EE 303, Quiz 8, April 18, 2019, Dr. McCalley Closed book, closed notes, no calculator, 20 minutes

- 1. (30pts) A 2500 bus system has 500 generators; all of the generator buses are modeled in a power flow program with constant (known) terminal voltage.
 - a. How many type PV buses are there in the power flow model?
 - b. How many type PQ buses are there in the power flow model?
 - c. What is the minimum number of equations required to solve this problem?
 - d. How many bus voltage magnitudes are unknown in this problem?
 - e. How many bus voltage angles are unknown in this problem?

Answer:

a. 499 b. 2000 c. 4499 d. 2000 e. 2499

2. (40pts) Consider the following equations: $\underline{f}(\underline{x}) = \begin{bmatrix} f_1(\underline{x}) \\ f_2(\underline{x}) \end{bmatrix} = \begin{bmatrix} x_1^3 - x_2 \\ x_1 - x_2 \end{bmatrix}$. Using an initial

guess at the solution of $\underline{x}^{(0)} = \begin{bmatrix} x_1^{(0)} \\ x_2^{(0)} \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$, show one iteration of the Newton-Raphson

solution procedure. To get full credit on this problem, you must provide $\underline{J}, \underline{J}^{-1}, \underline{\Delta x}^{(0)}$, and $\underline{x}^{(1)}$.

$$\underline{f}(\underline{x}^{(0)}) = \begin{bmatrix} f_1(\underline{x}^{(0)}) \\ f_2(\underline{x}^{(0)}) \end{bmatrix} = \begin{bmatrix} 2^3 - 2 \\ 2 - 2 \end{bmatrix} = \begin{bmatrix} 6 \\ 0 \end{bmatrix}$$
$$\underline{J}(\underline{x}) = \begin{bmatrix} 3x_1^2 & -1 \\ 1 & -1 \end{bmatrix} \Longrightarrow \underbrace{J}(\underline{x}^{(0)}) = \begin{bmatrix} 12 & -1 \\ 1 & -1 \end{bmatrix} \Longrightarrow \underbrace{J}^{-1} = \begin{bmatrix} \frac{1}{11} & \frac{-1}{11} \\ \frac{1}{11} & \frac{-12}{11} \end{bmatrix}$$
$$\Delta \underline{x}^{(0)} = -\underline{J}^{-1} \underline{f}(\underline{x}^{(0)}) = -\begin{bmatrix} \frac{1}{11} & \frac{-1}{11} \\ \frac{1}{11} & \frac{-12}{11} \end{bmatrix} \begin{bmatrix} 6 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{-6}{11} \\ \frac{-6}{11} \end{bmatrix} \xrightarrow{\bullet} \underline{x}^{(1)} = \underline{x}^{(0)} + \Delta \underline{x}^{(0)} = \begin{bmatrix} 2 \\ 2 \end{bmatrix} + \begin{bmatrix} \frac{-6}{11} \\ \frac{-6}{11} \end{bmatrix} = \begin{bmatrix} \frac{16}{11} \\ \frac{16}{11} \end{bmatrix}$$

3. (30pts) For the following optimization problem, (*a*) express the Lagrangian function you would use to obtain a first solution of the problem; (*b*) If your answer to the problem expressed in *part a* was $(x_1, x_2)=(1.2, 0.6)$, what would you do next? (c) for the situation of part b, what is the value of the Lagrange multiplier (μ) corresponding to the inequality constraint?

min
$$f(x_1, x_2) = x_1^2 + x_2^2$$

subject to
 $h(x_1, x_2) = 2x_1 + x_2 = 3$
 $g(x_1, x_2) = x_2 \le 0.7$

Answer:

- a. $F(x_1, x_2, \lambda) = x_1^2 + x_2^2 \lambda(2x_1 + x_2 3)$
- b. Declare the solution to the overall problem to be the solution to the problem solved in part *a*.