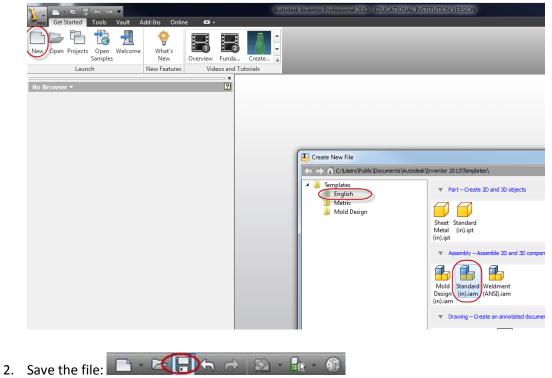
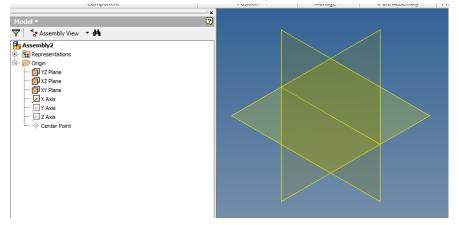
The Rack / Spur assembly

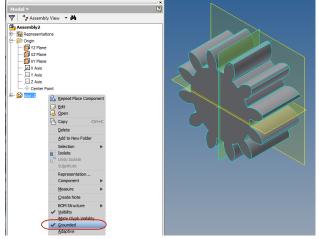
1. Create a new assembly: New | English | Standard (in).iam



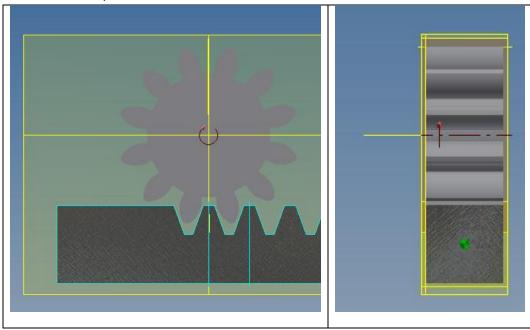
3. Inialize: Home View and Reference Visibility



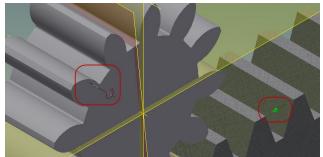
4. Place Component: Spur | Remove Grounded (uncheck)



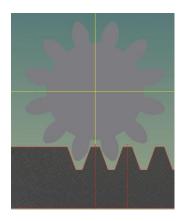
- 5. Constrain the spur Gear: It has to be free to rotate.
 - a. Mate the Gear axis with x-axis
 - b. Mate a face of the gear with the YZ plane
- 6. Place the component: Rack
- 7. Constrain the rack component
 - a. Mate the face of the rack with the YZ plane
 - b. Offset the top of the rack from the .45 (Flush Constraint)
- 8. Verify:
 - a. Position of components



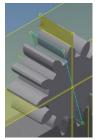
- b. Verify Degrees of freedom (Ribbon: View | Degrees of Freedom)
 - i. Gear should be able to rotate
 - ii. Rack should be free to translate



- 9. Set the starting position : Mate appropriate work planes Verify
 - a. Alignment (See Below)
 - b. Degrees of freedom (none displayed)



- 10. Angle Constraint
 - a. Suppress previous constraint (alignment)
 - b. Rotate the gear slightly
 - c. Create an angle constraint
 - i. Spur Gear: Select the visible reference plane
 - ii. Assembly: Select the XY plane



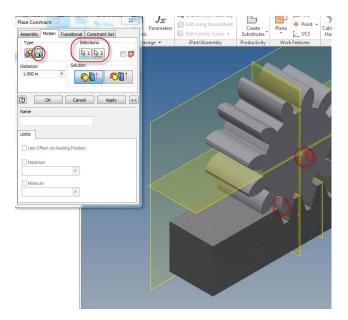
d. Set the starting angle to 0 degrees

- 11. Drive Constraint
 - a. Select: The Angle Constraint | Drive Constraint

| | E- Rack:1 | 🖄 Repeat Update |
|----|-----------------------------------|----------------------------|
| | 🕂 🔄 3rd Party | <u>D</u> elete |
| | - [=- View: | Isolate Components |
| | 🗐 🕀 🧰 Origin | Edit |
| | | |
| | Work Plane3 | Drive Constraint |
| | Work Plane3 | Drive Constraint |
| b. | Work Plane4 | Modify |
| b. | | Modify |
| b. | Select: Start=0 End =360 Forwa | Modify rd (and Reverse) |

12. Motion Constraint |Rotation-Translation

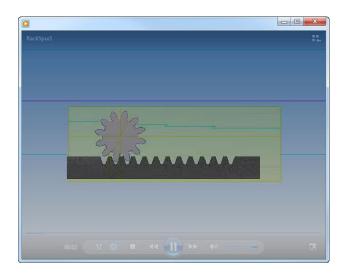
- a. Selection 1: Spur Gear axis
- b. Selection 2: Rack edge



- 13. Drive Constraint: Play again, notice the rack moves but timing is off
- 14. Edit the Motion Constraint: Change Distance to 3.1416 (Corresponds to the gear dia = 1in.)
- 15. Drive Constraint: Play again, notice the timing.
- 16. Drive Constraint: Select Collision Detection
 - a. Play (Gear stops at the end of the rack) Enter the current angle for the End Angle
 - b. Reverse: Adjust start angle determine minimum start angle

| Drive Constraint (-3.00 deg) | | | |
|------------------------------|------------------------|--|--|
| Start End | Pause Delay 0.000 s | | |
| | | | |
| | | | |
| | | | |
| Increment | Repetitions | | |
| amount of value | Start/End | | |
| total # of steps | Start/End/Start | | |
| 1.00 deg 🕨 | 2.000 ul | | |
| Avirate | | | |
| 10.000 ul ト | | | |
| | | | |

- 17. Record the final animation.
 - a. Repititions: Start/End/Start= 2
 - b. Select Record
 - c. Select: WMV Files (.wmv) | BroadBand | 640x 4809
 - d. Select Forward
- 18. Play the animation



Alternative Problem (Recommend Practice)

