Learning Measurement Matrices for Redundant Dictionaries

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Sparsity as a powerful instrument in signal processing is now commonplace. However, it is also well known that certain classes of signals do *not* admit a sparse expansion in an orthonormal basis (e.g., a mixture of spikes and sinuoids is non-sparse in either the canonical or Fourier basis). Therefore, it is typical to use an *overcomplete basis*, or a *redundant dictionary*, for representing such complicated signals. Mathematically, $\mathbf{x} \in \mathbb{R}^N$ is k-sparse in a dictionary $\mathbf{D} \in \mathbb{R}^{n \times N}$, where n < N, if $\mathbf{x} = \mathbf{D}\alpha$ where $\alpha \in \mathbb{R}^N$ contains only k nonzeros.

Compressive Sensing (CS) [1] encompasses the development of efficient techniques for sampling and reconstruction of sparse signals. A signal $\mathbf{x} \in \mathbb{R}^n$ may be sampled by inner products with m < n vectors; therefore, $\mathbf{y} = \mathbf{\Phi}\mathbf{x} = \mathbf{\Phi}\mathbf{D}\alpha$, where $\mathbf{\Phi} \in \mathbb{R}^{m \times n}$ is the *measurement matrix*. Here, the matrix $\mathbf{\Phi}\mathbf{D}$ is sometimes called the *holographic basis*. Signal reconstruction can be performed using a slew of algorithms; see, for example, [2]. It is generally accepted that the *mutual coherence* μ (or the maximum absolute off-diagonal entry of the Gram matrix) of the holographic basis plays an important role in reconstruction performance; smaller values of μ typically lead to better reconstruction.

An important consideration is the choice of measurement matrix Φ . The typical CS approach offers a very simple, *universal* solution: construct $\Phi \in \mathbb{R}^{m \times n}$ elementwise by *randomly* drawing from a Gaussian (or Bernoulli) probability distribution. Remarkably, if **x** is *k*-sparse, then with high probability, $m = \mathcal{O}(k \log n)$ samples suffice in order to ensure efficient, stable reconstruction of α (and consequently, **x**) from **y**; in other words, *m* needs only to be linear in the sparsity level *k* and logarithmic in the actual signal length *n*.

While randomized constructions of measurement matrices are agnostic to the dictionary **D** under consideration, the question remains whether one can do better, i.e., whether one can construct a hypothetical Φ with an even fewer number of rows *m* by leveraging the intrinsic structure of **D**. In this work, we answer this question in the affirmative. We develop an algorithmic framework for *learning* measurement matrices Φ that are well-tuned to the dictionary under consideration. Our framework can be viewed as a variant of *NuMax* [3], a new convex optimization framework for designing nearisometric linear embeddings of high-dimensional point clouds.

A brief sketch of our approach is as follows. Consider a sparsifying dictionary $\mathbf{D} = [\mathbf{d}_1, \ldots, \mathbf{d}_N]$ with unit-norm columns. We seek a matrix $\mathbf{\Phi} \in \mathbb{R}^{m \times n}$, with as few rows as possible, such that the mutual coherence of the holographic basis $\mathbf{\Phi}\mathbf{D}$ is at most a scalar parameter $\mu > 0$. To avoid numerical degeneracies, we also impose the constraints that the columns of $\mathbf{\Phi}\mathbf{D}$ themselves be approximately unit-norm. Define $\mathbf{P} = \mathbf{\Phi}^T \mathbf{\Phi}$ so that rank $(\mathbf{P}) = m$. Then, \mathbf{P} can be posed as the solution to the problem:

minimize rank(**P**) (1)
subject to
$$|\mathbf{d}_i^T \mathbf{P} \mathbf{d}_j| \le \mu, \quad i \ne j,$$

 $\mathbf{d}_i^T \mathbf{P} \mathbf{d}_i \ge 1 - \mu, \quad \mathbf{P} \succeq 0.$

Note that (1) consists of inequality constraints that are *linear* in the



Fig. 1. CS recovery performance for random projections versus the matrix produced by our proposed algorithm (NuMax-Dict). NuMax-Dict far outperforms random Gaussian projections in terms of recovered signal SNR.

optimization variable **P**. Since rank minimization is NP-hard, we relax (1) to obtain a *nuclear norm* minimization problem, subject to linear inequality constraints, over the cone of positive semidefinite (PSD) matrices. This problem is convex and can be solved very efficiently, for example, using a simple modification of Algorithm 1 in [3]. We dub this modified algorithm *NuMax-Dict*. A simple matrix square root of the optimal \mathbf{P}^* reveals the desired $\boldsymbol{\Phi}$, modulo an orthogonal transformation. The choice of the parameter μ is important; larger values of μ result in optimal matrices \mathbf{P}^* of smaller rank, and consequently, a smaller number m of rows in $\boldsymbol{\Phi}$.

Figure 1 illustrates the benefits of CS recovery using our approach. We consider a generic dictionary D populated with i.i.d. Gaussian entries with parameters n = 64, N = 128 and solve the nuclear norm relaxation of (1) using NuMax-Dict for a given parameter μ . We generate 500 coefficient vectors α with k = 5 nonzeros and random amplitudes, form signals $x = D\alpha$, and obtain m compressive samples using both the learned measurement matrix Φ as well as a random Gaussian measurement matrix with m rows. We reconstruct the signals using orthogonal matching pursuit (OMP) [2] and record the error in signal recovery in terms of SNR. We repeat this experiment for different values of input μ . As illustrated in Fig. 1, the learned matrix using our proposed NuMax-Dict algorithm outperforms conventional random sampling over a wide range of measurement regimes. Our proposed formulation (1) can be adapted to other notions of matrix coherence, such as average coherence. Further, it is applicable to a number of practical settings, such as the compressive acquisition of images that are sparse in large-scale redundant dictionaries. We explore these avenues further in the full version of this work.

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