A Probability Review

Outline:

• A probability review.

Shorthand notation: RV stands for random variable.

A Probability Review

Reading:

• Go over handouts 2–5 in EE 420x notes.

Basic probability rules:

(1)
$$\Pr{\Omega} = 1$$
, $\Pr{\emptyset} = 0$, $0 \le \Pr{A} \le 1$;
 $\Pr{\bigcup_{i=1}^{\infty} A_i} = \sum_{i=1}^{\infty} \Pr{A_i}$ if $A_i \cap A_j = \emptyset$ for all $i \ne j$;
 A_i and A_j disjoint

(2) $\Pr{A \cup B} = \Pr{A} + \Pr{B} - \Pr{A \cap B}, \ \Pr{A^c} = 1 - \Pr{A};$

(3) If $A \perp B$, then $\Pr\{A \cap B\} = \Pr\{A\} \cdot \Pr\{B\}$;

(4)

$$\Pr\{A \mid B\} = \frac{\Pr\{A \cap B\}}{\Pr\{B\}} \quad \text{(conditional probability)}$$

or

$$\Pr\{A \cap B\} = \Pr\{A \mid B\} \cdot \Pr\{B\} \quad \text{(chain rule)};$$

 $\Pr\{A\} = \Pr\{A \mid B_1\} \Pr\{B_1\} + \dots + \Pr\{A \mid B_n\} \Pr\{B_n\}$

if B_1, B_2, \ldots, B_n form a *partition* of the full space Ω ;

(6) Bayes' rule:

$$\Pr\{A \mid B\} = \frac{\Pr\{B \mid A\} \Pr\{A\}}{\Pr\{B\}}.$$

Reminder: Independence, Correlation and Covariance

For simplicity, we state all the definitions for pdfs; the corresponding definitions for pmfs are analogous.

Two random variables X and Y are *independent* if

$$f_{X,Y}(x,y) = f_X(x) \cdot f_Y(y).$$

Correlation between real-valued random variables X and Y:

$$E_{X,Y}\{XY\} = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} x \, y \, f_{X,Y}(x,y) \, dx \, dy.$$

Covariance between real-valued random variables X and Y:

$$\operatorname{cov}_{X,Y}(X,Y) = \operatorname{E}_{X,Y}\{(X-\mu_X)(Y-\mu_Y)\}$$
$$= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} (x-\mu_X)(y-\mu_Y) f_{X,Y}(x,y) \, dx \, dy$$

where

$$\mu_X = \operatorname{E}_X(X) = \int_{-\infty}^{+\infty} x f_X(x) \, dx$$
$$\mu_Y = \operatorname{E}_Y(Y) = \int_{-\infty}^{+\infty} y f_Y(y) \, dy.$$

Uncorrelated random variables: Random variables X and Y are *uncorrelated* if

$$c_{X,Y} = \operatorname{cov}_{X,Y}(X,Y) = 0.$$
 (1)

If X and Y are real-valued RVs, then (1) can be written as

$$\operatorname{E}_{X,Y}\{XY\} = \operatorname{E}_X\{X\}\operatorname{E}_Y\{Y\}.$$

Mean Vector and Covariance Matrix:

Consider a random vector

$$oldsymbol{X} = \left[egin{array}{c} X_1 \ X_2 \ dots \ X_N \end{array}
ight]$$

The mean of this random vector is defined as

$$\boldsymbol{\mu}_{\boldsymbol{X}} = \begin{bmatrix} \mu_{1} \\ \mu_{2} \\ \vdots \\ \mu_{N} \end{bmatrix} = \mathbf{E}_{\boldsymbol{X}} \{ \boldsymbol{X} \} = \begin{bmatrix} \mathbf{E}_{X_{1}}[X_{1}] \\ \mathbf{E}_{X_{2}}[X_{2}] \\ \vdots \\ \mathbf{E}_{X_{N}}[X_{N}] \end{bmatrix}$$

Denote the *covariance* between X_i and X_k , $\operatorname{cov}_{X_i,X_k}(X_i,X_k)$, by $c_{i,k}$; hence, the *variance* of X_i is $c_{i,i} = \operatorname{cov}_{X_i,X_k}(X_i,X_i) = \operatorname{var}_{X_i}(X_i) = \sigma_{X_i}^2$. The *covariance matrix* of X is defined as more notation

$$C_{\mathbf{X}} = \begin{bmatrix} c_{1,1} & c_{1,2} & \cdots & \cdots & c_{1,N} \\ c_{2,1} & c_{2,2} & \cdots & \cdots & c_{2,N} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ c_{N,1} & c_{N,2} & \cdots & \cdots & c_{N,N} \end{bmatrix}.$$

The above definitions apply to both real and complex vectors X.

Covariance matrix of a real-valued random vector X:

$$C_{\boldsymbol{X}} = E_{\boldsymbol{X}}\{(\boldsymbol{X} - E_{\boldsymbol{X}}[\boldsymbol{X}]) (\boldsymbol{X} - E_{\boldsymbol{X}}[\boldsymbol{X}])^{T}\}$$

= $E_{\boldsymbol{X}}[\boldsymbol{X} \boldsymbol{X}^{T}] - E_{\boldsymbol{X}}[\boldsymbol{X}] (E_{\boldsymbol{X}}[\boldsymbol{X}])^{T}.$

For real-valued X, $c_{i,k} = c_{k,i}$ and, therefore, C_X is a symmetric matrix.

Linear Transform of Random Vectors

Linear Transform. For real-valued $\boldsymbol{Y}, \boldsymbol{X}, A$,

$$\boldsymbol{Y} = g(\boldsymbol{X}) = A \, \boldsymbol{X}.$$

Mean Vector:

$$\boldsymbol{\mu}_{\boldsymbol{Y}} = \mathbf{E}_{\boldsymbol{X}} \{ A \, \boldsymbol{X} \} = A \, \boldsymbol{\mu}_{\boldsymbol{X}}. \tag{2}$$

Covariance Matrix:

$$C_{Y} = E_{Y} \{ Y Y^{T} \} - \mu_{Y} \mu_{Y}^{T}$$

$$= E_{X} \{ A X X^{T} A^{T} \} - A \mu_{X} \mu_{X}^{T} A^{T}$$

$$= A \left(\underbrace{E_{X} \{ X X^{T} \} - \mu_{X} \mu_{X}^{T} }_{C_{X}} \right) A^{T}$$

$$= A C_{X} A^{T}.$$
(3)

Reminder: Iterated Expectations

In general, we can find $E_{X,Y}[g(X,Y)]$ using *iterated expectations*:

$$E_{X,Y}[g(X,Y)] = E_Y\{E_{X|Y}[g(X,Y)|Y]\}$$
(4)

where $E_{X|Y}$ denotes the expectation with respect to $f_{X|Y}(x|y)$ and E_Y denotes the expectation with respect to $f_Y(y)$.

Proof.

$$\begin{split} & E_{Y} \{ E_{X|Y}[g(X,Y)|Y] \} = \int_{-\infty}^{+\infty} E_{X|Y}[g(X,Y)|y] f_{Y}(y) \, dy \\ & = \int_{-\infty}^{+\infty} \left(\int_{-\infty}^{+\infty} g(x,y) f_{X|Y}(x|y) \, dx \right) f_{Y}(y) \, dy \\ & = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} g(x,y) f_{X|Y}(x|y) f_{Y}(y) \, dx \, dy \\ & = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} g(x,y) \, f_{X,Y}(x,y) \, dx \, dy \\ & = E_{X,Y}[g(X,Y)]. \end{split}$$

Reminder: Law of Conditional Variances

Define the conditional variance of X given Y = y to be the variance of X with respect to $f_{X \mid Y}(x \mid y)$, i.e.

$$\operatorname{var}_{X \mid Y}(X \mid Y = y) = \operatorname{E}_{X \mid Y}\left[(X - \operatorname{E}_{X \mid Y}[X \mid y])^2 \mid y \right]$$
$$= \operatorname{E}_{X \mid Y}[X^2 \mid y] - (\operatorname{E}_{X \mid Y}[X \mid y])^2.$$

The random variable $\operatorname{var}_{X \mid Y}(X \mid Y)$ is a function of Y only, taking values $\operatorname{var}(X \mid Y = y)$. Its expected value with respect to Y is

$$E_{Y} \{ \operatorname{var}_{X \mid Y}(X \mid Y) \} = E_{Y} \{ E_{X \mid Y}[X^{2} \mid Y] - (E_{X \mid Y}[X \mid Y])^{2} \}$$

$$\stackrel{\text{iterated exp.}}{=} E_{X,Y}[X^{2}] - E_{Y} \{ (E_{X \mid Y}[X \mid Y])^{2} \}$$

$$= E_{X}[X^{2}] - E_{Y} \{ (E_{X \mid Y}[X \mid Y])^{2} \}.$$

Since $E_{X|Y}[X|Y]$ is a random variable (and a function of Y only), it has variance:

$$\operatorname{var}_{Y} \{ \operatorname{E}_{X|Y}[X \mid Y] \} = \operatorname{E}_{Y} \{ (\operatorname{E}_{X|Y}[X \mid Y])^{2} \} - (\operatorname{E}_{Y} \{ \operatorname{E}_{X|Y}[X \mid Y] \})^{2} \\ \stackrel{\text{iterated exp.}}{=} \quad \operatorname{E}_{Y} \{ (\operatorname{E}_{X|Y}[X \mid Y])^{2} \} - (\operatorname{E}_{X,Y}[X])^{2} \\ = \quad \operatorname{E}_{Y} \{ \operatorname{E}_{X|Y}[X \mid Y]^{2} \} - (\operatorname{E}_{X}[X])^{2}.$$

Adding the above two expressions yields the *law of conditional variances*:

 $E_{Y}\{\operatorname{var}_{X|Y}(X|Y)\} + \operatorname{var}_{Y}\{E_{X|Y}[X|Y]\} = \operatorname{var}_{X}(X).$ (5)

Note: (4) and (5) hold for both real- and complex-valued random variables.

Useful Expectation and Covariance Identities for Real-valued Random Variables and Vectors

where a, b, and c are constants and X and Y are random variables. A vector/matrix version of the above identities:

$$E_{\boldsymbol{X},\boldsymbol{Y}}[A\,\boldsymbol{X} + B\,\boldsymbol{Y} + \boldsymbol{c}] = A E_{\boldsymbol{X}}[\boldsymbol{X}] + B E_{\boldsymbol{Y}}[\boldsymbol{Y}] + \boldsymbol{c}$$
$$\operatorname{cov}_{\boldsymbol{X},\boldsymbol{Y}}(A\,\boldsymbol{X} + B\,\boldsymbol{Y} + \boldsymbol{c}) = A \operatorname{cov}_{\boldsymbol{X}}(\boldsymbol{X}) A^{T} + B \operatorname{cov}_{\boldsymbol{Y}}(\boldsymbol{Y}) B^{T}$$
$$+ A \operatorname{cov}_{\boldsymbol{X},\boldsymbol{Y}}(\boldsymbol{X},\boldsymbol{Y}) B^{T} + B \operatorname{cov}_{\boldsymbol{X},\boldsymbol{Y}}(\boldsymbol{Y},\boldsymbol{X}) A^{T}$$

where "T" denotes a transpose and

$$\operatorname{cov}_{\boldsymbol{X},\boldsymbol{Y}}(\boldsymbol{X},\boldsymbol{Y}) = \operatorname{E}_{\boldsymbol{X},\boldsymbol{Y}}\{(\boldsymbol{X} - \operatorname{E}_{\boldsymbol{X}}[\boldsymbol{X}])(\boldsymbol{Y} - \operatorname{E}_{\boldsymbol{Y}}[\boldsymbol{Y}])^T\}.$$

Useful properties of crosscovariance matrices:

$$\operatorname{cov}_{\boldsymbol{X},\boldsymbol{Y},\boldsymbol{Z}}(\boldsymbol{X},\boldsymbol{Y}+\boldsymbol{Z}) = \operatorname{cov}_{\boldsymbol{X},\boldsymbol{Y}}(\boldsymbol{X},\boldsymbol{Y}) + \operatorname{cov}_{\boldsymbol{X},\boldsymbol{Z}}(\boldsymbol{X},\boldsymbol{Z}).$$

$$\operatorname{cov}_{\mathbf{Y},\mathbf{X}}(\mathbf{Y},\mathbf{X}) = [\operatorname{cov}_{\mathbf{X},\mathbf{Y}}(\mathbf{X},\mathbf{Y})]^{T}.$$

$$\operatorname{cov}_{\mathbf{X}}(\mathbf{X}) = \operatorname{cov}_{\mathbf{X}}(\mathbf{X},\mathbf{X})$$

$$\operatorname{var}_{X}(X) = \operatorname{cov}_{X}(X,X).$$

$$\operatorname{cov}_{\boldsymbol{X},\boldsymbol{Y}}(A\,\boldsymbol{X}+\boldsymbol{b},P\,\boldsymbol{Y}+\boldsymbol{q}) = A\operatorname{cov}_{\boldsymbol{X},\boldsymbol{Y}}(\boldsymbol{X},\boldsymbol{Y})P^{T}.$$

(To refresh memory about covariance and its properties, see p. 12 of handout 5 in EE 420x notes. For random vectors, see handout 7 in EE 420x notes, particularly pp. 1-15.)

Useful theorems:

(1) (handout 5 in EE 420x notes)

$$\begin{split} & \mathbf{E}_X(X) = \mathbf{E}_Y[\mathbf{E}_{X \mid Y}(X \mid Y)] \quad \text{shown on p. 8} \\ & \mathbf{E}_{X \mid Y}[g(X) \cdot h(Y) \mid y] = h(y) \cdot \mathbf{E}_{X \mid Y}[g(X) \mid y] \\ & \mathbf{E}_{X,Y}[g(X) \cdot h(Y)] = \mathbf{E}_Y\{h(Y) \cdot \mathbf{E}_{X \mid Y}[g(X) \mid Y]\}. \end{split}$$

The vector version of (1) is the same — just put bold letters.

$$\operatorname{var}_{X}(X) = \operatorname{E}_{Y}[\operatorname{var}_{X \mid Y}(X \mid Y)] + \operatorname{var}_{Y}(\operatorname{E}_{X \mid Y}[X \mid Y]);$$

and the vector/matrix version is

$$\begin{split} \underbrace{\operatorname{cov}_{\boldsymbol{X}}(\boldsymbol{X})}_{\operatorname{variance/covariance}} &= \operatorname{E}_{\boldsymbol{Y}}[\operatorname{cov}_{\boldsymbol{X} \mid \boldsymbol{Y}}(\boldsymbol{X} \mid \boldsymbol{Y})] \\ \text{variance/covariance} \\ & \operatorname{matrix of} \boldsymbol{X} \\ & + \operatorname{cov}_{\boldsymbol{Y}}(\operatorname{E}_{\boldsymbol{X} \mid \boldsymbol{Y}}[\boldsymbol{X} \mid \boldsymbol{Y}]) \quad \text{shown on p. .} \end{split}$$

(3) Generalized law of conditional variances:

$$\operatorname{cov}_{X,Y}(X,Y) = \operatorname{E}_{Z}[\operatorname{cov}_{X,Y\mid Z}(X,Y\mid Z)] + \operatorname{cov}_{Z}(\operatorname{E}_{X\mid Z}[X\mid Z], \operatorname{E}_{Y\mid Z}[Y\mid Z]).$$

(4) Transformation:

$$\mathbf{Y} = \mathbf{g}(\mathbf{X}) \qquad \stackrel{\text{one-to-one}}{\iff} \qquad \begin{array}{c} Y_1 = g_1(X_1, \dots, X_n) \\ \vdots \\ Y_n = g_n(X_1, \dots, X_n) \end{array}$$

then

$$f_Y(\boldsymbol{y}) = f_X(h_1(y_1), \dots, h_n(y_n)) \cdot |J|$$

where $h(\cdot)$ is the unique inverse of $g(\cdot)$ and

$$J = \left| \frac{\partial \boldsymbol{x}}{\partial \boldsymbol{y}^T} \right| = \left| \begin{array}{ccc} \frac{\partial x_1}{\partial y_1} & \cdots & \frac{\partial x_1}{\partial y_n} \\ \vdots & \vdots & \vdots \\ \frac{\partial x_n}{\partial y_1} & \cdots & \frac{\partial x_n}{\partial y_n} \end{array} \right|$$

Print and read the handout **PROBABILITY DISTRIBUTIONS** from the Course readings section on **WebCT**. Bring it with you to the midterm exams.

Scalar Gaussian random variables:

$$f_X(x) = \frac{1}{\sqrt{2 \pi \sigma_X^2}} \exp\left[-\frac{(x-\mu_X)^2}{2 \sigma_X^2}\right].$$

Definition. Two real-valued RVs X and Y are jointly Gaussian if their joint pdf is of the form

$$f_{X,Y}(x,y) = \frac{1}{2\pi\sigma_X\sigma_Y\sqrt{1-\rho_{X,Y}^2}} \\ \cdot \exp\left\{-\frac{1}{2\left(1-\rho_{X,Y}^2\right)} \cdot \left[\frac{(x-\mu_X)^2}{\sigma_X^2} + \frac{(y-\mu_Y)^2}{\sigma_Y^2} -2\rho_{X,Y}\frac{(x-\mu_X)\left(y-\mu_Y\right)}{\sigma_X\sigma_Y}\right]\right\}.$$
(6)

This pdf is parameterized by $\mu_X, \mu_Y, \sigma_X^2, \sigma_Y^2$, and $\rho_{X,Y}$. Here, $\sigma_X = \sqrt{\sigma_X^2}$ and $\sigma_Y = \sqrt{\sigma_Y^2}$.

Note: We will soon define a more general multivariate Gaussian pdf.

If X and Y are jointly Gaussian, contours of equal joint pdf are ellipses defined by the quadratic equation

$$\frac{(x-\mu_X)^2}{\sigma_X^2} + \frac{(y-\mu_Y)^2}{\sigma_Y^2} - 2\,\rho_{X,Y}\frac{(x-\mu_X)\,(y-\mu_Y)}{\sigma_X\sigma_Y} = \text{const} \ge 0.$$

Examples: In the following examples, we plot contours of the joint pdf $f_{X,Y}(x,y)$ for zero-mean jointly Gaussian RVs for various values of σ_X, σ_Y , and $\rho_{X,Y}$.



EE 527, Detection and Estimation Theory, # 0b











If X and Y are jointly Gaussian, the conditional pdfs are Gaussian, e.g.

$$X | \{Y = y\} \sim \mathcal{N}\left(\rho_{X,Y} \cdot \sigma_X \cdot \frac{y - \mathrm{E}_Y[Y]}{\sigma_Y} + \mathrm{E}_X[X], (1 - \rho_{X,Y}^2) \cdot \sigma_X^2\right).$$
(7)

If X and Y are jointly Gaussian and uncorrelated, i.e. $\rho_{X,Y} = 0$, they are also independent.

Gaussian Random Vectors

Real-valued Gaussian random vectors:

$$f_{\mathbf{X}}(\mathbf{x}) = \frac{1}{(2\pi)^{N/2} |C_{\mathbf{X}}|^{1/2}} \exp\left[-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_{\mathbf{X}})^T C_{\mathbf{X}}^{-1} (\mathbf{x} - \boldsymbol{\mu}_{\mathbf{X}})\right].$$

Complex-valued Gaussian random vectors:

$$f_{\boldsymbol{Z}}(\boldsymbol{z}) = \frac{1}{\pi^{N} |C_{\boldsymbol{Z}}|} \exp\left[-\left(\boldsymbol{z} - \boldsymbol{\mu}_{\boldsymbol{Z}}\right)^{H} C_{\boldsymbol{Z}}^{-1} \left(\boldsymbol{z} - \boldsymbol{\mu}_{\boldsymbol{Z}}\right)\right].$$

Notation for *real-* and *complex-valued* Gaussian random vectors:

$$oldsymbol{X} \sim \mathcal{N}_{\mathrm{r}}(oldsymbol{\mu}_{oldsymbol{X}}, C_{oldsymbol{X}})$$
 [or simply $\mathcal{N}(oldsymbol{\mu}_{oldsymbol{X}}, C_{oldsymbol{X}})$] real $oldsymbol{X} \sim \mathcal{N}_{\mathrm{c}}(oldsymbol{\mu}_{oldsymbol{X}}, C_{oldsymbol{X}})$ complex.

An *affine transform* of a Gaussian vector is also a Gaussian random vector, i.e. if

$$Y = A X + b$$

then

$$\begin{split} \boldsymbol{Y} &\sim \mathcal{N}_{\mathrm{r}}(A \, \boldsymbol{\mu}_{\boldsymbol{X}} + \boldsymbol{b}, A \, C_{\boldsymbol{X}} \, A^{T}) & \text{real} \\ \boldsymbol{Y} &\sim \mathcal{N}_{\mathrm{c}}(A \, \boldsymbol{\mu}_{\boldsymbol{X}} + \boldsymbol{b}, A \, C_{\boldsymbol{X}} \, A^{H}) & \text{complex.} \end{split}$$

The Gaussian random vector $\boldsymbol{W} \sim \mathcal{N}_{r}(\boldsymbol{0}, \sigma^{2} I_{n})$ (where I_{n} denotes the identity matrix of size n) is called *white*; pdf contours of a white Gaussian random vector are spheres centered at the origin. Suppose that $W[n], n = 0, 1, \ldots, N - 1$ are independent, identically distributed (i.i.d.) zeromean univariate Gaussian $\mathcal{N}(0, \sigma^{2})$. Then, for $\boldsymbol{W} = [W[0], W[1], \ldots, W[N-1]]^{T}$,

$$f_{\boldsymbol{W}}(\boldsymbol{w}) = \mathcal{N}(\boldsymbol{w} \mid \boldsymbol{0}, \sigma^2 I).$$

Suppose now that, for these W[n],

$$Y[n] = \theta + W[n]$$

where θ is a constant. What is the joint pdf of $Y[0], Y[1], \ldots$, and Y[N-1]? This pdf is the pdf of the vector $\mathbf{Y} = [Y[0], Y[1], \ldots, Y[N-1]]^T$:

 $Y = 1 \theta + W$

where $\mathbf{1}$ is an $N \times 1$ vector of ones. Now,

$$f_{\mathbf{Y}}(\mathbf{y}) = \mathcal{N}(\mathbf{y} \mid \mathbf{1}\,\theta, \sigma^2 I).$$

Since θ is a constant,

$$f_{\boldsymbol{Y}}(\boldsymbol{y}) = f_{\boldsymbol{Y} \mid \theta}(\boldsymbol{y} \mid \theta).$$

Gaussian Random Vectors

A real-valued random vector $\boldsymbol{X} = [X_1, X_2, \dots, X_n]^T$ with

- mean μ and
- covariance matrix Σ with determinant $|\Sigma| > 0$ (i.e. Σ is positive definite)

is a *Gaussian random vector* (or X_1, X_2, \ldots, X_n are *jointly Gaussian RVs*) if and only if its joint pdf is

$$f_{\boldsymbol{X}}(\boldsymbol{x}) = \frac{1}{|2\pi\Sigma|^{1/2}} \exp[-\frac{1}{2} (\boldsymbol{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\boldsymbol{x} - \boldsymbol{\mu})].$$
(8)

Verify that, for n = 2, this joint pdf reduces to the two-dimensional pdf in (6).

Notation: We use $X \sim \mathcal{N}(\mu, \Sigma)$ to denote a Gaussian random vector. Since Σ is positive definite, Σ^{-1} is also positive definite and, for $x \neq \mu$,

$$(\boldsymbol{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\boldsymbol{x} - \boldsymbol{\mu}) > 0$$

which means that the contours of the multivariate Gaussian pdf in (8) are ellipsoids.

The Gaussian random vector $X \sim \mathcal{N}(\mathbf{0}, \sigma^2 I_n)$ (where I_n denotes the identity matrix of size n) is called *white* — contours of the pdf of a white Gaussian random vector are spheres centered at the origin.

Properties of Real-valued Gaussian Random Vectors

Property 1: For a Gaussian random vector, "uncorrelation" implies independence.

This is easy to verify by setting $\Sigma_{i,j} = 0$ for all $i \neq j$ in the joint pdf, then Σ becomes diagonal and so does Σ^{-1} ; then, the joint pdf reduces to the product of marginal pdfs $f_{X_i}(x_i) = \mathcal{N}(\mu_i, \Sigma_{i,i}) = \mathcal{N}(\mu_i, \sigma_{X_i}^2)$. Clearly, this property holds for blocks of RVs (subvectors) as well.

Property 2: A linear transform of a Gaussian random vector $X \sim \mathcal{N}(\mu_X, \Sigma_X)$ yields a Gaussian random vector:

$$\boldsymbol{Y} = A \, \boldsymbol{X} \sim \mathcal{N}(A \, \boldsymbol{\mu}_{\boldsymbol{X}}, A \, \boldsymbol{\Sigma}_{\boldsymbol{X}} \, A^T).$$

It is easy to show that $E_{Y}[Y] = A \mu_{X}$ and $cov_{Y}(Y) = \Sigma_{Y} = A \Sigma_{X} A^{T}$. So

$$\operatorname{E}_{\boldsymbol{Y}}[\boldsymbol{Y}] = \operatorname{E}_{\boldsymbol{X}}[A \boldsymbol{X}] = A \operatorname{E}_{\boldsymbol{X}}[\boldsymbol{X}] = A \boldsymbol{\mu}_{\boldsymbol{X}}$$

and

$$\begin{split} \varSigma_{\mathbf{Y}} &= \operatorname{E}_{\mathbf{Y}}[(\mathbf{Y} - \operatorname{E}_{\mathbf{Y}}[\mathbf{Y}]) (\mathbf{Y} - \operatorname{E}_{\mathbf{Y}}[\mathbf{Y}])^{T}] \\ &= \operatorname{E}_{\mathbf{X}}[(A \, \mathbf{X} - A \, \boldsymbol{\mu}_{\mathbf{X}}) (A \, \mathbf{X} - A \, \boldsymbol{\mu}_{\mathbf{X}})^{T}] \\ &= A \operatorname{E}_{\mathbf{X}}[(\mathbf{X} - \boldsymbol{\mu}_{\mathbf{X}}) (\mathbf{X} - \boldsymbol{\mu}_{\mathbf{X}})^{T}] A^{T} = A \, \varSigma_{\mathbf{X}} A^{T}. \end{split}$$

Of course, if we use the definition of a Gaussian random vector in (8), we cannot yet claim that Y is a Gaussian random vector. (For a different definition of a Gaussian random vector, we would be done right here.)

Proof. We need to verify that the joint pdf of Y indeed has the right form. Here, we decide to take the equivalent (easier) task and verify that the *characteristic function* of Y has the right form.

Definition. Suppose $X \sim f_X(X)$. Then the characteristic function of X is given by

$$\Phi_{\boldsymbol{X}}(\boldsymbol{\omega}) = \mathrm{E}_{\boldsymbol{X}}[\exp(j\,\boldsymbol{\omega}^T\,\boldsymbol{X})]$$

where $\boldsymbol{\omega}$ is an *n*-dimensional real-valued vector and $j = \sqrt{-1}$.

Thus

$$\Phi_{\boldsymbol{X}}(\boldsymbol{\omega}) = \int_{-\infty}^{+\infty} \cdots \int_{-\infty}^{+\infty} f_{\boldsymbol{X}}(\boldsymbol{x}) \exp(j \, \boldsymbol{\omega}^T \, \boldsymbol{x}) \, d\boldsymbol{x}$$

proportional to the inverse multi-dimensional Fourier transform of $f_X(x)$; therefore, we can find $f_X(x)$ by taking the Fourier transform (with the appropriate proportionality factor):

$$f_{\mathbf{X}}(\mathbf{x}) = \frac{1}{(2\pi)^n} \int_{-\infty}^{+\infty} \cdots \int_{-\infty}^{+\infty} \Phi_{\mathbf{X}}(\boldsymbol{\omega}) \exp(-j\,\boldsymbol{\omega}^T\,\mathbf{x})\,d\mathbf{x}$$

Example: The characteristic function for $X \sim \mathcal{N}(\mu, \sigma^2)$ is given by

$$\Phi_X(\omega) = \exp(-\frac{1}{2}\,\omega^2\,\sigma^2 + j\,\mu\,\omega) \tag{9}$$

and for a Gaussian random vector $oldsymbol{Z}\sim\mathcal{N}(oldsymbol{\mu},\varSigma)$,

$$\Phi_{\boldsymbol{Z}}(\boldsymbol{\omega}) = \exp(-\frac{1}{2}\,\boldsymbol{\omega}^T\,\boldsymbol{\Sigma}\boldsymbol{\omega} + j\,\boldsymbol{\omega}^T\,\boldsymbol{\mu}). \tag{10}$$

Now, go back to our proof: the characteristic function of $oldsymbol{Y}=Aoldsymbol{X}$ is

$$\Phi_{\mathbf{Y}}(\boldsymbol{\omega}) = \operatorname{E}_{\mathbf{Y}}[\exp(j\,\boldsymbol{\omega}^{T}\,\mathbf{Y})]$$

=
$$\operatorname{E}_{\mathbf{X}}[\exp(j\,\boldsymbol{\omega}^{T}\,A\,\mathbf{X})]$$

=
$$\exp(-\frac{1}{2}\,\boldsymbol{\omega}^{T}\,A\,\boldsymbol{\Sigma}_{\mathbf{X}}\,A^{T}\,\boldsymbol{\omega} + j\,\boldsymbol{\omega}^{T}\,A\,\boldsymbol{\mu}_{\mathbf{X}}).$$

Thus

$$\boldsymbol{Y} = A \, \boldsymbol{X} \sim \mathcal{N}(A \, \boldsymbol{\mu}_{\boldsymbol{X}}, A \boldsymbol{\Sigma}_{\boldsymbol{X}} A^T).$$

Example: Let

$$\mathbf{X} \sim \mathcal{N}\left(\mathbf{0}, \begin{bmatrix} 2 & 1\\ 1 & 3 \end{bmatrix}\right)$$

Find the joint pdf of

$$\mathbf{Y} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \mathbf{X}$$

Solution: From Property 2, we conclude that

$$\mathbf{Y} \sim \mathcal{N}\left(\mathbf{0}, \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}\right) = \mathcal{N}\left(\mathbf{0}, \begin{bmatrix} 7 & 3 \\ 3 & 2 \end{bmatrix}\right)$$

Property 3: Marginals of a Gaussian random vector are Gaussian, i.e. if X is a Gaussian random vector, then, for any $\{i_1, i_2, \dots, i_k\} \subset \{1, 2, \dots, n\}$,

$$\boldsymbol{Y} = \begin{bmatrix} X_{i_1} \\ X_{i_2} \\ \vdots \\ X_{i_k} \end{bmatrix}$$

is a Gaussian random vector. To show this, we use Property 2. Here is an example with n = 3 and $\mathbf{Y} = \begin{bmatrix} X_1 \\ X_3 \end{bmatrix}$. We set

$$\boldsymbol{Y} = \left[\begin{array}{rrr} 1 & 0 & 0 \\ 0 & 0 & 1 \end{array} \right] \left[\begin{array}{c} X_1 \\ X_2 \\ X_3 \end{array} \right]$$

thus

$$\mathbf{Y} \sim \mathcal{N}\left(\begin{bmatrix} \mu_1 \\ \mu_3 \end{bmatrix}, \begin{bmatrix} \Sigma_{1,1} & \Sigma_{1,3} \\ \Sigma_{3,1} & \Sigma_{3,3} \end{bmatrix} \right).$$

Here
$$\mathbf{E}_{\mathbf{X}} \left\{ \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} \right\} = \begin{bmatrix} \mu_1 \\ \mu_2 \\ \mu_3 \end{bmatrix}$$

and

and

$$\operatorname{cov}_{\boldsymbol{X}}\left\{ \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} \right\} = \begin{bmatrix} \Sigma_{1,1} & \Sigma_{1,2} & \Sigma_{1,3} \\ \Sigma_{2,1} & \Sigma_{2,2} & \Sigma_{2,3} \\ \Sigma_{3,1} & \Sigma_{3,2} & \Sigma_{3,3} \end{bmatrix}$$

and note that

$$\left[\begin{array}{c} \mu_1\\ \mu_3 \end{array}\right] = \left[\begin{array}{ccc} 1 & 0 & 0\\ 0 & 0 & 1 \end{array}\right] \left[\begin{array}{c} \mu_1\\ \mu_2\\ \mu_3 \end{array}\right]$$

and

$$\begin{bmatrix} \Sigma_{1,1} & \Sigma_{1,3} \\ \Sigma_{3,1} & \Sigma_{3,3} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \Sigma_{1,1} & \Sigma_{1,2} & \Sigma_{1,3} \\ \Sigma_{2,1} & \Sigma_{2,2} & \Sigma_{2,3} \\ \Sigma_{3,1} & \Sigma_{3,2} & \Sigma_{3,3} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{bmatrix}$$

The converse of Property 3 does not hold in general; here is a counterexample:

Example: Suppose $X_1 \sim \mathcal{N}(0, 1)$ and

$$X_2 = \begin{cases} 1, & \text{w.p.} \frac{1}{2} \\ -1, & \text{w.p.} \frac{1}{2} \end{cases}$$

are independent RVs and consider $X_3 = X_1 X_2$. Observe that

• $X_3 \sim \mathcal{N}(0,1)$ and

• $f_{X_1,X_3}(x_1,x_3)$ is *not* a jointly Gaussian pdf.



Property 4: Conditionals of Gaussian random vectors are Gaussian, i.e. if

$$oldsymbol{X} = \left[egin{array}{c} oldsymbol{X}_1 \ oldsymbol{X}_2 \end{array}
ight] \sim \mathcal{N} \Big(\left[egin{array}{c} oldsymbol{\mu}_1 \ oldsymbol{\mu}_2 \end{array}
ight], \left[egin{array}{c} arsigma_{1,1} & arsigma_{1,2} \ arsigma_{2,1} & arsigma_{2,2} \end{array}
ight] \Big)$$

then

$$\{ \boldsymbol{X}_2 \,|\, \boldsymbol{X}_1 = \boldsymbol{x}_1 \} \sim \mathcal{N} \Big(\Sigma_{2,1} \Sigma_{1,1}^{-1} (\boldsymbol{x}_1 - \boldsymbol{\mu}_1) + \boldsymbol{\mu}_2, \Sigma_{2,2} - \Sigma_{2,1} \Sigma_{1,1}^{-1} \Sigma_{1,2} \Big)$$

 $\quad \text{and} \quad$

$$\{X_1 | X_2 = x_2\} \sim \mathcal{N}\Big(\Sigma_{1,2}\Sigma_{2,2}^{-1}(x_2 - \mu_2) + \mu_1, \Sigma_{1,1} - \Sigma_{1,2}\Sigma_{2,2}^{-1}\Sigma_{2,1}\Big)$$

Example: Compare this result to the case of n = 2 in (7):

$$\{X_2 \mid X_1 = x_1\} \sim \mathcal{N}\Big(\frac{\Sigma_{2,1}}{\Sigma_{1,1}} (x_1 - \mu_1) + \mu_2, \Sigma_{2,2} - \frac{\Sigma_{1,2}^2}{\Sigma_{1,1}}\Big).$$

In particular, having $X = X_2$ and $Y = X_1, y = x_1$, this result becomes:

$$\{X \mid Y = y\} \sim \mathcal{N}\left(\frac{\sigma_{X,Y}}{\sigma_Y^2} \left(y - \mu_Y\right) + \mu_X, \sigma_X^2 - \frac{\sigma_{X,Y}^2}{\sigma_Y^2}\right)$$

where $\sigma_{X,Y} = \operatorname{cov}_{X,Y}(X,Y), \sigma_X^2 = \operatorname{cov}_{X,X}(X,X) = \operatorname{var}_X(X),$ and $\sigma_Y^2 = \operatorname{cov}_{Y,Y}(Y,Y) = \operatorname{var}_Y(Y)$. Now, it is clear that

$$\rho_{X,Y} = \frac{\sigma_{X,Y}}{\sigma_X \, \sigma_Y}$$

where $\sigma_X = \sqrt{\sigma_X^2} > 0$ and $\sigma_Y = \sqrt{\sigma_Y^2} > 0$.

Example: Suppose

$$\begin{bmatrix} X_1 \\ X_1 \\ \vdots \\ X_2 \\ X_3 \end{bmatrix} \sim \mathcal{N} \left(\begin{bmatrix} 1 \\ -- \\ 2 \\ 2 \end{bmatrix} \right), \begin{bmatrix} 1 \\ -- \\ -- \\ 2 \\ 2 \end{bmatrix} \left(\begin{bmatrix} 1 \\ -- \\ -- \\ 2 \\ 2 \end{bmatrix} \right), \begin{bmatrix} 1 \\ -- \\ -- \\ 2 \\ 2 \\ 1 \end{bmatrix} \left(\begin{bmatrix} 2 \\ -- \\ -- \\ 2 \\ 2 \\ 1 \end{bmatrix} \right)$$

From Property 4, it follows that

erty 4, it follows that

$$E(\mathbf{X}_{2}|X_{1} = x) = \begin{bmatrix} 2\\1 \end{bmatrix} (x-1) + \begin{bmatrix} 2\\2 \end{bmatrix} = \begin{bmatrix} 2x\\x+1 \end{bmatrix}$$

$$\Sigma_{\{\mathbf{X}_{2}|X_{1}=x\}} = \begin{bmatrix} 5&2\\2&9 \end{bmatrix} - \begin{bmatrix} 2\\1 \end{bmatrix} \begin{bmatrix} 2&1 \end{bmatrix}$$

$$= \begin{bmatrix} 1&0\\0&8 \end{bmatrix}$$

Property 5: If $X \sim \mathcal{N}(\mu, \Sigma)$ then

 $(\boldsymbol{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\boldsymbol{x} - \boldsymbol{\mu}) \sim \chi_d^2$ (Chi-square in your distr. table).

Additive Gaussian Noise Channel

Consider a communication channel with input

$$X \sim \mathcal{N}(\mu_X, \tau_X^2)$$

and noise

$$W \sim \mathcal{N}(0, \sigma^2)$$

where X and W are independent and the measurement Y is

$$Y = X + W.$$

Since X and W are independent, we have

$$f_{X,W}(x,w) = f_X(x) f_W(x)$$

 and

$$\begin{bmatrix} X \\ W \end{bmatrix} \sim \mathcal{N}\Big(\begin{bmatrix} \mu_X \\ 0 \end{bmatrix}, \begin{bmatrix} \tau_X^2 & 0 \\ 0 & \sigma^2 \end{bmatrix} \Big).$$

What is $f_{Y \mid X}(y \mid x)$? Since

$$\{Y \mid X = x\} = x + W \sim \mathcal{N}(x, \sigma^2)$$

we have

$$f_{Y \mid X}(y \mid x) = \mathcal{N}(y \mid x, \sigma^2).$$

How about $f_Y(y)$? Construct the joint pdf $f_{X,Y}(x,y)$ of X and Y: since $\begin{bmatrix} X \\ Y \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} X \\ W \end{bmatrix}$ then

then

$$\begin{bmatrix} X \\ Y \end{bmatrix} \sim \mathcal{N}\Big(\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \mu_X \\ 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \tau_X^2 & 0 \\ 0 & \sigma^2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}\Big)$$

yielding

$$\begin{bmatrix} X \\ Y \end{bmatrix} \sim \mathcal{N}\Big(\begin{bmatrix} \mu_X \\ \mu_X \end{bmatrix}, \begin{bmatrix} \tau_X^2 & \tau_X^2 \\ \tau_X^2 & \tau_X^2 + \sigma^2 \end{bmatrix}\Big).$$

Therefore,

$$f_Y(y) = \mathcal{N}\Big(y \,\big|\, \mu_X, \tau_X^2 + \sigma^2\Big).$$

Complex Gaussian Distribution

Consider joint pdf of real and imaginary part of an $n\times 1$ complex vector \pmb{Z}

$$\boldsymbol{Z} = \boldsymbol{U} + j \, \boldsymbol{V}.$$

Assume

$$oldsymbol{X} = \left[egin{array}{c} oldsymbol{U} \ oldsymbol{Y} \end{array}
ight].$$

The 2n-variate Gaussian pdf of the (real!) vector X is

$$f_{\boldsymbol{X}}(\boldsymbol{x}) = \frac{1}{\sqrt{(2\pi)^{2n} |\Sigma_{\boldsymbol{X}}|}} \exp\left[-\frac{1}{2} (\boldsymbol{z} - \boldsymbol{\mu}_{\boldsymbol{X}})^T \Sigma_{\boldsymbol{X}}^{-1} (\boldsymbol{z} - \boldsymbol{\mu}_{\boldsymbol{X}})\right]$$

where

$$\boldsymbol{\mu}_{\boldsymbol{X}} = \begin{bmatrix} \boldsymbol{\mu}_{\boldsymbol{U}} \\ \boldsymbol{\mu}_{\boldsymbol{V}} \end{bmatrix}, \quad \boldsymbol{\Sigma}_{\boldsymbol{X}} = \begin{bmatrix} \boldsymbol{\Sigma}_{\boldsymbol{U}\boldsymbol{U}} & \boldsymbol{\Sigma}_{\boldsymbol{U}\boldsymbol{V}} \\ \boldsymbol{\Sigma}_{\boldsymbol{V}\boldsymbol{U}} & \boldsymbol{\Sigma}_{\boldsymbol{V}\boldsymbol{V}} \end{bmatrix}$$

Therefore,

$$\Pr{\{\boldsymbol{x} \in A\}} = \int_{\boldsymbol{x} \in A} f_{\boldsymbol{x}}(\boldsymbol{x}) d\boldsymbol{x}.$$

Complex Gaussian Distribution (cont.)

Assume that Σ_X has a special structure:

$$\Sigma_{UU} = \Sigma_{VV}$$
 and $\Sigma_{UV} = -\Sigma_{VU}$.

[Note that $\Sigma_{UV} = \Sigma_{VU}^T$ has to hold as well.] Then, we can define a complex Gaussian pdf of Z as

$$f_{\boldsymbol{Z}}(\boldsymbol{z}) = \frac{1}{\pi^n |\Sigma_{\boldsymbol{X}}|} \exp\left[-(\boldsymbol{z} - \boldsymbol{\mu}_{\boldsymbol{Z}})^H \Sigma_{\boldsymbol{Z}}^{-1} (\boldsymbol{z} - \boldsymbol{\mu}_{\boldsymbol{Z}})\right]$$

where

$$\boldsymbol{\mu}_{\boldsymbol{Z}} = \boldsymbol{\mu}_{\boldsymbol{U}} + j \boldsymbol{\mu}_{\boldsymbol{V}}$$

$$\boldsymbol{\Sigma}_{\boldsymbol{Z}} = \mathbf{E}_{\boldsymbol{Z}} \{ (\boldsymbol{Z} - \boldsymbol{\mu}_{\boldsymbol{Z}}) (\boldsymbol{Z} - \boldsymbol{\mu}_{\boldsymbol{Z}})^{H} \} = 2 (\boldsymbol{\Sigma}_{\boldsymbol{U}\boldsymbol{U}} + j \boldsymbol{\Sigma}_{\boldsymbol{V}\boldsymbol{U}})$$

$$\boldsymbol{0} = \mathbf{E}_{\boldsymbol{Z}} \{ (\boldsymbol{Z} - \boldsymbol{\mu}_{\boldsymbol{Z}}) (\boldsymbol{Z} - \boldsymbol{\mu}_{\boldsymbol{Z}})^{T} \}.$$