(\lambda) \) is that it must be infeasible.

Let’s write down the dual of the above primal to see.

\[
\begin{align*}
\min \ G &= 4\lambda_1 + 12\lambda_2 + 18\lambda_3 \\
\text{s.t.} \\
\lambda_1 + 4\lambda_2 + 3\lambda_3 &\geq 3 \\
0\lambda_1 + 0\lambda_2 + 0\lambda_3 &\geq 5 \\
\lambda_1 &\geq 0, \lambda_2 \geq 0, \lambda_3 \geq 0
\end{align*}
\]

and we immediately see that the second constraint cannot be satisfied, and so the dual is infeasible.

Likewise, we can show that if the dual is unbounded, the primal must be infeasible.

However, it is not necessarily true that if the primal (or dual) is infeasible, that the dual (or primal) is unbounded. It is possible for an infeasible primal to have an infeasible dual and vice-versa, that is, both the primal and the dual may be both be infeasible. Reference [1, p. 60] provides such a case.